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< PRECAUTION > [ICC]

PRECAUTION

PRECAUTIONS

Precaution for Supplemental Restraint System (SRS) "AIR BAG" and "SEAT BELT PRE-TENSIONER"

The Supplemental Restraint System such as "AIR BAG" and "SEAT BELT PRE-TENSIONER", used along with a front seat belt, helps to reduce the risk or severity of injury to the driver and front passenger for certain types of collision. This system includes seat belt switch inputs and dual stage front air bag modules. The SRS system uses the seat belt switches to determine the front air bag deployment, and may only deploy one front air bag, depending on the severity of a collision and whether the front occupants are belted or unbelted. Information necessary to service the system safely is included in the "SRS AIR BAG" and "SEAT BELT" of this Service Manual.

WARNING:

Always observe the following items for preventing accidental activation.

- To avoid rendering the SRS inoperative, which could increase the risk of personal injury or death in the event of a collision that would result in air bag inflation, all maintenance must be performed by an authorized NISSAN/INFINITI dealer.
- Improper maintenance, including incorrect removal and installation of the SRS, can lead to personal injury caused by unintentional activation of the system. For removal of Spiral Cable and Air Bag Module, see "SRS AIR BAG".
- Never use electrical test equipment on any circuit related to the SRS unless instructed to in this Service Manual. SRS wiring harnesses can be identified by yellow and/or orange harnesses or harness connectors.

PRECAUTIONS WHEN USING POWER TOOLS (AIR OR ELECTRIC) AND HAMMERS

WARNING:

Always observe the following items for preventing accidental activation.

- When working near the Air Bag Diagnosis Sensor Unit or other Air Bag System sensors with the
 ignition ON or engine running, never use air or electric power tools or strike near the sensor(s) with
 a hammer. Heavy vibration could activate the sensor(s) and deploy the air bag(s), possibly causing
 serious injury.
- When using air or electric power tools or hammers, always switch the ignition OFF, disconnect the battery, and wait at least 3 minutes before performing any service.

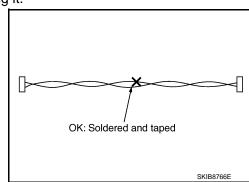
Precautions For Harness Repair

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ITS communication uses a twisted pair line. Be careful when repairing it.

Solder the repaired area and wrap tape around the soldered area.
 NOTE:

A fray of twisted lines must be within 110 mm (4.33 in).

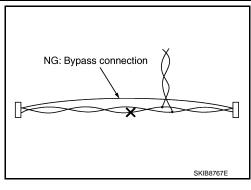


PRECAUTIONS

< PRECAUTION > [ICC]

Bypass connection is never allowed at the repaired area.
 NOTE:

Bypass connection may cause ITS communication error. The spliced wire becomes separated and the characteristics of twisted line are lost.



ICC System Service

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CAUTION:

- Turn the MAIN switch OFF in conditions similar to driving, such as free rollers or a chassis dynamometer.
- Never use the ICC sensor removed from vehicle. Never disassemble or remodel.
- Erase DTC when replacing parts of ICC system, then check the operation of ICC system after radar alignment if necessary.

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< PREPARATION > [ICC]

PREPARATION

PREPARATION

Special Service Tools

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Tool number (Kent-Moore No.) Tool name		Description
KV99112700 (—) ICC target board	JSOIA1012ZZ	Uses for radar alignment
 (1-20-2722-1-IF) ICC alignment kit [*]	AWOIA0016ZZ	Uses for radar alignment
 (1-20-2722-1-IF) Wheel adaptor [*]	AWOIA0017ZZ	Uses for radar alignment
— (J-51093) ICC sensor cone alignment tool [*]	ALOIA0197ZZ	Uses for radar alignment
— (J-50808) ICC alignment kit attachment board [*]	JSOIA1065ZZ	Uses for radar alignment

NOTE:

For radar alignment, KV99112700 or a set of Kent-Moore No. SST are to be used.

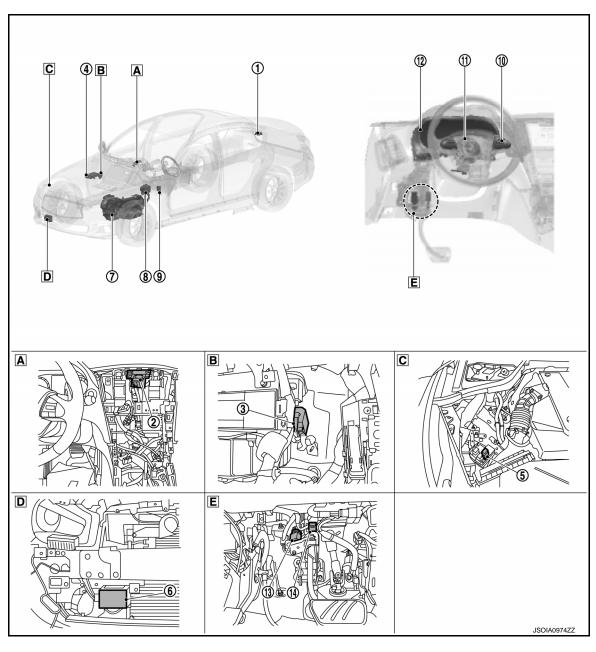
^{*:} This service manual does not apply when using special service tool 1-20-2722-1-IF, J-51093, and J-50808. For the radar alignment procedure with these tools, refer to the instructions included with the tool.

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SYSTEM DESCRIPTION

COMPONENT PARTS

Component Parts Location



- A Instrument panel (Center)
- Front bumper (RH)
- B Instrument lower panel (RH)
- E Upper side of brake pedal
- © Engine room (RH)

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×: Applicable

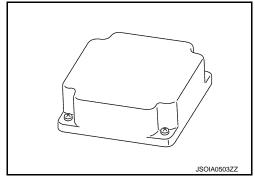
		Fun	ction	
No.	Component	Vehicle-to-vehicle distance control mode	Conventional (fixed speed) cruise control mode	Description
1	ADAS control unit	×	×	Refer to CCS-9, "ADAS Control Unit" Refer to DAS-14, "Component Parts Location" for detailed installation location
2	Driver assistance buzzer	×	×	Refer to CCS-11, "Driver Assistance Buzzer"
3	Driver assistance buzzer control module	×	×	Refer to CCS-11, "Driver Assistance Buzzer Control Module"
4	ECM	×	×	 ECM transmits the accelerator pedal position signal, ICC brake switch signal, stop lamp switch signal, ICC steering switch etc. to ADAS control unit via CAN communication ECM controls the electric throttle control actuator based on the engine torque demand received from the ADAS control unit via CAN communication
5	ICC brake hold relay	×		Refer to CCS-10, "ICC Brake Hold Relay"
6	ICC sensor	×	×	Refer to CCS-9, "ICC Sensor"
7	тсм	×	×	TCM transmits the signal related to A/T control to ADAS control unit via CAN communication
8	ABS actuator and electric unit (control unit)	×	×	 ABS actuator and electric unit (control unit) transmits the vehicle speed signal (wheel speed), stop lamp switch signal and VDC/TCS/ABS system operation condition to ADAS control unit via CAN communication ABS actuator and electric unit (control unit) controls the brake, based on a brake fluid pressure control signal received from the ADAS control unit via chassis control module
9	Chassis control module	×	Chassis control module transmits the drive mode signal to ADAS convia CAN communication	
10	ICC steering switch	×	×	Description: Refer to CCS-10, "ICC Steering Switch" Switch name and function: CCS-20, "VEHICLE-TO-VEHICLE DISTANCE CONTROL MODE FUNCTION: Switch Name and Function" (Vehicle to vehicle distance control mode) Switch name and function: CCS-24, "CONVENTIONAL (FIXED SPEED) CRUISE CONTROL MODE FUNCTION: Switch Name and Function" (Conventional cruise control mode)
11)	Steering angle sensor	×		Measures the rotation amount, rotation speed, and rotation direction of steering wheel, and then transmits them to ADAS control unit via CAN communication

		Fun	ction	
No.	Component	Vehicle-to-vehicle distance control mode	Conventional (fixed speed) cruise control mode	Description
(2)	Combination meter	×	×	Performs the following operations using the signals received from the ADAS control unit via the CAN communication • Description: Refer to CCS-10, "Combination Meter" • System display and warning: CCS-20, "VEHICLE-TO-VEHICLE DISTANCE CONTROL MODE FUNCTION: Menu Displayed by Pressing Each Switch" (Vehicle to vehicle distance control mode) • System display and warning: CCS-24, "CONVENTIONAL (FIXED SPEED) CRUISE CONTROL MODE FUNCTION: Menu Displayed by Pressing Each Switch" (Conventional cruise control mode)
13	Stop lamp switch	×	×	Refer to CCS-10, "Brake Pedal Position Switch / Stop Lamp Switch"
14)	Brake pedal position switch	×	×	Neier to OCO-10, Brake Fedar Fosition Switch / Stop Lamp Switch

ADAS Control Unit

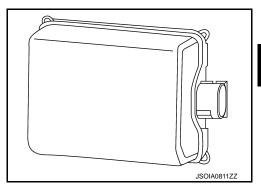
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- ADAS control unit is installed at trunk side of the parcel shelf.
- Communicates with each control unit via CAN communication/ITS communication/Chassis communication.
- ADAS control unit included gateway function, and necessary for system control signals are transmitted to each control unit between CAN communication and ITS communication by the ADAS control unit.
- ADAS control unit controls the each system, based on ITS communication signal, CAN communication signal, and chassis communication signal from each control unit.



ICC Sensor INFOID:0000000009644195

- ICC sensor is installed on the back of the front bumper and detects a vehicle ahead by using millimeter waves.
- ICC sensor detects radar reflected from a vehicle ahead by irradiating radar forward and calculates a distance from the vehicle ahead and relative speed, based on the detected signal.
- ICC sensor transmits the presence/absence of vehicle ahead and the distance from the vehicle to ADAS control unit via ITS communication.



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ICC Steering Switch

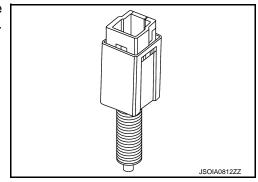
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- ICC steering switch is installed to the steering wheel and allows the driver to operate the ICC system by using this switch.
- ICC steering switch allows the ON/OFF of the Intelligent Cruise Control and the settings of a vehicle speed and distance between vehicles.
- ICC steering switch signal is transmitted to ECM. ECM transmits the signal to the ADAS control unit via CAN
 communication.

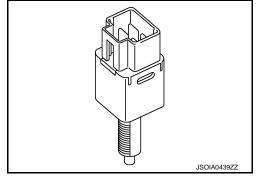
Brake Pedal Position Switch / Stop Lamp Switch

INFOID:0000000009644197

 Brake pedal position switch is installed at the upper part of the brake pedal and detects a brake operation performed by the driver.



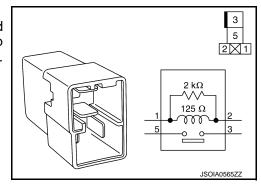
- Brake pedal position switch is turned OFF when depressing the brake pedal.
- Brake pedal position switch signal is input to ECM. Brake pedal position switch signal is transmitted from ECM to ADAS control unit via CAN communication.
- Stop lamp switch is installed at the upper part of the brake pedal and detects a brake operation performed by the driver.
- Stop lamp switch is turned ON, when depressing the brake pedal.
- Stop lamp switch signal is input to ECM and ABS actuator and electric unit (control unit). Stop lamp switch signals are transmitted from ECM and ABS actuator and electric unit (control unit) to ADAS control unit via CAN communication.



INFOID:00000000009644198

ICC Brake Hold Relay

- ICC brake hold relay is installed in the engine room (right side).
- When the brake is activated by the system, the ICC brake hold relay turns ON the stop lamp by bypassing the circuit of the stop lamp, according to a signal transmitted from the ADAS control unit.



Combination Meter

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- Receives meter display signal from ADAS control unit via CAN communication.
- Displays the system status according to a signal received from the ADAS control unit.

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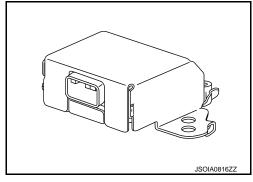
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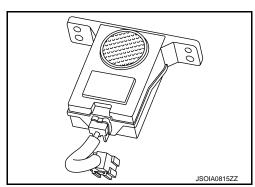
Driver Assistance Buzzer Control Module

- Driver assistance buzzer control module is installed at the behind of glove box.
- When driver assistance buzzer signal is received from the ADAS control unit, the driver assistance buzzer control module transmits the warning buzzer signal to driver assistance buzzer.



Driver Assistance Buzzer

- Driver assistance buzzer is installed at the behind the display control unit.
- When a warning buzzer signal is received from the driver assistance buzzer control module, the driver assistance buzzer sounds a buzzer.



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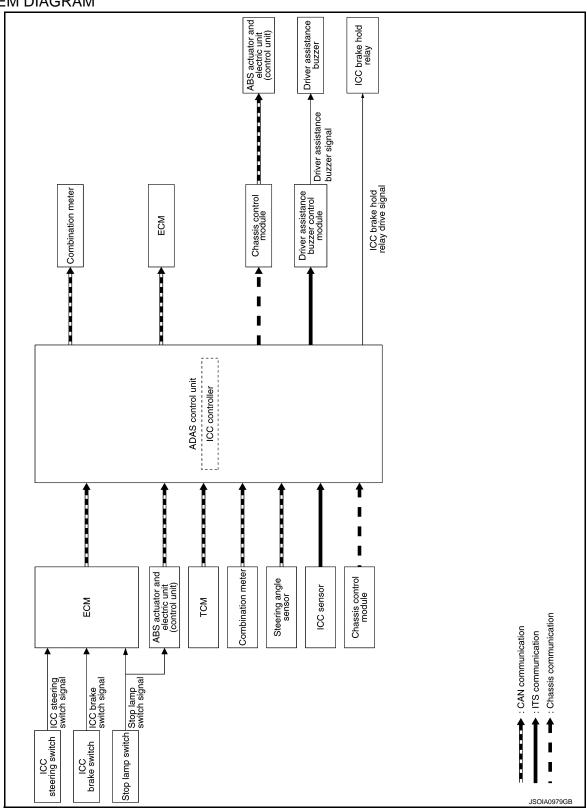
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SYSTEM

System Description

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SYSTEM DIAGRAM



ADAS CONTROL UNIT INPUT/OUTPUT SIGNAL ITEM

Input Signal Item

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Transmit unit		Signal name	e	Description
		Closed throttle positi	on signal	Receives idle position state (ON/OFF)
		Accelerator pedal po	sition signal	Receives accelerator pedal position (angle)
		ICC prohibition signa	al	Receives an operable/inoperable state of the ICC system
		Engine speed signal		Receives engine speed
			MAIN switch signal	
ECM	CAN com- munica-		SET/COAST switch signal	
	tion	ICC steering switch signal	CANCEL switch signal	Receives the operational state of the ICC steering switch
			RESUME/ACCEL- ERATE switch signal	
			DISTANCE switch signal	
		Stop lamp switch sig	nal	Receives an operational state of the brake pedal
		Brake pedal position	switch signal	Receives an operational state of the brake pedal
		Input speed signal		Receives the number of revolutions of input shaft
TCM	CAN com- munica-	Current gear position	n signal	Receives a current gear position
	tion	Shift position signal		Receives a selector lever position
		Output shaft revolution signal		Receives the number of revolutions of output shaft
		ABS malfunction sig	nal	Receives a malfunction state of ABS
		ABS operation signa	ıl	Receives an operational state of ABS
		ABS warning lamp s	ignal	Receives an ON/OFF state of ABS warning lamp
	TCS malfunction sig		nal	Receives a malfunction state of TCS
ABS actuator	CAN com-	TCS operation signa	l	Receives an operational state of TCS
and electric unit (control unit) munication		VDC OFF switch sig	nal	Receives an ON/OFF state of VDC
		VDC malfunction sig	nal	Receives a malfunction state of VDC
		VDC operation signa	al	Receives an operational state of VDC
		Vehicle speed signal	(ABS)	Receives wheel speeds of four wheels
		Stop lamp switch sig	nal	Receives an operational state of the brake pedal
		Yaw rate signal		Receives yaw rate acting on the vehicle
Combination meter	CAN com- munica- tion	Parking brake switch	n signal	Receives an operational state of the parking brake
		Steering angle sense	or malfunction signal	Receives a malfunction state of steering angle sensor
Steering angle sensor	CAN com- munica- tion	Steering angle sensor signal		Receives the number of revolutions, turning direction of the steering wheel
		Steering angle speed	d signal	Receives the turning angle speed of the steering whee
Chassis control module	CAN com- munica- tion	Drive mode signal	Snow mode	Receives an operational state of the snow mode
ICC sensor	ITS com- munica- tion	ICC sensor signal		Receives detection results, such as the presence or ab sence of a leading vehicle and distance from the vehicle

Output Signal Item

Reception unit		Signal na	me	Description
ECM	CAN commu- nication	ICC operation signal		Transmits an ICC operation signal necessary for intelligent cruise control
ABS actuator and electric unit (control unit)	CAN commu- nication	Brake fluid pressure control signal		Transmits a brake fluid pressure control signal to activates the brake via chassis control module
			Vehicle ahead detection indicator signal	
			Set vehicle speed indi- cator signal	
Combination	CAN commu-	ommu- Meter display	Set distance indicator signal	Transmits a signal to display a state of the system o the information display
meter	nication	signal	SET switch indicator signal	
			MAIN switch indicator signal	
			ICC malfunction signal	Transmits an ICC malfunction signal to turn ON the ICC system malfunction
ICC sensor	ITS commu- nication	Vehicle speed signal		Transmits a vehicle speed calculated by the ADAS control unit
Driver assis- tance buzzer control module	ITS commu- nication	Warning buzzer signal		Transmits a warning buzzer signal to turn ON the buzzer
ICC brake hold relay	ICC brake hold	d relay drive signal		Activates the brake hold relay and turns ON the stop lamp

DESCRIPTION

Intelligent Cruise Control

The Intelligent Cruise Control (ICC) system maintains a selected distance from the vehicle ahead within set speeds.

The driver can select the set speeds.

The vehicle travels at a set speed when the road ahead is clear.

The ICC system can be set to one of two cruise control modes:

CAUTION:

Never set the cruise speed exceeding the posted speed limit.

Vehicle-to-vehicle Distance Control Mode

For maintaining a selected distance between own vehicle and the vehicle in front of own vehicle up to the preset speed. Refer to CCS-16, "VEHICLE-TO-VEHICLE DISTANCE CONTROL MODE FUNCTION: System Description".

Conventional (Fixed Speed) Cruise Control Mode

For cruising at a preset speed. Refer to <u>CCS-18</u>, "<u>CONVENTIONAL</u> (<u>FIXED SPEED</u>) <u>CRUISE CONTROL MODE FUNCTION</u>: System Description".

NOTE:

In the Conventional (Fixed Speed) Cruise Control Mode, a warning chime will not sound to warn driver if own vehicle are too close to the vehicle ahead.

WARNING:

Always drive carefully and attentively when using either cruise control mode. To avoid serious injury or death, do not rely on the system to prevent accidents or to control the vehicle's speed in emergency situations. Do not use cruise control except in appropriate rode and traffic conditions.

Distance Control Assist (DCA) System

DCA share the systems and components with ICC system. Refer to DAS-170, "DCA: System Description".

Predictive Forward Collision Warning (PFCW) System

PFCW share the systems and components with ICC system. Refer to <u>DAS-174, "PFCW : System Description"</u>.

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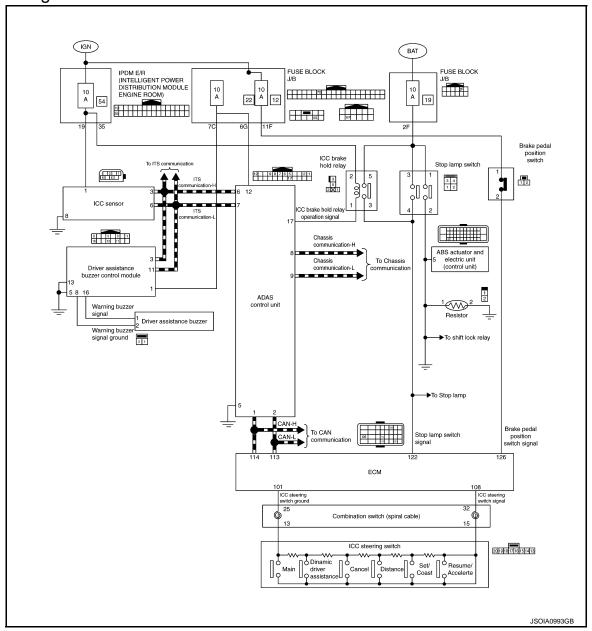
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Forward Emergency Brake (FEB) System

FEB system share the systems and components with ICC system. Refer to BRC-187, "System Description".

Circuit Diagram

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Fail-safe (ADAS Control Unit)

INFOID:0000000009727812

If a malfunction occurs in each system, ADAS control unit cancels each control, sounds a beep, and turns ON the warning or indicator lamp.

System	Buzzer	Warning lamp/Warning dis- play	Description
Vehicle-to-vehicle distance control mode	High- pitched tone	ICC system warning	Cancel
Conventional (fixed speed) cruise control mode	High- pitched tone	ICC system warning	Cancel

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System	Buzzer	Warning lamp/Warning dis- play	Description
Forward Emergency Braking (FEB)	High- pitched tone	FEB warning lamp Warning systems indicator (Forward position: Yellow)	Cancel
Predictive Forward Collision Warning (PFCW)	High- pitched tone	Warning systems indicator (Forward position: Yellow)	Cancel
Distance Control Assist (DCA)	High- pitched tone	Warning systems indicator (Forward position: Yellow)	Cancel
Blind Spot Warning (BSW)	_	Warning systems indicator (Blind spot position: Yellow)	Cancel
Back-up Collision Intervention (BCI)	High- pitched tone	BCI system warning	Cancel

Fail-safe (ICC Sensor)

INFOID:0000000009644205

If a malfunction occurs in the ICC sensor, ADAS control unit cancels control, sounds a beep, and turns ON the ICC system warning in the information display.

VEHICLE-TO-VEHICLE DISTANCE CONTROL MODE FUNCTION

VEHICLE-TO-VEHICLE DISTANCE CONTROL MODE FUNCTION: System Description

FUNCTION DESCRIPTION

In the vehicle-to-vehicle distance control mode, the Intelligent Cruise Control (ICC) system automatically maintains a selected distance from the vehicle traveling in front of own vehicle according to that vehicle's speed (up to the set speed), or at the set speed when the road ahead is clear.

With ICC system, the driver can maintain the same speed as other vehicles without the constant need to adjust the set speed as driver would with a normal cruise control system.

The following items are controlled in the vehicle-to-vehicle distance control mode

- When there are no vehicles traveling ahead, the vehicle-to-vehicle distance control mode maintains the speed set by the driver. The selectable speed ranges are as follows:
- Between approximately 32 and 144 km/h (20 and 90 MPH).
- When there is a vehicle traveling ahead, the vehicle-to-vehicle distance control mode adjusts the speed to maintain the distance, selected by driver, from a vehicle ahead. The adjusting speed range is up to the set speed.
- When the vehicle traveling ahead has moved out from its lane of travel, the vehicle-to-vehicle distance control mode accelerates and maintains vehicle speed up to the set speed.

CAUTION:

- If the vehicle ahead comes to stop, the vehicle decelerates to a standstill within the limitations of the system. The system will cancel once it judges that the vehicle has come to a standstill and sound a warning chime.
- To prevent the vehicle from moving, the driver must depress the brake pedal.

When the accelerator pedal is depressed, the brake operation and the warning are not performed by the ICC system.

OPERATION DESCRIPTION

Quickly push (less than 1.5 seconds) and release the MAIN switch ON.

The MAIN switch indicator, set distance indicator, own vehicle indicator, and set vehicle speed indicator come on and ICC system is set to a standby state.

ADAS control unit performs the control as per the following:

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Constant speed	Comparing the set vehicle speed with the current vehicle speed, transmit the command to ECM via CAN communication to reach the set vehicle speed, and controls the electric throttle control actuator.
Deceleration	When a vehicle ahead (slower than driver set vehicle speed) appears or when a vehicle ahead slows down, the system controls the electric throttle control actuator into the close direction and decelerates the vehicle. If greater deceleration is necessary, the system transmits the brake fluid pressure control signal to the ABS actuator and electric unit (control unit) via chassis control module and operates the brake.
Following	The system controls electric throttle control actuator and the brake fluid pressure to keep the proper distance between the vehicles according to the vehicle speed change of the vehicle ahead.
Acceleration	When a vehicle ahead is not detected because of it changes lanes or own vehicle changes lanes during the following driving, the system controls the electric throttle control actuator in the open direction and accelerates the vehicle to the set vehicle speed slowly.

Set Condition

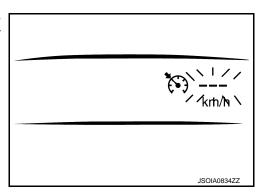
Under a standby state, pushing down the SET/COAST switch will start system control.

- When vehicle speed is between approximately 32 km/h and 144 km/h (20 MPH and 90 MPH).
- When vehicle speed is below approximately 32 km/h (20 MPH) if the vehicle ahead is detected. The set vehicle speed becomes 32 km/h (20 MPH).

If the system is canceled by conditions 1-10 below, the system will resume control at the last set cruising speed by pushing up the RESUME/ACCELERATE switch.

NOTE:

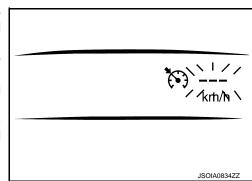
 When the SET/COAST switch is pushed under the following conditions, the system cannot be set and the set vehicle speed indicator will blink for approximately 2 seconds.



- When traveling below 32 km/h (20 MPH) and the vehicle ahead is not detected.
- When the selector lever is not in the "D" position or manual mode.
- When the parking brakes are applied.
- When the brakes are operated by the driver.
- When the SET/COAST switch is pushed under the following conditions, the system cannot be set. A warning chime will sound and the set speed indicator will blink.
- When the drive mode select switch is in SNOW position. (To use the ICC system, turn OFF the snow mode, push the MAIN switch to turn OFF the ICC system and reset the ICC system by pushing the MAIN switch again.)
- When the VDC is OFF. (To use the ICC system, turn ON the VDC system, push the MAIN switch to turn OFF the ICC system and reset the ICC system by pushing the MAIN switch again.)
- When ABS or VDC (including the TCS) operates.
- When the wheel is slipping. (To use the ICC system, make sure the wheels are no longer spinning, push the MAIN switch to turn OFF the ICC system and reset the ICC system by pushing the MAIN switch again.)

Cancel Conditions

- When CANCEL switch is pressed.
- When brake pedal is depressed.
- When the vehicle ahead is not detected below the speed of 24 km/h (15 MPH).
- When the selector lever is not in the "D" position or manual mode.
- When the parking brakes are applied.
- 6. When the system judges the vehicle is at standstill.
- 7. When the drive mode select switch is in SNOW position.
- When ABS or VDC (including the TCS) operates.



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- When a wheel slips.
- 10. When the VDC is turned OFF.
- 11. When the MAIN switch is turned OFF.
- 12. When the system malfunction occurs.

CONVENTIONAL (FIXED SPEED) CRUISE CONTROL MODE FUNCTION

CONVENTIONAL (FIXED SPEED) CRUISE CONTROL MODE FUNCTION: System Description

FUNCTION DESCRIPTION

This mode allows driving at a speed between 40 to 144 km/h (25 to 90 MPH) without keeping foot on the accelerator pedal.

NOTE:

In the conventional (fixed speed) cruise control mode, a warning chime does not sound to warn driver if own vehicle are too close to the vehicle ahead, as neither the presence of the vehicle ahead nor the vehicle-to-vehicle distance is detected.

OPERATION DESCRIPTION

To turn ON the conventional (fixed speed) cruise control mode, push and hold the MAIN switch for longer than approximately 1.5 seconds when ICC system is OFF.

When pushing the MAIN switch ON, the ICC system display and the MAIN switch indicator are displayed on the information display.

After hold the MAIN switch ON for longer than approximately 1.5 seconds, the ICC system display goes out. The MAIN switch indicator stays lit and brings the system to standby state.

NOTE:

- To turn on the vehicle-to-vehicle distance control mode again, turn OFF the system and quickly push (less than 1.5 seconds) the MAIN switch.
- When the DCA system is ON, the conventional (fixed speed) cruise control mode cannot be turned on even though the MAIN switch is pushed and held.
- To turn ON the conventional (fixed speed) cruise control mode, turn OFF the DCA system. Refer to DAS-170, "DCA: System Description".

ADAS control unit performs the control as per the following:

Constant speed	Comparing the set vehicle speed with the current vehicle speed, transmits the command to ECM via CAN com-
Constant speed	munication to reach the set vehicle speed, and controls electronic throttle control actuator.

Set Condition

When the system is under a standby state and the vehicle speed is between approximately 40 km/h (25 MPH) and 144 km/h (90 MPH), pushing the SET/COAST switch will start system control. If the system is canceled by conditions 1–7 below, the system will resume control at the last set cruising speed by pushing the RESUME/ACCELERATE switch.

Cancel conditions

- 1. When CANCEL switch is pressed.
- 2. When brake pedal depressed.
- 3. When the vehicle slows down more than 13 km/h (8 MPH) below the set speed.
- 4. When the selector lever is not in the "D" position or manual mode.
- 5. When the parking brakes are applied.
- 6. When VDC (including the TCS) operates.
- 7. When a wheel slips.
- 8. When the MAIN switch is turned OFF.
- When the system malfunction occurs.

WARNING/INDICATOR/CHIME LIST

WARNING/INDICATOR/CHIME LIST: Warning/Indicator (On Information Display)

INFOID:0000000009644209

SYSTEM

[ICC] < SYSTEM DESCRIPTION >

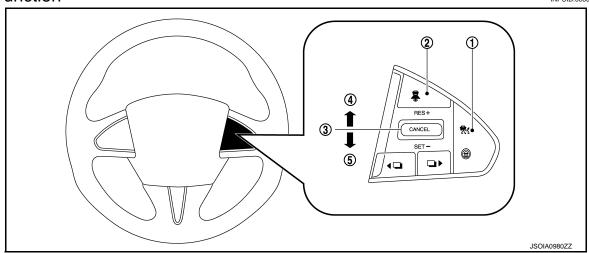
Name	Design	Function
ICC system display (Vehicle-to-vehicle distance control mode)	100 km/h	CCS-20, "VEHICLE-TO-VEHICLE DISTANCE CON-
CC system warning 'Vehicle-to-vehicle distance control mode)		TROL MODE FUNCTION: Menu Displayed by Pressing Each Switch"
CC system display conventional (fixed speed) cruise control node)	JSOIA0893ZZ 100 km/h	CCS-24, "CONVENTIONAL (FIXED SPEED)
CC system warning conventional (fixed speed) cruise control mode)		CRUISE CONTROL MODE FUNCTION : Menu Displayed by Pressing Each Switch"

OPERATION

VEHICLE-TO-VEHICLE DISTANCE CONTROL MODE FUNCTION

VEHICLE-TO-VEHICLE DISTANCE CONTROL MODE FUNCTION : Switch Name

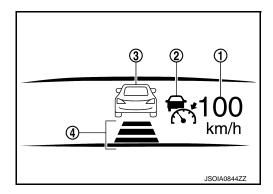
and Function



No.	Switch name	Description
1	MAIN switch	Master switch to activate the system (Press for less than 1.5 seconds)
2	DISTANCE switch	Changes the following distance from: Long, Middle, Short
3	CANCEL switch	Deactivates the system without erasing the set speed
4	RESUME/ACCELERATE switch	Resumes set speed or increases speed incrementally Push and hold the switch to increase the set speed by 5 km/h (5 MPH) Push then quickly release the switch to increase the set speed by 1 km/h (1 MPH)
⑤	SET/COAST switch	Sets desired cruise speed or reduces speed incrementally • Push and hold the switch to decrease the set speed by 5 km/h (5 MPH) • Push then quickly release the switch to decrease the set speed by 1 km/h (1 MPH) NOTE: The minimum set speed is 32 km/h (20 MPH)

VEHICLE-TO-VEHICLE DISTANCE CONTROL MODE FUNCTION : Menu Displayed by Pressing Each Switch

ICC SYSTEM DISPLAY (ON THE INFORMATION DISPLAY)



No.	Switch name	Description
1	Set vehicle speed indicator	 Indicates the set vehicle speed Indicates 32 km/h (20 MPH) when setting less than 32 km/h (20 MPH)

OPERATION

< SYSTEM DESCRIPTION >

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No.	No. Switch name Description	
	ICC system warning lamp (yellow)	Indicates that a malfunction occurs in the ICC system
2	MAIN switch indicator (white)	Indicates that the MAIN switch is ON (ICC system ON)
	Set switch indicator (green)	Indicates that the set vehicle to vehicle distance control mode is controlled
3	Vehicle ahead detection indicator	Indicates whether it detects a vehicle ahead
4	Set distance indicator	Indicates the selected distance between vehicles set with the DISTANCE switch

SYSTEM CONTROL CONDITION DISPLAY

Quickly push (less than 1.5 seconds) and release the MAIN switch ON.

The MAIN switch indicator (cruise indicator), set distance indicator, own vehicle indicator, and set vehicle speed indicator come on and ICC system is set to a standby state.

	Condition		Display on ICC system display
Standby mode			km/h JSOIA0845ZZ
		Set vehicle distance (Long)	100 km/h
	Without a vehicle	Set vehicle distance (Middle)	100 km/h
Control mode	ahead	Set vehicle distance (Short)	100 km/h
		When the vehicle speed exceeds the set speed	JSOIA0849ZZ

Condition			Display on ICC system display
		Set vehicle distance (Long)	100 km/h
Control mode	With a vehicle	Set vehicle distance (Middle)	100 km/h
Control mode	ahead	Set vehicle distance (Short)	100 km/h
		When the vehicle speed exceeds the set speed	JSOIA0853ZZ

NOTE:

The display of the DCA system is given priority when the DCA system is ON in a standby mode. (The set vehicle speed indicator, and set distance indicator, are not displayed).

APPROACH WARNING DISPLAY

If own vehicle comes closer to a vehicle ahead due to rapid deceleration of that vehicle or if another vehicle cuts in, the system warns the driver with the chime and ICC system display. Decelerate by depressing the brake pedal to maintain a safe vehicle distance if:

- The chime sounds.
- The vehicle ahead detection indicator and set distance indicator blink.

The warning chime may not sound in some cases when there is a short distance between vehicles. Some examples are:

- When the vehicles are traveling at the same speed and the distance between vehicles is not changing.
- When the vehicle ahead is traveling faster and the distance between vehicles is increasing.
- When a vehicle cuts in at near own vehicle.

The warning chime will not sound when own vehicle approaches vehicles that are parked or moving slowly.

The warning chime will not sound when the accelerator pedal is depressed, overriding the system.

The approach warning chime may sound and the system display may blink when the ICC sensor detects some reflectors which are fitted on vehicles in other lanes or on the side of the road.

This may cause the ICC system to decelerate or accelerate the vehicle.

The ICC sensor may detect these object when the vehicle is driven on winding roads, hilly roads or when entering or exiting a curve.

The ICC sensor may also detect object on narrow roads or in road construction zones.

In these cases driver will have to manually control the proper distance ahead of own vehicle.

Also, the sensor sensitivity can be affected by vehicle operation (steering maneuver or driving position in the lane) or traffic or vehicle condition (for example, if a vehicle is being driven with some damage).



	Cond	ition	Display on ICC system display
ween the	vehicles is not sufficient	e ahead and it is judged that the distance be-	JSOIA1047ZZ
	Condition	Description	Display on ICC system display
/arning	 When the VDC is turned OFF When the VDC or ABS (including the TCS) operates When a wheel slips When the drive mode select switch is in SNOW mode 	NOTE: When the conditions listed above are no longer present, turn the system OFF using the MAIN switch. Turn the ICC system back on to use the system	
splay	When the front bumper grille near the ICC sensor is dirty, making it impossible to detect a vehicle ahead.	A chime sounds and the control is automatically canceled. NOTE: Park the vehicle in a safe place, turn the engine OFF. Clean the front bumper grille near the ICC sensor and then perform the settings again.	JSOIA1048ZZ

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Condition		Description	Display on ICC system display
Warning display	When the ICC system is mal- functioning	A chime sounds and the control is automatically canceled. NOTE: Turn the engine OFF and restart engine. If there is no malfunction, it is possible to set the system.	(Yellow)
Automatic cancella- tion display	When brake pedal is depressed When CANCEL switch is pressed When a vehicle ahead is not detected below the speed of 24 km/h (15 MPH) When the system judges the vehicle is at standstill When the selector lever is not in "D" position or manual mode When the parking brake are applied	A chime sounds and the control is automatically canceled. NOTE: The system will be in a standby, after the control is automatically canceled. A chime sounds when the control is automatically canceled, except when brake pedal is depressed or when CANCEL switch is pressed.	km/h JSOIA0845ZZ

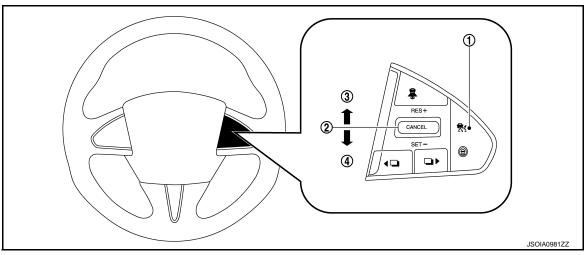
NOTE:

When the ICC system is automatically canceled, the cancellation condition can be displayed on "WORK SUP-PORT" of CONSULT (ICC/ADAS).

CONVENTIONAL (FIXED SPEED) CRUISE CONTROL MODE FUNCTION

CONVENTIONAL (FIXED SPEED) CRUISE CONTROL MODE FUNCTION: Switch

Name and Function



No.	Description	Function
1	MAIN switch	Master switch to activate the system (Press for more than 1.5 seconds)
2	CANCEL switch	Deactivates system without erasing set speed
3	RESUME/ACCELERATE switch	Resumes set speed or increases speed incrementally
4	SET/COAST switch	Sets desired cruise speed or reduces speed incrementally

CONVENTIONAL (FIXED SPEED) CRUISE CONTROL MODE FUNCTION: Menu

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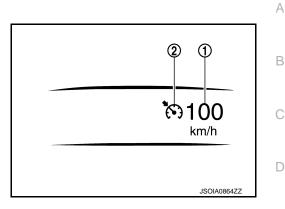
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Displayed by Pressing Each Switch

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ICC SYSTEM DISPLAY (ON THE INFORMATION DISPLAY)



No.	Description	Function
1	Set vehicle speed indicator	Indicates the set vehicle speed
	ICC system warning (yellow)	Indicates that a malfunction occurs in the ICC system
2	MAIN switch indicator (white)	Indicates that the MAIN switch is ON (ICC system ON)
	SET switch indicator (green)	Indicates that the set conventional (fixed speed) cruise control mode is controlled

SYSTEM CONTROL CONDITION DISPLAY

Push and hold the MAIN switch for longer than approximately 1.5 seconds. This mode will be in a standby state for setting.

Condition	Display on ICC system display	
Standby mode	₹ 5) —— km/h	
	JSOIA0865ZZ	
Control mode	100 km/h	
	JSOIA0866ZZ	

WARNING AND AUTOMATIC CANCELLATION DISPLAY

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OPERATION

< SYSTEM DESCRIPTION >

[ICC]

Condition		Description	Display on ICC system display
Warning display	When the ICC system is malfunctioning	A chime sounds and the control is automatically canceled NOTE: Turn the engine OFF and restart engine. If there is no malfunction, it is possible to set the system	(Yellow)
	 When brake pedal is depressed When pressing CANCEL switch When the vehicle slows down more than 13 km/h (8 MPH) below the set speed 	A chime sounds and the control is automatically canceled NOTE: • The system will be in a standby,	(White)
System cancel display	 When the selector lever is not in the "D" position or manual mode When the parking brakes are applied When VDC (including the TCS) operates When a wheel slips 	after the control is automatically canceled • A chime sounds when the control is automatically canceled, except when brake pedal is depressed or when CANCEL switch is pressed	km/h

NOTE:

When the ICC system is automatically canceled, the cancellation condition can be displayed on "WORK SUP-PORT" of CONSULT (ICC/ADAS).

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HANDLING PRECAUTION

Precautions for Vehicle-to-Vehicle Distance Control Mode

• ICC system is only an aid to assist the driver and is not a collision warning or avoidance device. It is the driver's responsibility to stay alert, drive safely and be in control of the vehicle at all times.

• The system is primarily intended for use on straight, dry, open roads with light traffic. It is not advisable to use the system in city traffic or congested areas.

- This system will not adapt automatically to road conditions. This system should be used in evenly flowing traffic. Do not use the system on roads with sharp curves, or on icy roads, in heavy rain or in fog.
- The ICC sensor will not detect under most conditions.
- Stationary and slow moving vehicles.
- Pedestrians or objects in the roadway.
- Oncoming vehicles in the some lane.
- Motorcycles traveling offset in the travel lane.
- As there is a performance limit to the distance control function, never rely solely on the ICC system. This
 system does not correct careless, inattentive or absent-minded driving, or overcome poor visibility in rain,
 fog, or other bad weather. Decelerate the vehicle speed by depressing the brake pedal, depending on the
 distance to the vehicle ahead and the surrounding circumstances in order to maintain a safe distance
 between vehicles.
- If the vehicle ahead comes to a stop, the vehicle decelerates to a standstill within the limitations of the system. The system will cancel once it judges that the vehicle has come to a standstill and sound a warning chime. To prevent the vehicle from moving, the driver must depress the brake pedal.
- The system may not detect the vehicle in front of the driver in certain road or weather conditions. To avoid accidents, never use the ICC system under the following conditions:
- On roads where the traffic is heavy or there are sharp curves.
- On slippery road surfaces such as on ice or snow, etc.
- During bad weather (rain, fog, snow, etc.)
- When rain, snow or dirt adhere to the system sensor.
- On steep downhill roads (the vehicle may go beyond the set vehicle speed and frequent braking may result in overheating the brakes).
- On repeated uphill and downhill roads.
- When traffic conditions make it difficult to keep a proper distance between vehicles because of frequent acceleration or deceleration.
- In some road or traffic conditions, a vehicle or object can unexpectedly come into the sensor detection zone
 and cause automatic braking. The driver may need to control the distance from other vehicles using the
 accelerator pedal. Always stay alert and avoid using the ICC system when it is not recommended in this section.
- The vehicle-to-vehicle distance control mode uses a sensor located behind the lower grille of the front bumper to detect vehicles traveling ahead. The sensor generally detects the signals returned from the vehicle ahead. Therefore, if the sensor cannot detect the reflection from the vehicle ahead, the ICC system may not maintain the selected distance.
- The following are some conditions in which the sensor cannot detect the signals:
- When the snow or road spray from traveling vehicles reduces the sensor's visibility.
- When excessively heavy baggage is loaded in the rear seat or the trunk room of own vehicle.
- The ICC system is designed to automatically check the sensor's operation within the limitation of the system. When the sensor area of the front bumper is covered with dirt or is obstructed, the system will automatically be canceled. If the sensor is covered with ice, a transparent or translucent vinyl bag, etc., the ICC system may not detect them. In these instances, the vehicle-to-vehicle distance control mode may not cancel and may not be able to maintain the selected following distance from the vehicle ahead. Be sure to check and clean the sensor regularly.
- The ICC system does not control vehicle speed or warn the driver when own vehicle approaches stationary and slow moving vehicles. The driver must pay attention to vehicle operation to maintain proper distance from vehicles ahead when approaching toll gates or traffic congestion.

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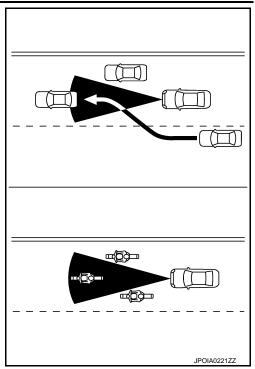
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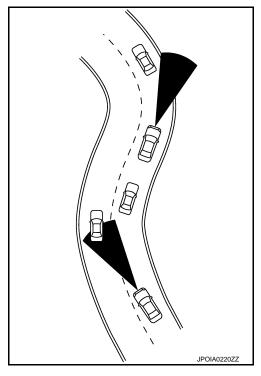
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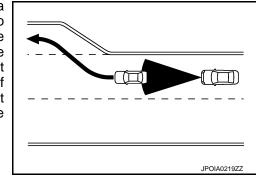
• The detection zone of the ICC sensor is limited. A vehicle ahead must be in the detection zone for the vehicle-to-vehicle distance detection mode to maintain the selected distance from the vehicle ahead. A vehicle ahead may move outside of the detection zone due to its position within the same lane of travel. Motorcycles may not be detected in the same lane ahead if they are traveling offset from the center line of the lane. A vehicle that is entering the lane ahead may not be detected until the vehicle has completely moved into the lane. If this occurs, the ICC system may warn the driver by blinking the system indicator and sounding the chime. The driver may have to manually control the proper distance away from vehicle traveling ahead.



• When driving on some roads, such as winding, hilly, curved, narrow roads, or roads which are under construction, the ICC sensor may detect vehicles in a different lane, or may temporarily not detect a vehicle traveling ahead. This may cause the ICC system to decelerate or accelerate the vehicle. The detection of vehicles may also be affected by vehicle operation (steering maneuver or traveling position in the lane, etc.) or vehicle condition. If this occurs, the ICC system may warn the driver by blinking the system indicator and sounding the chime unexpectedly. The driver will have to manually control the proper distance away from the vehicle traveling ahead.



• When driving on the freeway at a set speed and approaching a slower traveling vehicle ahead, the ICC will adjust the speed to maintain the distance, selected by the driver, from the vehicle ahead. If the vehicle ahead changes lanes or exits the freeway, the ICC system will accelerate and maintain the speed up to the set speed. Pay attention to the driving operation to maintain control of the vehicle as it accelerates to the set speed. The vehicle may not maintain the set speed on winding or hilly roads. If this occurs, the driver will have to manually control the vehicle speed.



HANDLING PRECAUTION

< SYSTEM DESCRIPTION >

[ICC]

Normally when controlling the distance to a vehicle ahead, this system automatically accelerates or decelerates own vehicle according to the speed of the vehicle ahead. Depress the accelerator to properly accelerate own vehicle when acceleration is required for a lane change. Depress the brake pedal when deceleration is required to maintain a safe distance to the vehicle ahead due to its sudden braking or if a vehicle cuts in. Always stay alert when using the ICC system.

Precautions for Conventional (Fixed Speed) Cruise Control Mode

INFOID:0000000009644217

- In the conventional (fixed speed) cruise control mode, a warning chime does not sound to warn the driver if own vehicle is too close to the vehicle ahead, as neither the presence of the vehicle ahead nor the vehicleto-vehicle distance is detected.
- Pay special attention to the distance between own vehicle and the vehicle ahead or a collision could occur.
- Always confirm the setting in the ICC system display.
- Do not use the conventional (fixed speed) cruise control mode when driving under the following conditions:
- When it is not possible to keep the vehicle at a set speed.
- In heavy traffic or in traffic that varies in speed.
- On winding or hilly roads.
- On slippery roads (rain, snow, ice, etc.).
- In very windy areas.
- Doing so could cause a loss of vehicle control and result in an accident.
- To avoid accidentally engaging cruise control, make sure to turn the MAIN switch off when not using the ICC system.

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DIAGNOSIS SYSTEM (ADAS CONTROL UNIT)

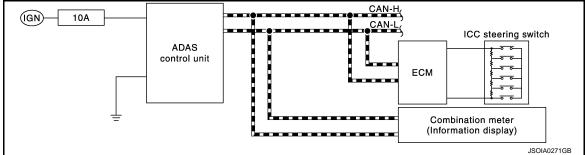
On Board Diagnosis Function

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DESCRIPTION

The DTC is displayed on the information display by operating the ICC steering switch.

On Board Self-diagnosis System Diagram



METHOD OF STARTING

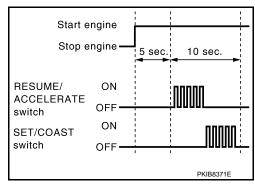
CAUTION:

Start condition of on board self-diagnosis

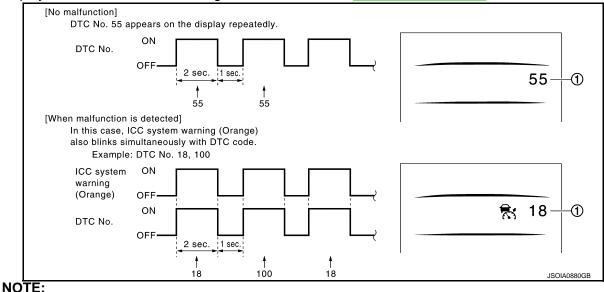
- ICC system OFF
- DCA system OFF
- Vehicle speed 0 km/h (0 MPH)
- 1. Turn the ignition switch OFF.
- 2. Start the engine.
- Wait for 5 seconds after starting the engine. Push up the RESUME/ACCELERATE switch 5 times and push down the SET/COAST switch 5 times within 10 seconds.

NOTE:

If the above operation cannot be performed within 10 seconds after waiting for 5 seconds after starting the engine, repeat the procedure from step 1.



 The DTC is displayed on the set vehicle speed indicator (1) on the ICC system display on the information display when the on board self-diagnosis starts. Refer to <u>DAS-44, "DTC Index"</u>.



< SYSTEM DESCRIPTION >

- It displays for up to 5 minutes and then stops.
- If multiple malfunctions exist, up to 6 DTCs can be stored in memory at the most, and the most recent one is displayed first.

WHEN THE ON BOARD SELF-DIAGNOSIS DOES NOT START

If the on board self-diagnosis does not start, check the following items.

	Assumed abnormal part	Inspection item	
Information display	Combination meter malfunction	Check that the self-diagnosis function of the combination meter operates. Refer to MWI-62 , "On Board Diagnosis Function".	
ICC steering switch male	unction		
Harness malfunction be	ween ICC steering switch and ECM	Perform the inspection for DTC "C1A06". Refer to DAS-80, "DTC Logic".	
ECM malfunction			
ADAS control unit malfu	nction	 Check power supply and ground circuit of ADAS control unit. Refer to <u>DAS-160</u>, "<u>Diagnosis Procedure</u>". Perform SELF-DIAGNOSIS for "ICC/ADAS" with CONSULT, and then check the malfunctioning parts. Refer to <u>DAS-44</u>, "<u>DTC Index</u>". 	

HOW TO ERASE ON BOARD SELF-DIAGNOSIS

- 1. Turn the ignition switch OFF.
- 2. Start the engine, and then start the on board self-diagnosis.
- Press the CANCEL switch 5 times, and then press the DIS-TANCE switch 5 times under the condition that the on board self-diagnosis starts.

NOTE:

- Complete the operation within 10 seconds after pressing the CANCEL switch first.
- If the operation is not completed within 10 seconds, repeat the procedure from step 1.
- 4. DTC 55 is displayed after erasing.

NOTE:

DTCs for existing malfunction can not be erased.

5. Turn ignition switch OFF, and finish the diagnosis.

CONSULT Function (ICC/ADAS)



APPLICATION ITEMS

CONSULT performs the following functions via CAN communication using ADAS control unit.

Diagnosis mode	Description
Configuration	 The vehicle specification that is written in ADAS control unit can be displayed or stored The vehicle specification can be written when ADAS control unit is replaced
Work Support	Displays causes of automatic system cancellation occurred during system control
Self Diagnostic Result	Displays the name of a malfunctioning system stored in the ADAS control unit
Data Monitor	Displays ADAS control unit input/output data in real time
Active Test	Enables an operational check of a load by transmitting a driving signal from the ADAS control unit to the load
ECU Identification	Displays ADAS control unit part number
CAN Diag Support Monitor	Displays a reception/transmission state of CAN communication and ITS communication

CONFIGURATION

Configuration includes functions as follows.

CANCEL ON 10 sec.

CANCEL ON 10 sec.

DISTANCE ON 10 switch OFF 10 switch OFF 11 switch OFF 11 switch OFF 11 switch OFF 11 switch OFF 12 switch OFF 13 switch OFF 14 switch OFF 15 switc

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Fu	nction	Description
Read/Write Configuration	Before Replace ECU	Allows the reading of vehicle specification written in ADAS control unit to store the specification in CONSULT.
	After Replace ECU	Allows the writing of the vehicle information stored in CONSULT into the ADAS control unit.
Manual Configuration		Allows the writing of the vehicle specification into the ADAS control unit by hand.

WORK SUPPORT

Work support items	Description					
CAUSE OF AUTO-CANCEL 1	Displays causes of automatic system cancellation occurred during control of the following systems • Vehicle-to-vehicle control mode • Conventional (fixed speed) control mode • Distance Control Assist (DCA) • Forward Emergency Braking (FEB)					
CAUSE OF AUTO-CANCEL 2	NOTE: The item is displayed, but it is not monitored					
CAUSE OF AUTO-CANCEL 3	Displays causes of automatic system cancellation occurred during control of the Back-up Collision Intervention (BCI)					

NOTE:

- Causes of the maximum five cancellations (system cancel) are displayed.
- The displayed cancellation causes display the number of the ignition switch ON/OFF up to 254. It is fixed to 254 if it is over 254. It returns to 0 when the same cancellation cause is detected again.

Display Items for The Cause of Automatic Cancellation 1

Cause of cancellation	Vehicle-to-vehicle distance control mode	Conventional (fixed speed) cruise control mode	Distance Control Assist	Forward Emergency Braking	Description
OPERATING ABS	×		×	×	ABS function was operated
OPERATING TCS	×	×	×		TCS function was operated
OPERATING VDC	×	×	×	×	VDC function was operated
ECM CIRCUIT	×	×			ECM did not permit ICC operation
OPE SW VOLT CIRC	×	×	×		The ICC steering switch input voltage is not within standard range
SNOW MODE SW	×		×		Shifting of the drive mode selector to SNOW position
OP SW DOUBLE TOUCH	×	×			ICC steering switches were pressed at the same time
VHCL SPD DOWN	×	×	×		Vehicle speed lower than the speed as follows Vehicle-to-vehicle distance control mode is 24 km/h (15 MPH) Conventional (fixed speed) cruise control mode is 32 km/h (20 MPH)

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WHL SPD ELEC NOISE	×	×	×		Wheel speed sensor signal caught electromagnetic noise
VDC/TCS OFF SW	×		×	×	VDC OFF switch was pressed
VHCL SPD UNMATCH	×	×	×		Wheel speed became different from A/T vehicle speed
TIRE SLIP	×	×			Wheel slipped
IGN LOW VOLT	×	×	×	×	Decrease in ADAS control unit ignition voltage
PARKING BRAKE ON	×	×			The parking brake is operating
WHEEL SPD UNMATCH	×	×	×		The wheel speeds of 4 wheels are out of the specified values
INCHING LOST	×				A vehicle ahead is not detected during the following driving when the vehicle speed is approximately 24 km/h (15 MPH) or less
CAN COMM ERROR	×	×	×	×	ADAS control unit received an abnormal signal with CAN communication
ABS/TCS/VDC CIRC	×	×	×	×	An abnormal condition occurs in VDC/TCS/ABS system
ECD CIRCUIT	×	×	×	×	An abnormal condition occurs in ECD system
ENG SPEED DOWN	×	×			Engine speed became extremely low while controlling ICC system
ASCD VHCL SPD DTAC		×			Vehicle speed is detached from set vehicle speed
ASCD DOUBLE COMD		×			Cancel switch and operation switch are detected simultaneously
APA HI TEMP			×		The accelerator pedal actuator integrated motor temperature is high
ICC SENSOR CAN COMM ERR	×		×	×	Communication error between ADAS control unit and the ICC sensor
ABS WARNING LAMP	×		×		ABS warning lamp ON
FR RADAR BLOCKED	×		×	×	Inclusion of dirt or stains on the ICC sensor area of the front bumper
FEB) CURVATURE				×	Road curve was more than the specified value
FEB) YAW RATE				×	Detected yawing speed was more than the specified value
FEB) LTRL ACCELERA- TION				×	Detected lateral speed is the specified value or more
RADAR INTERFER- ENCE	×		×	×	ICC sensor receives electromagnetic interference
NO RECORD	×	×	×		_

Display Items for The Cause of Automatic Cancellation 3

Cause of cancellation	Back-up Collision Intervention	Description
CAN COMM ERROR (CAN)	×	ADAS control unit received an abnormal signal with CAN communication
CAN COMM ERROR (ECD)	×	ADAS control unit received an abnormal signal with CAN communication
IGN LOW VOLT	×	Decrease in ADAS control unit ignition voltage
VEHICLE SPEED UP	×	Vehicle speed higher than 8 km/h (5 MPH)
ACCEL IS OPERATED	×	Accelerator pedal was depressed
BRAKE IS OPERATED	×	Brake pedal was operated
APA HI TEMP	×	The accelerator pedal actuator integrated motor temperature is high

[ICC]

Cause of cancellation	Back-up Collision Intervention	Description
APA POWER	×	Decrease in accelerator pedal actuator ignition or battery voltage
NO RECORD	×	-

SELF DIAGNOSTIC RESULT

Refer to DAS-44, "DTC Index".

DATA MONITOR

NOTE:

The following table includes information (items) inapplicable to this vehicle. For information (items) applicable to this vehicle, refer to CONSULT display items.

Monitored item [Unit]	ALL SIG (ICC)	MAIN SIG (ICC)	MAIN SIG (LDW/LDP)	MAIN SIG (BSW/BSI)	MAIN SIG (BCI)	Description
MAIN SW [On/Off]	×	×	×	×		Indicates [On/Off] status as judged from ICC steering switch
SET/COAST SW [On/Off]	×	×				Indicates [On/Off] status as judged from ICC steering switch
CANCEL SW [On/Off]	×	×				Indicates [On/Off] status as judged from ICC steering switch
RESUME/ACC SW [On/Off]	×	×				Indicates [On/Off] status as judged from ICC steering switch
DISTANCE SW [On/Off]	×					Indicates [On/Off] status as judged from ICC steering switch
CRUISE OPE [On/Off]	×	×				Indicates whether controlling or not (ON means "controlling")
ON ROOT GUID- ANCE [On/Off]	×					NOTE: The item is displayed, but it is not monitored
BRAKE SW [On/Off]	×	×	×	×	×	Indicates [On/Off] status as judged from ICC brake switch signal (ECM transmits ICC brake switch signal through CAN communication)
STOP LAMP SW [On/Off]	×	×	×	×	×	Indicates [On/Off] status as judged from stop lamp switch signal (ECM transmits stop lamp switch signal through CAN communication)
CLUTCH SW SIG [On/Off]	×	×	×	×		Indicates [On/Off] status as judged from clutch pedal position signal (ECM transmits ICC clutch switch signal through CAN communication)
IDLE SW [On/Off]	×				×	Indicates [On/Off] status of idle switch read from ADAS control unit through CAN communication (ECM transmits On/Off status through CAN communication)
SET DISTANCE [Short/Mid/Long]	×	×				Indicates set distance memorized in ADAS control unit
CRUISE LAMP [On/Off]	×	×				Indicates [On/Off] status of MAIN switch indicator output
OWN VHCL [On/Off]	×					Indicates [On/Off] status of own vehicle indicator output

< SYSTEM DESCRIPTION > [ICC]

Monitored item [Unit]	ALL SIG (ICC)	MAIN SIG (ICC)	MAIN SIG (LDW/LDP)	MAIN SIG (BSW/BSI)	MAIN SIG (BCI)	Description
VHCL AHEAD [On/Off]	×					Indicates [On/Off] status of vehicle ahead detection indicator output
ICC WARNING [On/Off]	×					Indicates [On/Off] status of ICC system warning lamp output
VHCL SPEED SE [km/h] or [mph]	×	×	×	×	×	Indicates vehicle speed calculated from ADAS control unit through CAN communication [ABS actuator and electric unit (control unit) transmits vehicle speed signal (wheel speed) through CAN communication]
SET VHCL SPD [km/h] or [mph]	×	×				Indicates set vehicle speed memorized in ADAS control unit
BUZZER O/P [On/Off]	×				×	Indicates [On/Off] status of ICC warning chime output
THRTL SENSOR [deg]	×	×				NOTE: The item is displayed, but it is not monitored
ENGINE RPM [rpm]	×					Indicates engine speed read from ADAS control unit through CAN communication (ECM transmits engine speed signal through CAN communication)
WIPER SW [OFF/LOW/HIGH]	×					Indicates wiper [OFF/LOW/HIGH] status (BCM transmits front wiper request signal through CAN communication)
YAW RATE [deg/s]	×					NOTE: The item is displayed, but it is not monitored
BA WARNING [On/Off]	×					Indicates [On/Off] status of FEB indicator lamp output
STP LMP DRIVE [On/Off]	×	×			×	Indicates [On/Off] status of ICC brake hold relay drive output
D RANGE SW [On/Off]	×					Indicates [On/Off] status of "D" or "M" positions read from ADAS control unit through CAN communication; ON when position "D" or "M" (TCM transmits shift position signal through CAN communication).
NP RANGE SW [On/Off]	×					Indicates shift position signal read from ADAS control unit through CAN communication (TCM transmits shift position signal through CAN communication)
PKB SW [On/Off]	×					Parking brake switch status [On/Off] judged from the parking brake switch signal that ADAS control unit readout via CAN communication is displayed (combination meter transmits the parking brake switch signal via CAN communication)
PWR SUP MONI [V]	×	×				Indicates IGN voltage input by ADAS control unit
VHCL SPD AT [km/h] or [mph]	×					Indicates vehicle speed calculated from A/T vehicle speed sensor read from ADAS control unit through CAN communication (TCM transmits A/T vehicle speed sensor signal through CAN communication)
THRTL OPENING [%]	×	×			×	Indicates throttle position read from ADAS control unit through CAN communication (ECM transmits accelerator pedal position signal through CAN communication).
GEAR [1, 2, 3, 4, 5, 6, 7]	×					Indicates A/T gear position read from ADAS control unit through CAN communication (TCM transmits current gear position signal through CAN communication)
NP SW SIG [On/Off]	×					Indicates [On/Off] status as judged from park/neutral position switch signal (ECM transmits park/neutral position switch signal through CAN communication).
MODE SIG [OFF, ICC, ASCD]	×					Indicates the active mode from ICC or ASCD [conventional (fixed speed) cruise control mode]
SET DISP IND [On/Off]	×					Indicates [On/Off] status of SET switch indicator output

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< SYSTEM DESCRIPTION >

[ICC]

Monitored item [Unit]	ALL SIG (ICC)	MAIN SIG (ICC)	MAIN SIG (LDW/LDP)	MAIN SIG (BSW/BSI)	MAIN SIG (BCI)	Description
DISTANCE [m]	×					Indicates the distance from the vehicle ahead
RELATIVE SPD [m/s]	×					Indicates the relative speed of the vehicle ahead
DYNA ASIST SW [On/Off]	×	×		×		Indicates [On/Off] status as judged from ICC steering switch signal (ECM transmits ICC steering switch signal through CAN communication)
DCA ON IND [On/Off]	×					The status [ON/OFF] of DCA system switch indicator output is displayed
DCA VHL AHED [On/Off]	×					The status [ON/OFF] of vehicle ahead detection indicator output in DCA system is displayed
IBA SW [On/Off]	×	×				NOTE: The item is displayed, but it is not monitored
FCW SYSTEM ON [On/Off]	×	×				Indicates [On/Off] status of PFCW system
APA TEMP [°C]	×				×	Accelerator pedal actuator integrated motor temperature that the ADAS control unit readout via ITS communication is displayed (Accelerator pedal actuator transmits the integrated motor temperature via ITS communication)
APA PWR [V]	×				×	Accelerator pedal actuator power supply voltage that the ADAS control unit readout via ITS communication is displayed (Accelerator pedal actuator transmits the power supply voltage via ITS communication)
LDW SYSTEM ON [On/Off]			×			Indicates [On/Off] status of LDW system
LDW ON LAMP [On/Off]			×			Indicates [On/Off] status of LDW system display output
LDP ON IND [On/Off]			×			Indicates [On/Off] status of LDP system display output
LANE DPRT W/L [On/Off]			×			Indicates [On/Off] status of LDW/LDP warning display (Yellow) output
LDW BUZER OUT- PUT [On/Off]			×			Indicates [On/Off] status of warning buzzer output
LDP SYSTEM ON [On/Off]			×			Indicates [On/Off] status of LDP system
WARN REQ [On/Off]			×			Indicates an ADAS control unit judged warning state (ON/OFF) of LDP system
READY signal [On/Off]			×			Indicates LDP system settings
Camera lost [Detect/Deviate/Both]			×	×		Indicates a lane marker detection state judged from a lane marker detection signal read by the ADAS control unit via ITS communication (Lane camera unit transmits a lane marker signal via ITS communication)
Shift position [Off, P, R, N, D, M/T1 - 7]			×	×	×	Indicates shift position read from ADAS control unit through CAN communication (TCM transmits shift position signal through CAN communication)
Turn signal [OFF/LH/RH/LH&RH]			×	×		Indicates turn signal operation status read from ADAS control unit through CAN communication (BCM transmits turn indicator signal through CAN communication)
SIDE G [G]			×	×		Indicates lateral G acting on the vehicle. This lateral G is judged from a side G sensor signal read by ADAS control unit via CAN communication (The ABS actuator and electric unit (control unit) transmits a side G sensor signal via CAN communication)

< SYSTEM DESCRIPTION > [ICC]

Monitored item [Unit]	ALL SIG (ICC)	MAIN SIG (ICC)	MAIN SIG (LDW/LDP)	MAIN SIG (BSW/BSI)	MAIN SIG (BCI)	Description
STATUS signal [Stnby/Warn/Cancl/ Off]			×			Indicates a control state of LDP system
Lane unclear [On/Off]			×	×		Indicates an ON/OFF state of the lane marker. The ON/OFF state is judged from a detected lane condition signal read by the ADAS control unit via ITS communication (The lane camera unit transmits a detected lane condition signal via ITS communication)
FUNC ITEM (FCW) [On/Off]	×	×	×	×		Indicates systems which can be set to ON/OFF by selecting "Driver Aids" ⇒ "Emergency Assist" of the integral switch Forward Emergency Braking
FUNC ITEM (LDW) [On/Off]	×	×	×	×		Indicates systems which can be set to ON/OFF by selecting "Driver Aids" ⇒ "Lane" of the integral switch Lane Departure Warning
FUNC ITEM (BSW) [On/Off]	×	×	×	×		Indicates systems which can be set to ON/OFF by selecting "Driver Aids" ⇒ "Blind spot" of the integral switch Blind Spot Warning
FUNC ITEM (NV-ICC) [Off]	×	×	×	×		NOTE: The item is displayed, but it is not monitored
FUNC ITEM (NV- DCA) [Off]	×	×	×	×		NOTE: The item is displayed, but it is not monitored
DCA SELECT [On/Off]	×	×	×	×		Indicates an ON/OFF state of the DCA system. The DCA system can be set to ON/OFF by selecting "Driving Aids" ⇒ "Front assist" of the integral switch
LDP SELECT [On/Off]	×	×	×	×		Indicates an ON/OFF state of LDP system. LDP system can be set to ON/OFF by selecting "Driving Aids" ⇒ "Lane" of the integral switch
BSI SELECT [On/Off]	×	×	×	×		Indicates an ON/OFF state of Blind Spot Intervention system. Blind Spot Intervention system can be set to ON/OFF by selecting "Driving Aids" ⇒ "Blind Spot" of the integral switch
FCW SELECT [On/Off]	×	×	×	×		Indicates an ON/OFF state of the PFCW system. The PFCW system can be set to ON/OFF by selecting "Driving Aids" ⇒ "Emergency Assist" of the integral switch
LDW SELECT [On/Off]	×	×	×	×		Indicates an ON/OFF state of the LDW system. The LDW system can be set to ON/OFF by selecting "Driving Aids" ⇒ "Lane" of the integral switch
BSW SELECT [On/Off]	×	×	×	×		Indicates an ON/OFF state of the BSW system. The BSW system can be set to ON/OFF by selecting "Driving Aids" ⇒ "Blind spot" of the integral switch
NAVI ICC SELECT [Off]	×	×	×	×		NOTE: The item is displayed, but it is not monitored
NAVI DCA SELECT [Off]	×	×	×	×		NOTE: The item is displayed, but it is not monitored
SYS SELECTABILITY [On/Off]	×	×	×	×		Indicates the availability of ON/OFF switching for "Driving Aids" items received from the integral switch via CAN communication
DRIVE MODE STATS [STD/SPORT/ECO/ SNOW/MID/ERROR]	×	×	×	×		Indicates a drive mode selector select position judged from a drive mode select switch position signal read by the ADAS control unit via CAN communication (The chassis control module transmits a switch position signal of the drive mode select switch signal via CAN communication)
WARN SYS SW [On/Off]	×	×	×	×		NOTE: The item is displayed, but it is not monitored
BSW/BSI WARN LMP [On/Off]				×		Indicates [On/Off] status of Blind Spot warning malfunction

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< SYSTEM DESCRIPTION >

[ICC]

Monitored item [Unit]	ALL SIG (ICC)	MAIN SIG (ICC)	MAIN SIG (LDW/LDP)	MAIN SIG (BSW/BSI)	MAIN SIG (BCI)	Description
BSI ON IND [On/Off]				×		Indicates [On/Off] status of Blind Spot Intervention system display
BSW SYSTEM ON [On/Off]				×		Indicates [On/Off] status of BSW system
BSI SYSTEM ON [On/Off]				×		Indicates [On/Off] status of Blind Spot Intervention system
BCI SYSTEM ON [On/Off]					×	Indicates [On/Off] status of BCI system
BATTERY CIRCUIT OFF [On/Off]	×					NOTE: The item is displayed, but it is not used
LDP WARNING INDI- CATOR [On/Off]			×			Indicates [On/Off] status of LDP warning display (Yellow) output
LDW ON INDICATOR [On/Off]			×			Indicates [On/Off] status of LDW system ON display output
LDW WARNING INDI- CATOR [On/Off]			×			Indicates [On/Off] status of LDW system warning display output
SYSTEM CANCEL MESSAGE [NOREQ/SLIP/ SNOW/VDC OFF]	×	×	×	×		Indicates [On/Off] status of system cancel display output
CAMERA HI TEMP MSG [On/Off]			×	×		Indicates [On/Off] status of lane camera unit high temperature warning display output
ITS SETTING ITEM(DCA) [On/Off]	×	×	×	×		Indicates the presence or absence of DCA system.
ITS SETTING ITEM(LDP) [On/Off]	×	×	×	×		Indicates the presence or absence of LDP system.
ITS SETTING ITEM(BSI) [On/Off]	×	×	×	×		Indicates the presence or absence of Blind Spot Intervention system.
BSI WARNING INDI- CATOR [On/Off]				×		Indicates [On/Off] status of Blind Spot Intervention warning display output
BSW ON INDICATOR [On/Off]				×		Indicates [On/Off] status of BSW system ON display output
SIDE RADAR BLOCK COND [On/Off]				×		Indicates [On/Off] status of side radar with dirt or foreign materials
LDW WARNING ALERT TIMING [Nothing/Early/Late]			×			NOTE: The item is displayed, but it is not monitored
BSW IND BRIGHT- NESS [Nothing/Bright/Nor- mal/Dark]				×		Indicates status of brightness of Blind Spot Warning/Blind Spot Intervention indicator
SL MAIN SW [On/Off]		×				Indicates [On/Off] status as judged from steering switch

< SYSTEM DESCRIPTION > [ICC]

Monitored item [Unit]	ALL SIG (ICC)	MAIN SIG (ICC)	MAIN SIG (LDW/LDP)	MAIN SIG (BSW/BSI)	MAIN SIG (BCI)	Description
FUNC ITEM(FEB) [On/Off]	×					Indicates systems which can be set to ON/OFF by selecting "Driver Aids" ⇒ "Emergency Assist" of the integral switch Forward Emergency Braking
FEB SELECT [On/Off]	×					Indicates an ON/OFF state of the FEB system. The FEB system can be set to ON/OFF by selecting "Driving Aids" ⇒ "Emergency Assist" of the integral switch
FEB SW [On/Off]	×					Indicates [On/Off] status of FEB system
SL TARGET VEHI- CLE SPEED [km/h]	×					Indicates set vehicle speed memorized in ADAS control unit
SL SET LAMP [On/Off]	×					Indicates [On/Off] status of speed limiter SET display output
SL LIMIT LAMP [On/Off]	×					Indicates [On/Off] status of speed limiter MAIN switch display output
ASCD CANCEL (LOW SPEED) [NON/CUT]	×					Indicates the vehicle cruise condition. NON: Vehicle speed is maintained at the ASCD set speed. CUT: Vehicle speed decreased to excessively low, and ASCD operation is cut off.
ASCD CANCEL (SPEED DIFF) [NON/CUT]	×					Indicates the vehicle cruise condition. NON: Vehicle speed is maintained at the ASCD set speed. CUT: Vehicle speed decreased to excessively low compared with the ASCD set speed, and ASCD operation is cut off.
KICK DOWN [On/Off]	×					Display Kick Down decision state. On: Accelerator pedal is depressed Off: Accelerator pedal is fully released

ACTIVE TEST

CAUTION:

- Never perform "Active Test" while driving the vehicle.
- The "Active Test" cannot be performed when the following systems malfunction is displayed.
- ICC system
- DCA
- LDW
- LDP
- Blind Spot Warning
- Blind Spot Intervention
- BCI
- The "Active Test" cannot be performed when the FEB warning lamp is illuminated.
- Shift the selector lever to "P" position, and then perform the test.

Test item	Description
METER LAMP	The MAIN switch indicator and FEB warning lamp can be illuminated by ON/OFF operations as necessary
STOP LAMP	The ICC brake hold relay can be operated by ON/OFF operations as necessary, and the stop lamp can be illuminated
ICC BUZZER	Sounds a buzzer used for following systems by arbitrarily operating ON/OFF Intelligent Cruise Control (ICC) Distance Control Assist (DCA) Predictive Forward Collision Warning (PFCW) Forward Emergency Brake (FEB)
BRAKE ACTUATOR	Activates the brake by an arbitrary operation
ACTIVE PEDAL	The accelerator pedal actuator can be operated as necessary
DCA INDICATOR	The DCA system display can be illuminated by ON/OFF operations as necessary

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[ICC]

Test item	Description
Sounds a buzzer used for following systems by arbitrarily operating ON/OFF • Lane Departure Warning (LDW) • Lane Departure Prevention (LDP) • Blind Spot Warning (BSW) • Blind Spot Intervention	
LDP ON IND	The LDP system display can be illuminated by ON/OFF operations as necessary
LANE DEPARTURE W/L	The LDW/LDP warning can be illuminated by ON/OFF operations as necessary
BSW ON INDICATOR	The Blind Spot Warning system display can be illuminated by ON/OFF operations as necessary
BSI ON INDICATOR	The Blind Spot Intervention system display can be illuminated by ON/OFF operations as necessary
LDW ON INDICATOR	The LDW system display can be illuminated by ON/OFF operations as necessary
LDP WARNING INDICATOR	The LDP malfunction can be illuminated by ON/OFF operations as necessary
LDW WARNING INDICATOR	The LDW malfunction can be illuminated by ON/OFF operations as necessary
BSW WARNING INDICATOR	The BSW malfunction can be illuminated by ON/OFF operations as necessary
BSI WARNING INDICATOR	The Blind Spot Intervention malfunction can be illuminated by ON/OFF operations as necessary

METER LAMP

NOTE:

The test can be performed only when the engine is running.

Test item	Oper- ation	Description	MAIN switch indicator ICC system warning FEB warning lamp
METER LAMP	Off	Stops sending the following signals to exit from the test • Meter display signal • FEB warning lamp signal	OFF
	On	Transmits the following signals to the combination meter via CAN communication • Meter display signal • FEB warning lamp signal	ON

STOP LAMP

Test item	Oper- ation	Description	Stop lamp
STOP LAMP	Off	Stops transmitting the ICC brake hold relay drive signal below to end the test	OFF
	On	Transmits the ICC brake hold relay drive signal	ON

ICC BUZZER

Test item	Operation	Description	Operation sound
ICC BUZZER	MODE1	Transmits the buzzer output signals to the driver assistance buzzer control module via ITS communication	Intermittent beep sound
	Test start	Starts the tests of "MODE1"	_
ICC BUZZER	Reset	Stops transmitting the buzzer output signal below to end the test	_
	End	Returns to the "SELECT TEST ITEM" screen	_

BRAKE ACTUATOR

NOTE:

The test can be performed only when the engine is running.

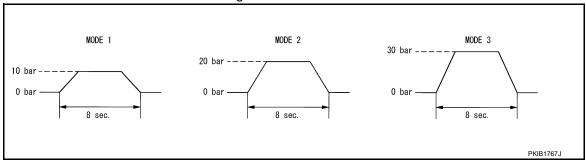
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Test item	Operation	Description	"PRESS SENS" value
BRAKE ACTUATOR	MODE1	Transmits the brake fluid pressure control signal to the ABS actuator and electric unit (control unit) via chassis	10 bar
	MODE2		20 bar
	MODE3	control module	30 bar
	Test start	Starts the tests of "MODE1", "MODE2" and "MODE3"	_
	Reset	Stops transmitting the brake fluid pressure control signal below to end the test	_
	End	Returns to the "SELECT TEST ITEM" screen	_

NOTE:

The test is finished in 10 seconds after starting



Active Pedal

CAUTION:

- Shift the selector lever to "P" position, and then perform the test.
- Never depress the accelerator pedal excessively. (The engine speed may rise unexpectedly when finishing the test.)

NOTE:

- Depress the accelerator pedal to check when performing the test.
- The test can be performed only when the engine is running.

Test item	Operation	Description	Accelerator pedal operation
	MODE1		Constant with a force of 25 N for 8 seconds
ACTIVE PEDAL	MODE2	Transmit the accelerator pedal feedback force control signal	Constant with a force of 15 N for 8 seconds
	MODE3	to the accelerator pedal actuator via ITS communication.	Change up to a force of 25 N for 8 seconds
	MODE4		Change up to a force of 15 N for 8 seconds
	Test start	Starts the tests of "MODE1", "MODE2", "MODE3" and "MODE4"	_
	Reset	Stops transmitting the accelerator pedal feedback force control signal below to end the test.	_
	End	Returns to the "SELECT TEST ITEM" screen	_

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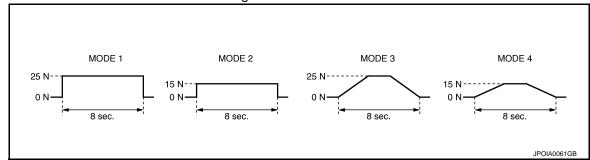
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[ICC]

The test is finished in 10 seconds after starting



DCA INDICATOR

NOTE:

The test can be performed only when the engine is running.

Test item	Opera- tion	Description	DCA system display
	Off	Stops transmitting the meter display signal below to end the test	_
DCA INDICATOR —	On	Transmits the meter display signal to the combination meter via CAN communication	ON

LDP BUZZER

Test item	Opera- tion	Description	Warning buzzer
LDP BUZZER	Off	Stops transmitting the warning buzzer signal below to end the test	_
	On	Transmits the warning buzzer signal to the warning buzzer	ON

LDP ON IND

Test item	Oper- ation	Description	LDP system display (Green)
LDP ON IND	Off	Stops transmitting the meter display signal below to end the test	_
	On	Transmits the meter display signal to the combination meter via CAN communication	ON

LANE DEPARTURE W/L

Test item	Oper- ation	Description	Lane departure system display (Yellow)
LANE DEPARTURE W/L	Off	Stops transmitting the meter display signal below to end the test	_
	On	Transmits the meter display signal to the combination meter via CAN communication	ON

BSW ON INDICATOR

Test item	Oper- ation	Description	Blind Spot Warning system display (Yellow)
BSW ON INDICATOR	Off	Stops transmitting the meter display signal below to end the test	_
	On	Transmits the meter display signal to the combination meter via CAN communication	ON

BSI ON INDICATOR

< SYSTEM DESCRIPTION >

Test item	Oper- ation	Description	Blind Spot Intervention system display (Green)
BSI ON INDICATOR	Off	Stops transmitting the meter display signal below to end the test	_
B3I ON INDICATOR	On	Transmits the meter display signal to the combination meter via CAN communication	ON
DW ON INDICATOR			
Test item	Oper- ation	Description	LDW system display (White)
LDW ON INDICATOR	Off	Stops transmitting the meter display signal below to end the test	_
LDW ON INDICATOR	On	Transmits the meter display signal to the combination meter via CAN communication	ON
DP WARNING INDIC	CATOR		
Test item	Oper- ation	Description	LDP malfunction (Yellow)
LDP WARNING INDI- CATOR	Off	Stops transmitting the meter display signal below to end the test	_
	On	Transmits the meter display signal to the combination meter via CAN communication	ON
DW WARNING INDI	CATOR		
Test item	Oper- ation	Description	LDW malfunction (Yellow)
LDW WARNING IN-	Off	Stops transmitting the meter display signal below to end the test	_
DICATOR	On	Transmits the meter display signal to the combination meter via CAN communication	ON
SSW WARNING INDI	CATOR		
Test item	Oper- ation	Description	BSW malfunction (Yellow)
BSW WARNING IN-	Off	Stops transmitting the meter display signal below to end the test	_
DICATOR	On	Transmits the meter display signal to the combination meter via CAN communication	ON
SI WARNING INDIC	ATOR		
Test item	Oper- ation	Description	Blind Spot Intervention malfunction (Yellow)
BSI WARNING INDI-	Off	Stops transmitting the meter display signal below to end the test	_
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Transmits the meter display signal to the combination

meter via CAN communication

CATOR

On

DIAGNOSIS SYSTEM (ICC SENSOR)

< SYSTEM DESCRIPTION >

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DIAGNOSIS SYSTEM (ICC SENSOR)

CONSULT Function (LASER/RADAR)

INFOID:0000000009644220

APPLICATION ITEMS

CONSULT performs the following functions via CAN communication with ADAS control unit and the communication with ICC sensor.

Diagnosis mode	Description	
Work Support	It can monitor the adjustment direction indication in order to perform the radar alignment operation smoothly	
Self Diagnostic Result	Displays malfunctioning system memorized in ICC sensor	
Data Monitor	Displays real-time input/output data of ICC sensor	
ECU Identification	Displays ICC sensor part number	
CAN Diag Support Monitor	The results of transmit/receive diagnosis of ITS communication can be read	

WORK SUPPORT

Work support items	Description
MILLIWAVE RADAR ADJUST	Outputs millimeter waves, calculates dislocation of the millimeter waves, and indicates adjustment direction

Radar Alignment

Refer to CCS-83, "TYPE 1: Description".

SELF DIAGNOSTIC RESULT

Refer to CCS-63, "DTC Index".

DATA MONITOR

NOTE:

The following table includes information (items) inapplicable to this vehicle. For information (items) applicable to this vehicle, refer to CONSULT display items.

Monitored item [Unit]	Description
VHCL SPEED SE [km/h] or [mph]	Vehicle speed judged from a vehicle speed signal read by the ICC sensor via ITS communication is displayed [ADAS control unit receives a vehicle speed signal from ABS actuator and electric unit (control unit) via CAN communication and transmits the calculated vehicle speed to ICC sensor via ITS communication]
YAW RATE [deg/s]	Indicates yaw rate read from ADAS control unit through ITS communication (ADAS control unit receives yaw rate signal from ABS actuator and electric unit (control unit) via CAN communication and transmits yaw rate calculated by the ADAS control unit) Yaw rate judged from a yaw rate signal read by ICC sensor via ITS communication is displayed [ADAS control unit receives a yaw rate signal from ABS actuator and electric unit (control unit) via CAN communication and transmits the calculated yaw rate to ICC sensor via ITS communication]
PWR SUP MONI [V]	Indicates IGN voltage input by ICC sensor
DISTANCE [m]	Indicates the distance from the vehicle ahead
RELATIVE SPD [m/s]	Indicates the relative speed of the vehicle ahead
RADAR OFFSET [m]	NOTE: The item is indicated, but not used
RADAR HEIGHT [m]	NOTE: The item is indicated, but not used
STEERING ANGLE [deg]	The steering angle is displayed

DIAGNOSIS SYSTEM (ICC SENSOR)

< SYSTEM DESCRIPTION > [ICC]

Monitored item [Unit]	Description
STRG ANGLE SPEED [deg/s]	The steering angle speed is displayed
L/R ADJUST	The horizontal correction value of the radar is displayed
U/D ADJUST	The vertical correction value of the radar is displayed

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DIAGNOSIS SYSTEM (DRIVER ASSISTANCE BUZZER CONTROL MOD-ULE)

CONSULT Function (BSW/BUZZER)

INFOID:0000000009791211

DESCRIPTION

CONSULT performs the following functions via CAN communication with ADAS control unit and the communication with driver assistance buzzer control module.

Test mode	Function
Self Diagnostic Result	 Displays malfunctioning system memorized in driver assistance buzzer control module Displays the Freeze Frame Data when the malfunction is detected
DATA MONITOR	Displays real-time input/output data of driver assistance buzzer control module
ACTIVE TEST	Enables operation check of electrical loads by sending driving signal to them
ECU Identification	Displays driver assistance buzzer control module parts number

SELF DIAGNOSTIC RESULT

Self Diagnostic Result

Refer to DAS-280, "DTC Index".

FFD (Freeze Frame Data)

The drive assistance buzzer control module records the following data when the malfunction is detected.

Freeze Frame Data item [Unit]	Description
IGN Counter ^{Note}	It displays number of ignition switch OFF $ ightarrow$ ON after the malfunction is detected

NOTE:

- The number is 0 when is detected now.
- The number increases like 1→ 2 ··· 38 → 39 after returning to the normal condition whenever IGN OFF → ON.
- The number is fixed to 39 until the self-diagnosis results are erased if it is over 39.

DATA MONITOR

NOTE:

The following table includes information (items) inapplicable to this vehicle. For information (items) applicable to this vehicle, refer to CONSULT display items.

Monitor item [Unit]	FUNCTION DESCRIPTION
Buzzer 1 request (ADAS) [Off/TYPE 1 - 3/Cancel]	Indicates buzzer request type status as judged from ADAS control unit through ITS communication (The ADAS control unit transmits the driver assistance buzzer signal via ITS communication)
Buzzer 1 volume (ADAS) [Vol. 1- 16]	Indicates buzzer volume status as judged from ADAS control unit through ITS communication (The ADAS control unit transmits the driver assistance buzzer signal via ITS communication)
Buzzer 1 stop (ADAS) [CYCLE/IMEDIAT]	Indicates buzzer stop status as judged from ADAS control unit through ITS communication (The ADAS control unit transmits the driver assistance buzzer signal via ITS communication)
Buzzer 2 request (ADAS) [Off/TYPE 1 - 3/Cancel]	Indicates buzzer request type status as judged from ADAS control unit through ITS communication (The ADAS control unit transmits the driver assistance buzzer signal via ITS communication)
Buzzer 2 volume (ADAS) [Vol. 1- 16]	Indicates buzzer volume status as judged from ADAS control unit through ITS communication (The ADAS control unit transmits the driver assistance buzzer signal via ITS communication)
Buzzer 2 stop (ADAS) [CYCLE/IMEDIAT]	Indicates buzzer stop status as judged from ADAS control unit through ITS communication (The ADAS control unit transmits the driver assistance buzzer signal via ITS communication)
Buzzer 3 request (ADAS) [Off/TYPE 1/Cancel]	Indicates buzzer request type status as judged from ADAS control unit through ITS communication (The ADAS control unit transmits the driver assistance buzzer signal via ITS communication)
Buzzer 3 volume (ADAS) [Vol. 1- 16]	Indicates buzzer volume status as judged from ADAS control unit through ITS communication (The ADAS control unit transmits the driver assistance buzzer signal via ITS communication)

[IČC] < SYSTEM DESCRIPTION >

Monitor item [Unit]	FUNCTION DESCRIPTION
Buzzer 3 stop (ADAS) [CYCLE/IMEDIAT]	Indicates buzzer stop status as judged from ADAS control unit through ITS communication (The ADAS control unit transmits the driver assistance buzzer signal via ITS communication)
Buzzer 4 request (ADAS) [Off/TYPE 1 - 7/Cancel]	Indicates buzzer request type status as judged from ADAS control unit through ITS communication (The ADAS control unit transmits the driver assistance buzzer signal via ITS communication)
Buzzer 4 volume (ADAS) [Vol. 1- 16]	Indicates buzzer volume status as judged from ADAS control unit through ITS communication (The ADAS control unit transmits the driver assistance buzzer signal via ITS communication)
Buzzer 4 stop (ADAS) [CYCLE/IMEDIAT]	Indicates buzzer stop status as judged from ADAS control unit through ITS communication (The ADAS control unit transmits the driver assistance buzzer signal via ITS communication)
Buzzer 1 request (CCM) [Off/TYPE 1 - 3/Cancel]	Indicates buzzer request type status as judged from chassis control module through chassis communication (The ADAS control unit transmits the driver assistance buzzer signal via chassis communication)
Buzzer 1 volume (CCM) [Vol. 1- 16]	Indicates buzzer volume status as judged from chassis control module through chassis communica tion
[100. 1 10]	(The ADAS control unit transmits the driver assistance buzzer signal via chassis communication)
Buzzer 1 stop (CCM) [CYCLE/IMEDIAT]	Indicates buzzer stop status as judged from chassis control module through chassis communication (The ADAS control unit transmits the driver assistance buzzer signal via chassis communication)
Buzzer 2 request (CCM) [Off/TYPE 1 - 3/Cancel]	Indicates buzzer request type status as judged from chassis control module through chassis communication (The ADAS control unit transmits the driver assistance buzzer signal via chassis communication)
Buzzer 2 volume (CCM) [Vol. 1-16]	Indicates buzzer volume status as judged from chassis control module through chassis communication (The ADAS control unit transmits the driver assistance buzzer signal via chassis communication)
Buzzer 2 stop (CCM) [CYCLE/IMEDIAT]	Indicates buzzer stop status as judged from chassis control module through chassis communication (The ADAS control unit transmits the driver assistance buzzer signal via chassis communication)
Buzzer 3 request (CCM) [Off/TYPE 1/Cancel]	Indicates buzzer request type status as judged from chassis control module through chassis communication (The ADAS control unit transmits the driver assistance buzzer signal via chassis communication)
Buzzer 3 volume (CCM) [Vol. 1- 16]	Indicates buzzer volume status as judged from chassis control module through chassis communication (The ADAS control unit transmits the driver assistance buzzer signal via chassis communication)
Buzzer 3 stop (CCM) [CYCLE/IMEDIAT]	Indicates buzzer stop status as judged from chassis control module through chassis communication (The ADAS control unit transmits the driver assistance buzzer signal via chassis communication)
Buzzer 4 request (CCM) [Off/TYPE 1 - 7/Cancel]	Indicates buzzer request type status as judged from chassis control module through chassis communication (The ADAS control unit transmits the driver assistance buzzer signal via chassis communication)
Buzzer 4 volume (CCM) [Vol. 1-16]	Indicates buzzer volume status as judged from chassis control module through chassis communication (The ADAS control unit transmits the driver assistance buzzer signal via chassis communication)
Buzzer 4 stop (CCM) [CYCLE/IMEDIAT]	Indicates buzzer stop status as judged from chassis control module through chassis communication (The ADAS control unit transmits the driver assistance buzzer signal via chassis communication)
ADAS MALFUNCTION [Off/On]	Indicates ADAS control unit status
CCM MALFUNCTION [Off/On]	Indicates chassis control module status
DR ASSIST BUZZ MALF [Off/On]	Indicates driver assistance control buzzer module status
DR ASSIST BUZZ STATUS [1/2/3/1, 2/2, 4/1, 4/4]	Indicates driver assistance control buzzer sound status

ACTIVE TEST

CAUTION:

Never perform ACTIVE TEST while driving the vehicle.

Item list

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< SYSTEM DESCRIPTION >

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Active test item	Description
BUZZER 1 (ADAS)	Sounds a buzzer used for following systems by arbitrarily operating ON/OFF Lane Departure Warning (LDW) Blind Spot Warning (BSW) Blind Spot Intervention
BUZZER 2 (ADAS)	Sounds a buzzer used for following systems by arbitrarily operating ON/OFF Intelligent Cruise Control (ICC) Predictive Forward Collision Warning (PFCW) Distance Control Assist (DCA)
BUZZER 3 (ADAS)	Sounds a buzzer used for following systems by arbitrarily operating ON/OFF • Forward Emergency Braking (FEB)
BUZZER 4 (ADAS)	Sounds a buzzer used for following systems by arbitrarily operating ON/OFF • Predictive Forward Collision Warning (PFCW)
BUZZER 1 (CCM)	Sounds a buzzer used for following systems by arbitrarily operating ON/OFF Lane Departure Warning (LDW) Blind Spot Warning (BSW) Blind Spot Intervention
BUZZER 2 (CCM)	Sounds a buzzer used for following systems by arbitrarily operating ON/OFF Intelligent Cruise Control (ICC) Predictive Forward Collision Warning (PFCW) Distance Control Assist (DCA)
BUZZER 3 (CCM)	Sounds a buzzer used for following systems by arbitrarily operating ON/OFF • Forward Emergency Braking (FEB)
BUZZER 4 (CCM)	Sounds a buzzer used for following systems by arbitrarily operating ON/OFF • Predictive Forward Collision Warning (PFCW)

BUZZER 1 (ADAS)

Active test item	Operation	Description
BUZZER 1 (ADAS)	Off	Stops transmitting the warning buzzer signal below to end of the test
BOZZEN I (ADAS)	On	Transmits the warning buzzer signal to the warning buzzer

BUZZER 2 (ADAS)

Active test item	Operation	Description
BUZZER 2 (ADAS)	Off	Stops transmitting the warning buzzer signal below to end of the test
BOZZEN Z (ADAS)	On	Transmits the warning buzzer signal to the warning buzzer

BUZZER 3 (ADAS)

Active test item	Operation	Description
BUZZER 3 (ADAS)	Off	Stops transmitting the warning buzzer signal below to end of the test
BUZZER 3 (ADA3)	On	Transmits the warning buzzer signal to the warning buzzer

BUZZER 4 (ADAS)

Active test item	Operation	Description
BUZZER 4 (ADAS)	Off	Stops transmitting the warning buzzer signal below to end of the test
DOZZEN 4 (ADAO)	On	Transmits the warning buzzer signal to the warning buzzer

BUZZER 1 (CCM)

Active test item	Operation	Description
BUZZER 1 (CCM)	Off	Stops transmitting the warning buzzer signal below to end of the test
BOZZER I (COM)	On	Transmits the warning buzzer signal to the warning buzzer

< SYSTEM DESCRIPTION > [ICC]

BUZZER 2 (CCM)

Active test item	Operation	Description
BUZZER 2 (CCM)	Off	Stops transmitting the warning buzzer signal below to end of the test
DOZZEN Z (COM)	On	Transmits the warning buzzer signal to the warning buzzer

BUZZER 3 (CCM)

Active test item	Operation	Description
BUZZER 3 (CCM)	Off	Stops transmitting the warning buzzer signal below to end of the test
DOZZEN 3 (OOM)	On	Transmits the warning buzzer signal to the warning buzzer

BUZZER 4 (CCM)

Active test item	Operation	Description
BUZZER 4 (CCM)	Off	Stops transmitting the warning buzzer signal below to end of the test
BOZZEN 4 (CCM)	On	Transmits the warning buzzer signal to the warning buzzer

ECU IDENTIFICATION

Displays driver assistance buzzer control module parts number.

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ECU DIAGNOSIS INFORMATION

ADAS CONTROL UNIT

Reference Value

VALUES ON THE DIAGNOSIS TOOL

NOTE:

The following table includes information (items) inapplicable to this vehicle. For information (items) applicable to this vehicle, refer to CONSULT display items.

Monitor item		Condition	Value/Status
MAIN SW	Ignition switch ON	When MAIN switch is pressed	On
	Ignition Switch ON	When MAIN switch is not pressed	Off
CET/COACT CVA/	Ignition quitab ON	When SET/COAST switch is pressed	On
SET/COAST SW	Ignition switch ON	When SET/COAST switch is not pressed	Off
CANOLI CIA	Legities exitely ON	When CANCEL switch is pressed	On
CANCEL SW	Ignition switch ON	When CANCEL switch is not pressed	Off
DECLIME (A CC C)A/	Legities exitely ON	When RESUME/ACCELERATE switch is pressed	On
RESUME/ACC SW	Ignition switch ON	When RESUME/ACCELERATE switch is not pressed	Off
DICTANCE CW	Legities exitely ON	When DISTANCE switch is pressed	On
DISTANCE SW	Ignition switch ON	When DISTANCE switch is not pressed	Off
	Drive the vehicle and activate	When ICC system is controlling	On
CRUISE OPE	the vehicle-to-vehicle distance control mode	When ICC system is not controlling	Off
		When brake or clutch pedal is depressed	Off
BRAKE SW	Ignition switch ON	When brake or clutch pedal is not depressed	On
		When brake pedal is depressed	On
STOP LAMP SW	Ignition switch ON	When brake pedal is not depressed	Off
		Idling	On
IDLE SW	Engine running	Except idling (depress accelerator pedal)	Off
SET DISTANCE	Start the engine and turn the	When set to "long"	Long
	ICC system ON • Press the DISTANCE switch to change the vehicle-to-vehicle distance setting	When set to "middle"	Mid
		When set to "short"	Short
CDI II CE I AMD	Start the engine and press	ICC system ON (MAIN switch indicator ON)	On
CRUISE LAMP	MAIN switch	ICC system OFF (MAIN switch indicator OFF)	Off
OWN VHCL	NOTE: The item is indicated, but not m	nonitored	Off
VHCL AHEAD	Drive the vehicle and activate the vehicle-to-vehicle distance	When a vehicle ahead is detected (vehicle ahead detection indicator ON)	On
	control mode	When a vehicle ahead is not detected (vehicle ahead detection indicator OFF)	Off
ICC WARNING	Start the engine and press	When ICC system is malfunctioning (ICC system malfunction ON)	On
ICC WARNING	MAIN switch	When ICC system is normal (ICC system malfunction OFF)	Off

< ECU DIAGNOSIS INFORMATION >

[ICC]

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Monitor item		Condition	Value/Status
VHCL SPEED SE	While driving		Displays the vehicle speed calculated by ADAS control unit
SET VHCL SPD	While driving	When vehicle speed is set	Displays the set vehicle speed
	Engine running	When the buzzer of the following system operates Vehicle-to-vehicle distance control mode DCA system PFCW system FEB system	On
BUZZER O/P		When the buzzer of the following system not operates Vehicle-to-vehicle distance control mode DCA system PFCW system FEB system	Off
THRTL SENSOR	NOTE: The item is indicated, but not n	nonitored	0.0
ENGINE RPM	Engine running	Equivalent to ta- chometer read- ing	
-		Wiper not operating	Off
WIPER SW	Ignition switch ON	Wiper LO operation	Low
		Wiper HI operation	High
YAW RATE	NOTE: The item is indicated, but not n	0.0	
DA WADNING	Engine running	FEB OFF indicator lamp ON • When FEB system is malfunctioning • When FEB system is turned to OFF	On
BA WARNING		FEB OFF indicator lamp OFF • When FEB system is normal • When FEB system is turned to ON	Off
	Drive the vehicle and activate	When ICC brake hold relay is activated	On
STP LMP DRIVE	the vehicle-to-vehicle distance control mode	When ICC brake hold relay is not activated	Off
D RANGE SW	Casina wasina	When the selector lever is in "D" position or manual mode	On
D RANGE SW	Engine running	When the selector lever is in any position other than "D" or manual mode	Off
		When the selector lever is in "N", "P" position	On
NP RANGE SW	Engine running	When the selector lever is in any position other than "N", "P"	Off
DIAD CIM	Ignition quitab ON	When the parking brake is applied	On
PKB SW	Ignition switch ON	When the parking brake is released	Off
PWR SUP MONI	Engine running	Power supply voltage value of ADAS control unit	
VHCL SPD AT	While driving	Value of A/T ve- hicle speed sen- sor signal	
THRTL OPENING	Engine running Depress accelerator pedal		Displays the throttle position

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< ECU DIAGNOSIS INFORMATION >

[ICC]

Monitor item		Value/Status	
GEAR	While driving		Displays the gear position
	Leaving and the CNI	When clutch or brake pedal is depressed	On
CLUTCH SW SIG	Ignition switch ON	When clutch or brake pedal is not depressed	Off
ND OW OLO	1 10 10 1	When the shift lever is in neutral position	On
NP SW SIG	Ignition switch ON	When the shift lever is in any position other than neutral	Off
		When ICC system is deactivated	Off
MODE SIG	Start the engine and press MAIN switch	When vehicle-to-vehicle distance control mode is activated	ICC
	W. W. C. W. C.	When conventional (fixed speed) cruise control mode is activated	ASCD
	Drive the vehicle and acti-	SET switch indicator ON	On
SET DISP IND	vate the conventional (fixed speed) cruise control mode • Press SET/COAST switch	SET switch indicator OFF	Off
DISTANCE	Drive the vehicle and activate the vehicle-to-vehicle distance control mode	When a vehicle ahead is detected	Displays the distance from the preceding vehicle
		When a vehicle ahead is not detected	0.0
RELATIVE SPD	Drive the vehicle and activate the vehicle-to-vehicle distance control mode	When a vehicle ahead is detected	Displays the relative speed.
		When a vehicle ahead is not detected	0.0
DYNA ASIST SW	Ignition switch ON	When dynamic driver assistance switch is pressed	On
DINA AGIOT GW		When dynamic driver assistance switch is not pressed	Off
DOA ON IND	Start the engine and press dy- namic driver assistance switch (When DCA setting is ON)	DCA system OFF	Off
DCA ON IND		DCA system ON	On
DCA VIII ALIED	Drive the vehicle and activate	When a vehicle ahead is not detected (vehicle ahead detection indicator OFF)	Off
the DCA system		When a vehicle ahead is detected (vehicle ahead detection indicator ON)	On
IBA SW	NOTE: The item is indicated, but not m	nonitored	Off
FCW SYSTEM ON	Ignition switch ON	When the PFCW system is ON	On
		When the PFCW system is OFF	Off
АРА ТЕМР	Engine running	Display the accelerator pedal actuator integrated motor temperature	
APA PWR	Ignition switch ON		Power supply voltage value of accelerator ped- al actuator
LDW SYSTEM ON	Ignition switch ON	When the LDW system is ON	On
	Ignition Switch Orv	When the LDW system is OFF	Off
LDW ON LAMP	Ignition switch ON	When the LDW system is ON	On
LDVV OIN LAIVII	ignition switch Oiv	When the LDW system is OFF	Off

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Monitor item		Condition	Value/Status
	Start the engine and press dy-	LDP ON indicator lamp ON	On
LDP ON IND	namic driver assistance switch (When LDP system setting is ON)	LDP ON indicator lamp OFF	Off
LANE DESTANT	Drive the vehicle and activate	Lane departure warning lamp ON	On
LANE DPRT W/L	the LDW system or LDP system	Lane departure warning lamp OFF	Off
LDW BUZER OUT-	Drive the vehicle and activate the LDW/LDP system or Blind	When the buzzer of the following system operates • LDW/LDP system • Blind Spot Warning/Blind Spot Intervention system	On
PUT	Spot Warning/Blind Spot Intervention system	When the buzzer of the following system does not operate LDW/LDP system Blind Spot Warning/Blind Spot Intervention system	Off
	Start the engine and press dy-	When the LDP system is ON	On
LDP SYSTEM ON	namic driver assistance switch (When LDP system setting is ON)	When the LDP system is OFF	Off
	Start the engine and press dy-	When the LDP system is ON	On
READY signal namic driver assistance switt (When LDP system setting i ON)		When the LDP system is OFF	Off
Camera lost	Drive the vehicle and activate	Both side lane markers are detected	Detect
	the LDW system, LDP system or Blind Spot Intervention sys-	Deviate side lane marker is lost	Deviate
	tem	Both side lane markers are lost	Both
Shift position	Engine running While driving		Displays the shift position
	Turn signal lamps OFF	Off	
Turn signal	Turn signal lamp LH blinking	LH	
Turri Signai	Turn signal lamp RH blinking	RH	
	Turn signal lamp LH and RH bl	inking	LH&RH
SIDE G	While driving	Vehicle turning right	Negative value
SIDE S	write driving	Vehicle turning left	Positive value
WARN REQ	Drive the vehicle and activate	Lane departure warning is operating	On
WARRES	the LDP system	Lane departure warning is not operating	Off
		When the LDP system is ON	Stnby
STATUS signal	Drive the vehicle and activate	When the LDP system is operating	Warn
O I / (1 O O olgila)	the LDP system	When the LDP system is canceled	Cancl
		When the LDP system is OFF	Off
Lane unclear	While driving	Lane marker is unclear	On
Lario arroroar	vviiiio diiviiig	Lane marker is clear	Off
FUNC ITEM	Ignition switch ON		FUNC3
FUNC ITEM (NV-ICC)	NOTE: The item is indicated, but not n	Off	
FUNC ITEM (NV- DCA)	NOTE: The item is indicated, but not monitored		Off
DCA SELECT	Ignition switch ON	"Distance Control Assist" set with the integral switch is ON	On
DCA SELECT	ignition switch ON	"Distance Control Assist" set with the integral switch is OFF	Off

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[ICC]

Monitor item		Condition	Value/Status
I DD CELECT	Ignition quital ON	"Lane Departure Intervention" set with the integral switch is ON	On
LDP SELECT	Ignition switch ON	"Lane Departure Intervention" set with the integral switch is OFF	Off
	Ignition switch ON	"Blind Spot Intervention" set with the integral switch is ON	On
BSI SELECT	ignition switch ON	"Blind Spot Intervention" set with the integral switch is OFF	Off
FCW SELECT	Ignition switch ON	"Forward Emergency Braking" set with the integral switch is ON	On
FOW SELECT	ignition switch ON	"Forward Emergency Braking" set with the integral switch is OFF	Off
LDW SELECT	Ignition switch ON	"Lane Departure Warning" set with the integral switch is ON	On
LDW SELECT	ignition switch ON	"Lane Departure Warning" set with the integral switch is OFF	Off
BSW SELECT	Ignition switch ON	"Blind Spot Warning" set with the integral switch is ON	On
DOW SELECT	Igillion Switch ON	"Blind Spot Warning" set with the integral switch is OFF	Off
NAVI ICC SELECT	NOTE: The item is indicated, but not monitored		
NAVI DCA SELECT	NOTE: The item is indicated, but not monitored		
SYS SELECTABILITY	Ignition switch ON	Items set with the integral switch can be switched normally	On
		Items set with the integral switch cannot be switched normally	Off
	Ignition switch ON	When drive mode select switch position is STANDARD	STD
		When drive mode select switch position is in SPORT	SPORT
		When drive mode select switch position is in ECO	ECO
DRIVE MODE STATS		When drive mode select switch position is in SNOW	SNOW
		When drive mode select switch position is in PERSON-AL	STD
		A signal other than those above is input	ERROR
WARN SYS SW	NOTE: The item is indicated, but not m	nonitored	Off
BSW/BSI WARN LMP	Ignition switch ON	When the BSW system is malfunctioning	On
BOW/BOI W/II(IV EI/III	Ignition switch Oil	When the BSW system is normal	Off
BSI ON IND	Ignition switch ON	Blind Spot Intervention warning ON	On
	Igiliani Switch Oiv	Blind Spot Intervention warning OFF	Off
BSW SYSTEM ON	Ignition switch ON	When the BSW system is ON	On
20 0.012101014	.g. maon omiton on	When the BSW system is OFF	Off
	Start the engine and press dy-	When the Blind Spot Intervention system is ON	On
BSI SYSTEM ON	namic driver assistance switch (When Blind Spot Intervention system setting is ON)	When the Blind Spot Intervention system is OFF	Off
DOLOVOTELLON	F	When the BCI system is ON	On
BCI SYSTEM ON	Engine running	When the BCI system is OFF	Off
BCI SWITCH	NOTE: The item is indicated, but not m	nonitored	Off

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Monitor item	Condition		
BATTERY CIRCUIT OFF	NOTE: The item is indicated, but n	ot used	Off
LDP WARNING INDI-	Engine rupping	When the LDP system is malfunctioning	On
CATOR	Engine running	When the LDP system is normal	Off
DW ON INDICATOR	Innitian quitab ON	LDW system display ON	On
_DW ON INDICATOR	Ignition switch ON	LDW system display OFF	Off
LDW WARNING INDI-	Innitian quitab ON	When the LDW system is malfunctioning	On
CATOR	Ignition switch ON	When the LDW system is normal	Off
SYSTEM CANCEL	Legition societals ON	System cancel display ON	On
MESSAGE	Ignition switch ON	System cancel display OFF	Off
		Lane camera unit high temperature warning display ON	On
CAMERA HI TEMP MSG	Ignition switch ON	Lane camera unit high temperature warning display OFF	Off
ITS SETTING ITEM(DCA)	Ignition switch ON		On
ITS SETTING ITEM(LDP)	Ignition switch ON		On
ITS SETTING ITEM(BSI)	Ignition switch ON		On
BSI WARNING INDI- CATOR	Engine running	When the Blind Spot Intervention is malfunctioning	On
		When the Blind Spot Intervention is normal	Off
BSW ON INDICATOR	Ignition switch ON	BSW system display ON	On
		BSW system display OFF	Off
SIDE RADAR BLOCK	Ignition switch ON	Front bumper or side radar is dirty	On
COND		Front bumper and side radar is clean	Off
	Ignition switch ON	LDW system OFF	Nothing
LDW WARNING ALERT TIMING		Lane departure warning timing is early setting	Early
ALLINI TIMINO		Lane departure warning timing is late setting	Late
	Ignition switch ON	BSW system OFF	Nothing
		Blind Spot Warning/Blind Spot Intervention indicator brightness bright	Bright
BSW IND BRIGHT- NESS		Blind Spot Warning/Blind Spot Intervention indicator brightness normal	Normal
		Blind Spot Warning/Blind Spot Intervention indicator brightness dark	Dark
FUNC ITEM (FEB)	Engine rupping	"Forward Emergency Braking" set with the integral switch is ON	On
TONOTILINI (FED)	Engine running	"Forward Emergency Braking" set with the integral switch is OFF	Off
FEB SELECT	Ignition switch ON	"Forward Emergency Braking" set with the integral switch is ON	
I LD SELECT	ignition Switch ON	"Forward Emergency Braking" set with the integral switch is OFF	Off
EED SW	Engine russiss	FEB system ON	On
FEB SW	Engine running	FEB system OFF	Off
CL MAIN CVA	Engine russing	When speed limiter MAIN switch is pressed	On
SL MAIN SW	Engine running	When speed limiter MAIN switch is not pressed	Off

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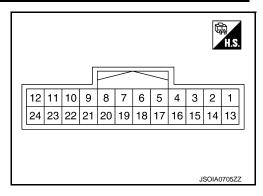
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< ECU DIAGNOSIS INFORMATION >

Monitor item		Condition	Value/Status
SL TARGET VEHI- CLE SPEED	While driving	When vehicle speed is set	Displays the set vehicle speed
	Drive the vehicle and acti-	Speed limiter SET indicator ON	On
SL SET LAMP	vate the speed limiterPress speed limiter MAIN switch	Speed limiter SET indicator OFF	Off
SL LIMIT LAMP	Drive the vehicle and acti-	Speed limiter system ON	On
	vate the speed limiterPress speed limiter MAIN switch	Speed limiter system OFF	Off
ASCD CANCEL	Drive the vehicle and activate	ASCD cancelled by low vehicle speed	On
(LOW SPEED)	the ASCD	Other than above	Off
ASCD CANCEL	Drive the vehicle and activate	ASCD cancelled by difference between set speed and vehicle speed	On
(SPEED DIFF)	the ASCD	Other than above	Off
KICK DOWN	Drive the vehicle and activate	When accelerator pedal is full depressed	On
KICK DOWN	the speed limiter	Other than above	Off

TERMINAL LAYOUT PHYSICAL VALUES



	nal No. color)	Description		Condition		Standard value	Reference value
+	_	Signal name	Input/ Output			Standard value	Neierence value
1 (L)		CAN -H		_		_	_
2 (R)		CAN -L	_		_	_	_
5 (B)		Ground	_	Ignition switch ON		0 - 0.1 V	Approx. 0 V
6 (L)		ITS communication-H	_	_		_	_
7 (P)	Ground	ITS communication-L	_	_		_	_
8 (L)	Giodila	Chassis communication-H	_			_	_
9 (V)		Chassis communication-L	_	_		_	_
12 (GR)		Ignition power supply	Input	Ignition switch ON	_	10 - 16 V	Battery voltage
17		ICC brake hold relay		Ignition switch ON	_	10 - 16 V	Approx. 12 V
(V)		drive signal	Output		At "STOP LAMP" test of "Active test"	0 - 0.1 V	Approx. 0 V

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Fail-safe (ADAS Control Unit)

INFOID:0000000009676508

If a malfunction occurs in each system, ADAS control unit cancels each control, sounds a beep, and turns ON the warning or indicator lamp.

System	Buzzer	Warning lamp/Warning dis- play	Description
Vehicle-to-vehicle distance control mode	High- pitched tone	ICC system warning	Cancel
Conventional (fixed speed) cruise control mode	High- pitched tone	ICC system warning	Cancel
Forward Emergency Braking (FEB)	High- pitched tone	FEB warning lamp Warning systems indicator (Forward position: Yellow)	Cancel
Predictive Forward Collision Warning (PFCW)	High- pitched tone	Warning systems indicator (Forward position: Yellow)	Cancel
Distance Control Assist (DCA)	High- pitched tone	Warning systems indicator (Forward position: Yellow)	Cancel
Blind Spot Warning (BSW)	_	Warning systems indicator (Blind spot position: Yellow)	Cancel
Back-up Collision Intervention (BCI)	High- pitched tone	BCI system warning	Cancel

DTC Inspection Priority Chart

INFOID:0000000009676509

If multiple DTCs are detected simultaneously, check them one by one depending on the following DTC inspection priority chart.

Priority	Detected items (DTC)		
1	U1507: LOST COMM (SIDE RDR R) U1508: LOST COMM (SIDE RDR L)		
2	1CA0A: CONFIG UNFINISHED U1000: CAN COMM CIRCUIT U1010: CONTROL UNIT (CAN)		
3	 C1F02: APA C/U MALF C1B53: SIDE RDR R MALF C1B54: SIDE RDR L MALF C1B84: DIST SEN MALFUNCTION 		

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Priority	Detected	items (DTC)
4	C1A01: POWER SUPPLY CIR C1A02: POWER SUPPLY CIR 2 C1A04: ABS/TCS/VDC CIRC C1A05: BRAKE SW/STOP L SW C1A06: OPERATION SW CIRC C1A13: STOP LAMP RLY FIX C1A14: ECM CIRCUIT C1A24: NP RANGE C1A26: ECD MODE MALF C1A27: ECD PWR SUPLY CIR C1A33: CAN TRANSMISSION ERR C1A34: COMMAND ERROR C1A36: APA CIR C1A36: APA CAN COMM CIR C1A37: APA CAN CIR 2 C1A38: APA CAN CIR 1 C1A39: STRG SEN CIR C1A39: STRG SEN CIR C1B5D: FEB OPE COUNT LIMIT C1B56: SONAR CIRCUIT C1B57: AVM CIRCUIT C1B59: CCM CIRCUIT C1B82: DIST SEN OFF-CENTER C1B86: DIST SEN ABNORMAL TEMP C1B86: DIST SEN PWR SUP CIR C1F01: APA MOTOR MALF C1F05: APA PWR SUPLY CIR	 U0121: VDC CAN CIR 2 U0126: STRG SEN CAN CIR 1 U0235: ICC SENSOR CAN CIRC 1 U0401: ECM CAN CIR 1 U0402: TCM CAN CIR 1 U0415: VDC CAN CIR 1 U0424: HVAC CAN CIR 1 U0428: STRG SEN CAN CIR 2 U1502: ICC SEN CAN COMM CIR U1503: SIDE RDR L CAN CIR 2 U1504: SIDE RDR L CAN CIR 1 U1505: SIDE RDR R CAN CIR 1 U1506: SIDE RDR R CAN CIR 1 U1508: ECM CAN CIRC 3 U1500: VDC CAN CIRC 3 U150D: TCM CAN CIRC 3 U150E: BCM CAN CIRC 3 U150F: AV CAN CIRC 3 U1512: HVAC CAN CIRC 3 U1513: METER CAN CIRC 3 U1514: STRG SEN CAN CIRC 3 U1515: ICC SENSOR CAN CIRC 3 U1517: APA CAN CIRC 3 U1518: SIDE RDR R CAN CIRC 3 U1519: SIDE RDR CAN CIRC 3 U1519: SIDE RDR CAN CIRC 3 U1522: SONAR CAN COMMUNICATION 3 U1523: SONAR CAN COMMUNICATION 3 U1524: AVM CAN COMMUNICATION 1 U1525: AVM CAN COMMUNICATION 3 U1527: CCM CAN CIR 1 U1537: CCM CAN CIR 2 U1530: DR ASSIST BUZZER CAN CIR 1 U1541: DAST 3 CAN CIR 2
5	C1A03: VHCL SPEED SE CIRC	
6	C1A15: GEAR POSITION	
7	C1A00: CONTROL UNIT	

DTC Index

NOTE

- The details of time display are as per the following.
- CRNT: A malfunction is detected now
- PAST: A malfunction was detected in the past
- IGN counter is displayed on FFD (Freeze Frame Data).
- 0: The malfunctions that are detected now CAN communication system (U1000, U1010)
- 1 39: It increases like 0 → 1 → 2 ··· 38 → 39 after returning to the normal condition whenever the ignition switch OFF → ON. It returns to 0 when a malfunction is detected again in the process.
- If it is over 39, it is fixed to 39 until the self-diagnosis results are erased. Other than CAN communication system (Other than U1000, U1010)
- 1 49: It increases like 0 → 1 → 2 ··· 38 → 49 after returning to the normal condition whenever the ignition switch OFF → ON. It returns to 0 when a malfunction is detected again in the process.
- If it is over 49, it is fixed to 49 until the self-diagnosis results are erased.

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Systems for fail-safe

- A: Vehicle-to-vehicle distance control mode
- B: Conventional (fixed speed) cruise control mode
- C: Distance Control Assist (DCA)
- D: Forward Emergency Braking (FEB)
- E: Predictive Forward Collision Warning (PFCW)
- F: Blind Spot Warning (BSW)
- G: Back-up Collision Intervention (BCI)

DTC			Fail-safe		
CONSULT	On board display	CONSULT display	System	Reference	
NO DTC IS DE- TECTED. FUR- THER TESTING MAY BE RE- QUIRED	55	NO DTC IS DETECTED. FURTHER TESTING MAY BE REQUIRED	_	_	
C1A0A	41	CONFIG UNFINISHED	A, B, C, D, E, F, G	DAS-69	
C1A00	0	CONTROL UNIT	A, B, C, D, E, F, G	DAS-70	
C1A01	1	POWER SUPPLY CIR	A, B, C, D, E, F, G	DAS-71	
C1A02	2	POWER SUPPLY CIR 2	A, B, C, D, E, F, G	DAS-71	
C1A03	3	VHCL SPEED SE CIRC	A, B, C, D, E, F, G	DAS-72	
C1A04	4	ABS/TCS/VDC CIRC	A, B, C, D, E, F, G	DAS-74	
C1A05	5	BRAKE SW/STOP L SW	A, B, C, D, G	<u>DAS-75</u>	
C1A06	6	OPERATION SW CIRC	A, B, C, D, E	DAS-80	
C1A13	13	STOP LAMP RLY FIX	A, B, C, D, E, G	<u>DAS-83</u>	
C1A14	14	ECM CIRCUIT	A, B, C, D, E	DAS-89	
C1A15	15	GEAR POSITION	A, B, C, D, E	DAS-91	
C1A24	24	NP RANGE	A, B, C, D, E, F, G	DAS-93	
C1A26	26	ECD MODE MALF	A, B, C, D, G	DAS-95	
C1A27	27	ECD PWR SUPLY CIR	A, B, C, D, G	DAS-97	
C1A33	33	CAN TRANSMISSION ERR	A, B, C, D, E	DAS-99	
C1A34	34	COMMAND ERROR	A, B, C, D, E	DAS-100	
C1A35	35	APA CIR	A, C, D, E	DAS-101	
C1A36	36	APA CAN COMM CIR	A, C, D, E	DAS-102	
C1A37	133	APA CAN CIR 2	A, C, D, E	DAS-103	
C1A38	132	APA CAN CIR 1	A, C, D, E	DAS-104	
C1A39	39	STRG SEN CIR	A, B, C, D, E, F, G	DAS-105	
C1B5D	198	FEB OPE COUNT LIMIT	C, D, E	DAS-106	
C1B53	84	SIDE RDR R MALF	F, G	DAS-107	
C1B54	85	SIDE RDR L MALF	F, G	DAS-108	
C1B56	86	SONAR CIRCUIT	G	DAS-109	
C1B57	87	AVM CIRCUIT	G	DAS-110	
C1B59	184	CCM CIRCUIT	A, B, C, F, G	DAS-111	
C1B82	12	DIST SEN OFF-CENTER	A, C, D, E	DAS-112	
C1B84	17	DIST SEN MALFUNCTION	A, C, D, E	DAS-113	
C1B85	21	DIST SEN ABNORMAL TEMP	A, C, D, E	DAS-114	
C1B86	80	DIST SEN PWR SUP CIR	A, C, D, E	DAS-115	
C1F01	91	APA MOTOR MALF	A, C, D, E	DAS-117	
C1F02	92	APA C/U MALF	A, C, D, E	DAS-118	

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Systems for fail-safe

- A: Vehicle-to-vehicle distance control mode
- B: Conventional (fixed speed) cruise control mode
- C: Distance Control Assist (DCA)
- D: Forward Emergency Braking (FEB)
- E: Predictive Forward Collision Warning (PFCW)
- F: Blind Spot Warning (BSW)
- G: Back-up Collision Intervention (BCI)

DTC			Fail-safe	
CONSULT	On board display	CONSULT display	System	Reference
C1F05	95	APA PWR SUPLY CIR	A, C, D, E	DAS-119
U0121	127	VDC CAN CIR 2	A, B, C, D, E, F, G	DAS-120
U0126	130	STRG SEN CAN CIR 1	A, B, C, D, E, F, G	DAS-121
U0235	144	ICC SENSOR CAN CIRC 1	A, C, D, E	DAS-122
U0401	120	ECM CAN CIR 1	A, B, C, D, E, F, G	DAS-123
U0402	122	TCM CAN CIR 1	A, B, C, D, E, F, G	DAS-124
U0415	126	VDC CAN CIR 1	A, B, C, D, E, F, G	DAS-125
U0424	156	HVAC CAN CIR 1		DAS-126
U0428	131	STRG SEN CAN CIR 2	A, B, C, D, E, F, G	DAS-127
U1000 ^{NOTE}	100	CAN COMM CIRCUIT	A, B, C, D, E, F, G	DAS-128
U1010	110	CONTROL UNIT (CAN)	A, B, C, D, E, F, G	DAS-130
U150B	157	ECM CAN CIRC 3	A, B, C, D, E, F, G	DAS-131
U150C	158	VDC CAN CIRC 3	A, B, C, D, E, F, G	DAS-132
U150D	159	TCM CAN CIRC 3	A, B, C, D, E, F, G	DAS-133
U150E	160	BCM CAN CIRC 3	A, B, C, D, F, G	DAS-134
U150F	161	AV CAN CIRC 3		DAS-135
U1502	147	ICC SEN CAN COMM CIR	A, C, D, E	DAS-136
U1503	150	SIDE RDR L CAN CIR 2	F, G	DAS-137
U1504	151	SIDE RDR L CAN CIR 1	F, G	DAS-138
U1505	152	SIDE RDR R CAN CIR 2	F, G	DAS-139
U1506	153	SIDE RDR R CAN CIR 1	F, G	DAS-140
U1507	154	LOST COMM (SIDE RDR R)	F, G	DAS-141
U1508	155	LOST COMM (SIDE RDR L)	F, G	DAS-142
U1512	162	HVAC CAN CIRC3		DAS-143
U1513	163	METER CAN CIRC 3	A, B, C, D, E, F, G	DAS-144
U1514	164	STRG SEN CAN CIRC 3	A, B, C, D, E, F, G	DAS-145
U1515	165	ICC SENSOR CAN CIRC 3	A, C, D, E	DAS-146
U1517	167	APA CAN CIRC 3	A, C, D, E	DAS-147
U1518	168	SIDE RDR L CAN CIRC 3	F, G	DAS-148
U1519	169	SIDE RDR R CAN CIRC 3	F, G	DAS-149
U1521	177	SONAR CAN COMMUNICATION 2	G	DAS-150
U1522	178	SONAR CAN COMMUNICATION 1	G	DAS-151
U1523	179	SONAR CAN COMMUNICATION 3	G	DAS-152
U1524	180	AVM CAN COMMUNICATION 1	G	DAS-153
U1525	181	AVM CAN COMMUNICATION 3	G	DAS-154
U1527	185	CCM CAN CIR1	A, B, C, F, G	DAS-155
U153F	186	CCM CAN CIR2	A, B, C, F, G	DAS-156

< ECU DIAGNOSIS INFORMATION >

[ICC]

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Systems for fail-safe

- A: Vehicle-to-vehicle distance control mode
- B: Conventional (fixed speed) cruise control mode
- C: Distance Control Assist (DCA)
- D: Forward Emergency Braking (FEB)
- E: Predictive Forward Collision Warning (PFCW)
- F: Blind Spot Warning (BSW)
- G: Back-up Collision Intervention (BCI)

DTC			Fail-safe	
CONSULT	On board display	CONSULT display	System	Reference
U1530	183	DR ASSIST BUZZER CAN CIR1		DAS-157
U1540	200	DAST CAN CIR 1	C, D, E	DAS-158
U1541	201	DAST CAN CIR 2	C, D, E	DAS-159

NOTE:

With the detection of "U1000" some systems do not perform the fail-safe operation.

A system controlling based on a signal received from the control unit performs fail-safe operation when the communication with the ADAS control unit becomes inoperable.

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ICC SENSOR

Reference Value

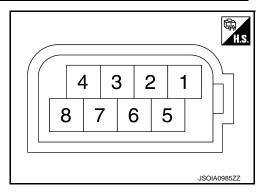
VALUES ON THE DIAGNOSIS TOOL

NOTE

The following table includes information (items) inapplicable to this vehicle. For information (items) applicable to this vehicle, refer to CONSULT display items.

Monitor item		Condition	Value/Status
VHCL SPEED SE	While driving		Value of vehicle speed signal (wheel speed)
		Vehicle stopped	0.0
YAW RATE	While driving	Vehicle turning right	Positive value
		Vehicle turning left	Negative value
PWR SUP MONI Ignition switch ON			Power supply voltage value of ICC sensor
DISTANCE	Drive the vehicle and activate the vehicle-to-vehicle distance control mode	When a vehicle ahead is detected	Displays the distance from the preceding vehicle
		When a vehicle ahead is not detected	0.0
RELATIVE SPD	Drive the vehicle and activate the vehicle-to-vehicle distance	When a vehicle ahead is detected	Displays the relative speed
	control mode	When a vehicle ahead is not detected	0.0
RADAR OFFSET	NOTE: The item is indicated, but not u	_	
RADAR HEIGHT	NOTE: The item is indicated, but not u	sed	_
077570110 41101 5		When setting the steering wheel in straight-ahead position	0.0
STEERING ANGLE	Ignition switch ON	When turning the steering wheel 90° rightward	+90
		When turning the steering wheel 90° leftward	-90
STRG ANGLE SPEED	Ignition switch ON At the time of turning the steering wheel		Steering wheel turning speed is displayed
L/R ADJUST	Ignition switch ON	At the completion of radar alignment adjustment	Horizontal cor- rection value is displayed
U/D ADJUST	Ignition switch ON	At the completion of radar alignment adjustment	Vertical correction value is displayed

TERMINAL LAYOUT



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PHYSICAL VALUES

	inal No. e color)	Description		Condition	Standard value	Reference value	Е
+	_	Signal name	Input/ Output	Condition	Staridard Value	Reference value	L
1 (R)		Ignition power supply	Input	Ignition switch ON	10 - 16 V	Battery voltage	(
3 (L)	Ground	ITS communication-H	_	_	_	_	
6 (Y)	Ground	ITS communication-L	_	_	_	_	L
8 (B)		Ground	_	Ignition switch ON	0 - 0.1 V	Approx. 0 V	Е

Fail-safe (ICC Sensor)

INFOID:0000000009644226

If a malfunction occurs in the ICC sensor, ADAS control unit cancels control, sounds a beep, and turns ON the ICC system warning in the information display.

DTC Inspection Priority Chart

INFOID:0000000009644227

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If multiple DTCs are detected simultaneously, check them one by one depending on the following DTC inspection priority chart.

Priority	Detected items (DTC)
1	U1000: CAN COMM CIRCUIT U1010: CONTROL UNIT (CAN)
2	C1A50: ADAS MALFUNCTION
3	 C1A01: POWER SUPPLY CIR C1A02: POWER SUPPLY CIR 2 C1A12: RADAR OFF-CENTER C1A16: RADAR BLOCKED C1A21: UNIT HIGH TEMP C1A23: UNIT LOW TEMP C1A39: STRG SEN CIR U0104: ADAS CAN CIR1 U0121: VDC CAN CIR2 U0126: STRG SEN CAN CIR1 U0405: ADAS CAN CIR2 U0415: VDC CAN CIR2 U0415: VDC CAN CIR1 U0428: STRG SEN CAN CIR2
4	C1A00: CONTROL UNIT

DTC Index

NOTE

- The details of time display are as per the following.
- 0: The malfunctions that are detected now CAN communication system (U1000, U1010)
- 1 39: It increases like 0 → 1 → 2 ··· 38 → 39 after returning to the normal condition whenever the ignition switch OFF → ON. It returns to 0 when a malfunction is detected again in the process.
- If it is over 39, it is fixed to 39 until the self-diagnosis results are erased.
 Other than CAN communication system (Other than U1000, U1010)
- 1 49: It increases like 0 → 1 → 2 ··· 38 → 49 after returning to the normal condition whenever the ignition switch OFF → ON. It returns to 0 when a malfunction is detected again in the process.
- If it is over 49, it is fixed to 49 until the self-diagnosis results are erased.

×: Applicable

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DTC			Fail	-safe		
CONSULT	CONSULT display	Vehicle-to-vehicle distance control mode	Conventional (fixed speed) cruise control mode	Distance Control Assist (DCA)	Forward Emergency Braking (FEB) /Predictive Forward Collision Warning (PFCW)	Reference
C1A00	CONTROL UNIT	×	×	×	×	CCS-101
C1A01	POWER SUPPLY CIR	×	×	×	×	CCS-102
C1A02	POWER SUPPLY CIR2	×	×	×	×	CCS-102
C1A12	RADAR OFF-CENTER	×		×	×	CCS-103
C1A16	RADAR BLOCKED	×		×	×	CCS-104
C1A21	UNIT HIGH TEMP	×	×	×	×	CCS-106
C1A23	UNIT LOW TEMP	×	×	×	×	CCS-107
C1A39	STRG SEN CIR	×	×	×	×	<u>CCS-108</u>
C1A50	ADAS MALFUNCTION		×	×	×	CCS-109
U0104	ADAS CAN CIR1	×	×	×	×	CCS-110
U0121	VDC CAN CIR2		×	×	×	CCS-111
U0126	STRG SEN CAN CIR1		×	×	×	CCS-112
U0405	ADAS CAN CIR2	×	×	×	×	CCS-113
U0415	VDC CAN CIR1	×	×	×	×	CCS-114
U0428	STRG SEN CAN CIR2	×	×	×	×	CCS-115
U1000	CAN COMM CIRCUIT	×	×	×	×	CCS-116
U1010	CONTROL UNIT (CAN)	×	×	×	×	CCS-117

< ECU DIAGNOSIS INFORMATION >

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DRIVER ASSISTANCE BUZZER CONTROL MODULE

Reference Value

VALUES ON THE DIAGNOSIS TOOL

NOTE:

The following table includes information (items) inapplicable to this vehicle. For information (items) applicable to this vehicle, refer to CONSULT display items.

Monitor item		Condition	Value/Status
		Except for the LDW/LDP/Blind Spot Warning/Blind Spot Intervention warning condition	Off
	Drive the vehicle and	When the LDW warning condition	TYPE 1
Buzzer 1 request (ADAS)	operate each system	When the BSW warning condition	TYPE 2
		When the Blind Spot Intervention warning condition	TYPE 3
		When the warning condition cancel	Cancel
Buzzer 1 volume (ADAS)	Ignition switch ON	When the buzzer sound	It changes according to the sound volume of buzzer
		When the buzzer cancel immediate	IMEDIAT
Buzzer 1 stop (ADAS)	Ignition switch ON	When the buzzer cancel other than above	CYCLE
		Except for the ICC/PFCW/DCA warning condition	Off
	Drive the vehicle and operate each system	When the approach warning condition	TYPE 1
Buzzer 2 request (ADAS)		When the PFCW warning condition	TYPE 2
		When the DCA condition	TYPE 3
		When the warning condition cancel	Cancel
Buzzer 2 volume (ADAS)	Ignition switch ON	When the buzzer sound	It changes according to the sound volume of buzzer
		When the buzzer cancel immediate	IMEDIAT
Buzzer 2 stop (ADAS)	Ignition switch ON	When the buzzer cancel other than above	CYCLE
		Except for the FEB warning condition	Off
Buzzer 3 request (ADAS)	Drive the vehicle and operate each system	When the FEB warning condition	TYPE 1
		When the warning condition cancel	Cancel
Buzzer 3 volume (ADAS)	Ignition switch ON	When the buzzer sound	It changes according to the sound volume of buzzer
		When the buzzer cancel immediate	IMEDIAT
Buzzer 3 stop (ADAS)	Ignition switch ON	When the buzzer cancel other than above	CYCLE
	5	Except for the PFCW warning condition	Off
Buzzer 4 request (ADAS)	Drive the vehicle and operate each system	When the PFCW warning condition	TYPE 1
	,	When the warning condition cancel	Cancel
Buzzer 4 volume (ADAS)	Ignition switch ON	When the buzzer sound	It changes according to the sound volume of buzzer
		When the buzzer cancel immediate	IMEDIAT
Buzzer 4 stop (ADAS)	Ignition switch ON	When the buzzer cancel other than above	CYCLE

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< ECU DIAGNOSIS INFORMATION >

[ICC]

Monitor item		Condition	Value/Status
		Except for the LDW/LDP/Blind Spot Warning/Blind Spot Intervention warning condition	Off
	Drive the vehicle and	When the LDW warning condition	TYPE 1
Buzzer 1 request (CCM)	operate each system	When the BSW warning condition	TYPE 2
		When the Blind Spot Intervention warning condition	TYPE 3
		When the warning condition cancel	Cancel
Buzzer 1 volume (CCM)	Ignition switch ON	When the buzzer sound	It changes according to the sound volume of buzzer
		When the buzzer cancel immediate	IMEDIAT
Buzzer 1 stop (CCM)	Ignition switch ON	When the buzzer cancel other than above	CYCLE
		Except for the ICC/PFCW/DCA warning condition	Off
	Drive the vehicle and	When the approach warning condition	TYPE 1
Buzzer 2 request (CCM)	operate each system	When the PFCW warning condition	TYPE 2
		When the DCA condition	TYPE 3
		When the warning condition cancel	Cancel
Buzzer 2 volume (CCM)	Ignition switch ON	When the buzzer sound	It changes according to the sound volume of buzzer
		When the buzzer cancel immediate	IMEDIAT
Buzzer 2 stop (CCM)	Ignition switch ON	When the buzzer cancel other than above	CYCLE
		Except for the FEB warning condition	Off
Buzzer 3 request (CCM)	Drive the vehicle and operate each system	When the FEB warning condition	TYPE 1
	operate each system	When the warning condition cancel	Cancel
Buzzer 3 volume (CCM)	Ignition switch ON	When the buzzer sound	It changes according to the sound volume of buzzer
		When the buzzer cancel immediate	IMEDIAT
Buzzer 3 stop (CCM)	Ignition switch ON	When the buzzer cancel other than above	CYCLE
		Except for the PFCW warning condition	Off
Buzzer 4 request (CCM)	Drive the vehicle and operate each system	When the PFCW warning condition	TYPE 1
	Sporate caon cyclom	When the warning condition cancel	Cancel
Buzzer 4 volume (CCM)	Ignition switch ON	When the buzzer sound	It changes according to the sound volume of buzzer
		When the buzzer cancel immediate	IMEDIAT
Buzzer 4 stop (CCM)	Ignition switch ON	When the buzzer cancel other than above	CYCLE
ADAS MALFUNCTION	Ignition switch ON	When the ADAS control unit malfunction	On
NUMO IVIALFUNG HUN	Ignition switch ON	When the ADAS control unit normal	Off
CCM MALFUNCTION	Ignition switch ON	When the chassis control module mal- function	On
		When the chassis control module normal	Off
DD ASSIST DI 177 MAL F	Ignition quitch ON	When the driver assistance control module malfunction	On
DR ASSIST BUZZ MALF	Ignition switch ON	When the driver assistance control module normal	Off

< ECU DIAGNOSIS INFORMATION >

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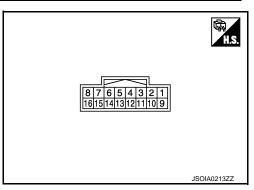
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Monitor item		Value/Status	
		Except for the warning condition	Off
		LDW/LDP//Blind Spot Warning/Blind Spot Intervention system warning in progress	1
		ICC/PFCW/DCA system warning in progress	2
		FEB system warning in progress	3
DR ASSIST BUZZ STATUS	operate each system Spot Interver tem warning	LDW/LDP//Blind Spot Warning/Blind Spot Intervention/ICC/PFCW/DCA sys- tem warning in progress	1, 2
		ICC/PFCW/DCA system warning in progress.	2, 4
		LDW/LDP//Blind Spot Warning/Blind Spot Intervention/PFCW system warning in progress	1, 4
		PFCW system	4

TERMINAL LAYOUT



PHYSICAL VALUES

	inal No. e color)	Description Signal name Input/Output			Condition	Standard value	Reference value
+	_				Condition	Standard value	
1 (G)	5 (B)	Ignition power supply	Input	Ignition switch ON	_	10 - 16 V	Battery voltage
3 (L)	_	ITS communication-H	_	_	_		_
5 (B)	Groun d	Ground	_	Ignition switch ON	_	0 - 0.1 V	Approx. 0 V

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[ICC]

	inal No. e color)	Description			Condition	Standard value	Reference value
+	_	Signal name	Input/Out- put		Condition	Standard value	Reference value
					Driver assistance buzzer OFF	0 - 0.1 V	Approx. 0 V
					At "BUZZER 1" test of "Active test"	(V) 4 0 -4	500μS JSOIA0949ZZ
8 (R)	16 (G)	Warning buzzer signal	Output	Ignition switch ON	At "BUZZER 2" test of "Active test"	(V) 4 0 -4	500μ S JSOIA0950ZZ
					At "BUZZER 3" test of "Active test"	(V) 4 0 -4	500μS JSOIA0951ZZ
11 (Y)	_	ITS communication-L	_	_	_	_	_
13 (B)	Groun d	Ground	_	Ignition switch ON	_	0 - 0.1 V	Approx. 0 V
16 (G)	5 (B)	Warning buzzer signal ground	Output	Ignition switch ON	_	0 - 0.1 V	Approx. 0 V

DTC Inspection Priority Chart

INFOID:0000000009759621

If multiple DTCs are detected simultaneously, check them one by one depending on the following DTC inspection priority chart.

Priority	Detected items (DTC)
1	U1000: CAN COMM CIRCUIT U1010: CONTROL UNIT (CAN)
2	U0104: ADAS CAN CIR2 U1527: CCM CAN CIRCUIT 1
3	C1B20: CONTROL MODULE

DTC Index

NOTE:

- The details of time display are as per the following.
- CRNT: A malfunction is detected now
- PAST: A malfunction was detected in the past
- IGN counter is displayed in FFD (Freeze Frame Data).
- 0: The malfunctions that are detected now

< ECU DIAGNOSIS INFORMATION >

[ICC]

1 - 39: It increases like 0 → 1 → 2 ··· 38 → 39 after returning to the normal condition whenever the ignition switch OFF → ON. It returns to 0 when a malfunction is detected again in the process.

- If it is over 39, it is fixed to 39 until the self-diagnosis results are erased.

×: Applicable

DTC		Reference
C1B20	CONTROL MODULE	DAS-332
U0104	ADAS CAN CIR2	DAS-348
U1527	CCM CAN CIRCUIT 1	DAS-358
U1000	CAN COMM CIRCUIT	DAS-353
U1010	CONTROL UNIT (CAN)	DAS-356

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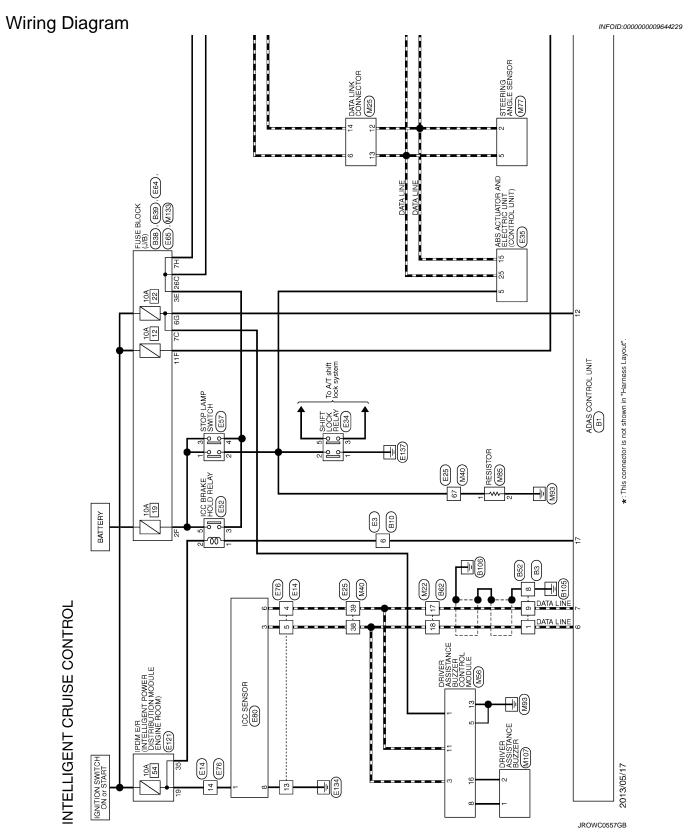
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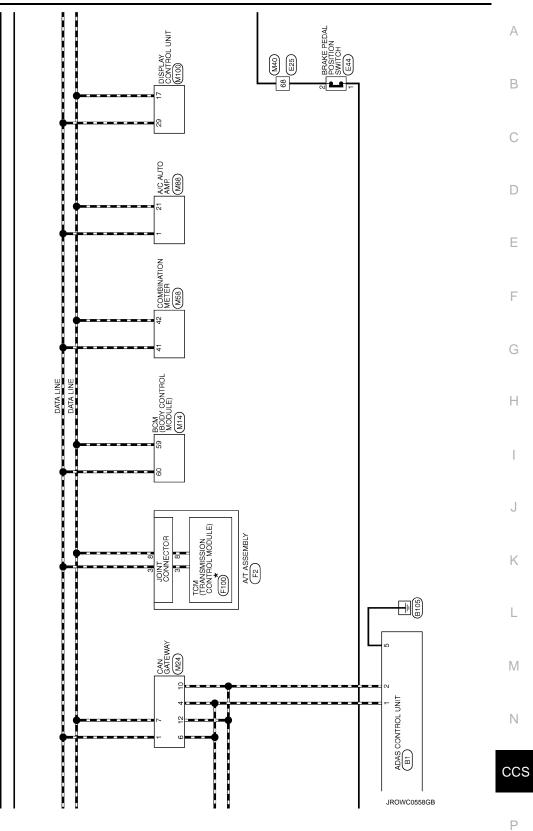
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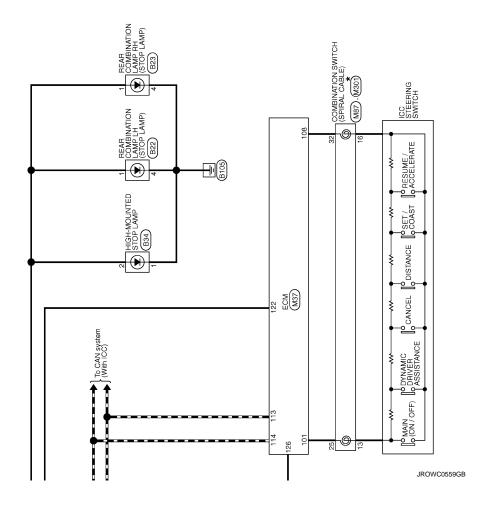
WIRING DIAGRAM

INTELLIGENT CRUISE CONTROL





Revision: 2013 October CCS-71 2014 Q50



INTELLIGENT CRUISE CONTROL			
Connector No. B1	Connector No. B10	Connector No. B23	Connector No. B38
Connector Name ADAS CONTROL UNIT	Connector Name WIRE TO WIRE	Connector Name REAR COMBINATION LAMP RH (BODY SIDE)	Connector Name FUSE BLOCK (J/B)
Connector Type TH24FW-NH	Connector Type TH24FW-NH	Connector Type NS04MW-CS	Connector Type NS10FW-CS
12 0 8 7 8 5 1	19 11 10 0	H.S.	H.S. 34 124 16
17	\exists	4 3 2 1	95 B9
Terminal Color Of Signal Name [Specification] No. Wire	Terminal Color Of Signal Name [Specification] No. Wire	Terminal Golor Of Signal Name [Specification] No.	Terminal Color Of Signal Name [Specification] No. Wire
1 L CAN-H	- ^ 9	1 1.6	1G GR -
2 R CAN-L	- M 6	2 R -	2G W -
5 B GROUND	10 B -	3 V	3G BR -
		4 B -	Н
7 P ITS COMM-L	\dashv		- 5 59
	┥	١	
CH	\dashv	Connector No. B34	-
æ	+	Connector Name HIGH-MOUNTED STOP LAMP	Connector No. B39
17 V BRAKE HOLD RLY DRIVE SIGNAL	T	Т	Connector Name FUSE BLOCK (J/B)
	24 SHIELD =	Connector Type TK02MBR-P	Connector Lyne TH10FR-NH
Connector No. B3			ı
Connector Name WIRE TO WIRE	Connector No. B22		
	Connector Name REAR COMBINATION LAMP LH (BODY SIDE)		
Connector Type NS16FW-CS	- 1	2 1	
	Connector Type NS04MW-CS		44.34
			104 8H 7H 6H
H.S.		Terminal Color Of	
		No. Wire Signal Name [Specification]	le C
16 15 14 9 8	4 3 2 1	- 8	Wire
		2 LG -	- d H01
			- J H
No. Wire Signal Name [Specification]	Terminal Color Of		ł
т	No. Wire Signal Name [Specification]		LG
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8 B -	2 P -		
4	3 SB -		
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+			
16 BR -			

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	13	œ	-	92	>-	1	4	>	-
	14	BG	-	96	W	-	5	7	-
	15	GR	-	97	٦		9	В	-
	16	>	-	66	Н	-	_	BR	-
	17	Ь	-	100	BR	-		P.C	-
7	92	_	-				6	+	-
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	20	GR		Connec	Connector No.	E3	12	+	-
	21	œ		Connec	Connector Name	WIRE TO WIRE	13	60	1
	22	۵	1				4	+	-
Simal Name [Spacification]	23	×	-	Connec	Connector Type	TH24MW-NH	15	GR	
Diagramousodol	24	>	-				16	>	
1	52	SB	-	_			1-	+	1
_	56	g	1	ŧ			92	+	1
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	39	>	-	Terminal	nal Color Of		56	an	1
	45	g	-	No.	Wire	Signal Name [Specification]	27	H	
	46	SHELD	1	9	>	1	28	H	1
	47	ŋ	1	6	٨	1			-
	48	BG	1	92	В	1			
	49	g	1	=	g	1	Com	Connector No.	E25
	25	>	-	12	œ	1	Į	1	
	53	~	-	13	뜡		Solu	Connector Name	WIRE TO WIRE
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	28	а	-	16	>		_	•	
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-	69	Ь		Connec	Connector Type	SAA18MB-RS10-SJZ2	Terminal	inal Color Of	JO
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< WIRING DIAGRAM > [ICC]

	Connector No. E57	Connector Name STOP LAMP SWITCH	Т	Connector Type M04FW-LC			H.S.		1 2			Terminal Color Of Similal Color Of	No. Wire Signal Name Lopecinication	1 G - [With ACSD]	1 L – [With ICC]	2 GR = [With AUSD]		_ ^			Connector No. E64	Connector Name FUSE BLOCK (J/B)	CO MICHOUN	Comhector Type INSUOTWTCS			HS.	HP H9			<u></u>	Wire	+	3E V	╀	1									
	15 P CAN-L [Without Gateway]	æ	> :	> %	19 SB FR LH WHEEL SENSOR SIGNAL	20 -	G VACUUM SEN	α.	SHIELD	g			Connector No. E44	Connector Name BRAKE PEDAL POSITION SWITCH	. 1	Connector Type SUZFL				2 1				No Wire Signal Name [Specification]	t	2 BG -		ſ		Connector Name ICC BRAKE HOLD RELAY	Connector Type MS02FL-M2-LC		~	T.					lal	No. Wire Signal Marite [Specification]	· -	2 G -	> -		
	- T 86	Ħ	100 SHIELD -		Commonder No.	Т	Connector Name SHIFT LOCK RELAY	Connector Type MS02FI -M2-1 C	1		m	H.S.		1 X C		Tarminal Color Of		- B	2 LG -	3 GR -	5 G -		D	Т	Connector Name ABS ACTUATOR AND ELECTRIC UNIT (CONTROL UNIT)	Connector Type SAZ30FB-SJZ4-U			2 15 17 18 19 30	-				Leminal Color Of Signal Name [Specification] No. Wire	1 B GROUND		3 G VALVE BATTERY	4 Y MOTOR BATTERY	5 LG STOP LAMP SW SIGNAL [With ICC]	5 V STOP LAMP SW SIGNAL [With ASCD]	7 GR RR LH WHEEL SENSOR SIGNAL	G RR	9 BR FRHWHEEL SENSOR SIGNAL	$^{+}$	2
INTELLIGENT CRUISE CONTROL	-	-		1					1	1	-		-	-	-			1	-	-	1	1	1			-	1	-			-	-	1		1	1	-		1			1	-		'
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INTELLIGENT CRUISE CONTROL Connector No. E65	14 R	Terminal No.	Color Of Wire	Signal Name [Specification]		Connector No.		F100
	16 V V T	19	υ S	1 1		Connector Name		TCM(TRANSMISSION CONTROL MODULE) SP10FG
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_	23 P	29	_ (2		1 2 3 4 5
	25 \	33	9 88		I			6 7 8 9 10
	Н	34	>					
	+	32	<i>5</i>		T			
Signal Name [Specification]	- B = -	37	88 89		T	No.	Color Of	Signal Name [Specification]
Γ		88	æ	1		-	,	IGNITION POWER SUPPLY
	Connector No. E80	41	GR	-		2	- B/	BATTERY POWER SUPPLY (MEMORY BACK-UP)
	Connector Name ICC SENSOR	43	>	1		6	,	CAN-H
	Т					4 4	,	K-LINE
	7	Connector No.	r	53		9		IGNITION POWER SUPPLY
		2	4	> idwood I/ v		7	,	BACK-UP LAMP RELAY
			o library	COCEMPE		8	-	CAN-L
	3 1 7	Connector Type		RK10FG-DGY		6		STARTER RELAY
	8	-		<		10	-	GROUND
		_						
		E.S.				Connector No.	No. M14	114
Ī	Terminal Color Of Signal Name [Specification]			7 0 0		Connector Name		BCM (BODY CONTROL MODULE)
	t					Connector Type	Т	TH40FB-NH
	3 L ITS COMM-H							
	6 Y ITSCOMM-L	Terminal Color Of	Color Of Wire	Signal Name [Specification]		7		
		-	g	Y Iddi IS BUMER SI IDDI	I	S	II.	7
		. 2	+	BATTERY POWER SUPPLY (MEMORY BACK-UP)	BACK-UP)		8	88 28 28 28 28 28 28 28 28 28 28 28 28 2
	Connector No. E121	8	T	CAN-H			8	17 17 17 17 17 17 18 18 67 18 64 1
	Connector Name IPDM E/R (INTELLIGENT POWER DISTRIBUTION MODULE ENGINE ROOM)	4 0	2 6	K-LINE GROUND				
	Connector Type TH32FW-NH	9	GR	IGNITION POWER SUPPLY		Terminal	Terminal Color Of	Signal Name [Specification]
Signal Name [Specification]		~ 0	BG c	BACK-UP LAMP RELAY	Ī	è.	Wire	
T			اء	CAN-L	T	48	۰	PUSH-BTN IGN SW ILL PWR
T		s 5	£ "	STARTER RELAY	T	25	5 >	COMM INF
	19 22 23 31 33 34	2	,	2	1	55		RAIN SENSOR
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						09	7	CAN-H
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teter No. M24 cter Type	-	16 W FOWER		Connector No. M37	Ozonoczen Nome		Connector Type RH24FGY-RZ8-R-LH-Z			128 124 113108104100	11.S. 127 123 107 103 98	126 122 114 110 106 102 98	125 121 117 113 109 106 101 97			lar O	Wire	> 8	ž	99 W SENSOR FONER SUPPLY (ACCELERATOR PEDAL POSITION SENSOR 1)	9	8 8%	LG EVAP CON	103 L senson power supply (Acceleration Petition Senson 2)	104 R SENSOR CROUND (ACCELERATOR PEDAL POSITION SENSOR 2)	٦	106 P FUEL TANK TEMPERATURE SENSOR	5 >	BB	110 V ENGINE SPEED SIGNAL OUTPUT	112 V GNDA PDPRES/FTPRES	113 P	114 L G	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	EG EVAP CAP	122 SB STOP LAMP SWITCH	9 1	20 00	×	BG BRAKE P	ш і	128 B ECM GROUND		T	Ţ	
K K K K K K K K K K	Γ						/	7 V	5	7 10 10 11 12			Color Of		L CAN-H											П					- 1	12 13 14		4 5 6 7		L						CAN-H				
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	ŀ	+	╁	>	H	Н	Н	Н		\vdash	H	_	H	Н	_	\dashv	+	+	+	+	+	+	H	3	H	Н	+	+	H	Н	Н	+	+	+	+	+	+	+	+	+	+	+	+	+	4	
	INTELLIGENT CRUISE CONTROL	IGN BLYAY (F/B) CONT	DIMMER	A/T SHIFT SELECT PWR SPLY	IGN RLYAY (IPDM E/R) CONT	DR DOOR REG SW	PASS DOOR REG SW	COMBI SW INPUT 5	COMBI SW INPUT 4	COMBI SW INPUT 3	COMBI SW INPUT 2	COMBI SW INPUT 1	TR LID OPNR SW			M22	WIRE TO WIRE	THOO WAS TAKE	I H8UMW-CS18-1 M4	9 9 9	8 0 0	8 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9	0 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	3 x x x x x x x x x x x x x x x x x x x			Signal Name [Specification]					1	-		1								- [with DCM]	- [Without DCM]		
		2 8	+	H	70 B	71 G	72 SB	Н	76 BG	H	78 Y	79 LG	H			Connector No.	Connector Name	,	ctor lype	•		HIS					Terminal Color Of	+	-	œ	SHIELD	g	9 BC	9	Ť	a SHELD	+	¥ ;	+	+	14 LG	+	+	× ×		_

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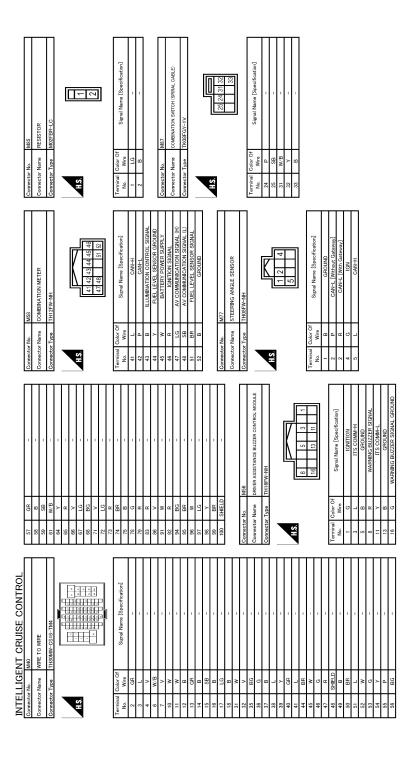
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CCS-77 2014 Q50 Revision: 2013 October



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SC V — — Connector No. MX01 Connector Nume COMBRATON SWITCH (SPIRAL CARLE) Connector Type TYGEFGY #\$5	Terminal Color of No. Wire Signal Name (Specification)
Connector No. M133 Connector Name FUSE BLOCK (J/B) Connector Type TH4679/-404 M35 M35 M35 M35 M35 M35 M35 M3	Terminal Color Of Wire Wire Wire Wire Wire Wire Wire Wire
Corrector No. Connector Name DISPLAY CONTROL UNIT Corrector Type IH24FW-WH (1.5) R R R R R R R R R R R R R R R R R R R	Ferminal Color Of Signal Name Specification 16 Signal Name Specification 16 Signal Name Specification 17 P DIAMER SIGNAL 19 R DIAMER SIGNAL 22 B R DIAMER SIGNAL 22 B R DIAMER SIGNAL 23 Signal Name Specification 24 DIAMER SIGNAL 24 DIAMER SIGNAL 25 Signal Name Specification 25 Signal Name 25 Sign
INTELLIGENT CRUISE CONTROL Connector No. M88 Connector Nums A/O AUTO AMP. Connector Type TH4679/484	Ferritoria Color Of Signal Name Specification 1

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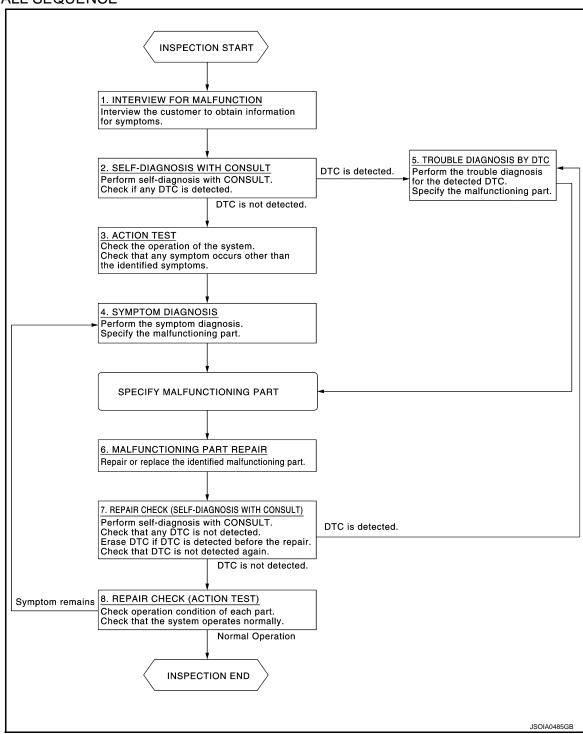
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BASIC INSPECTION

DIAGNOSIS AND REPAIR WORK FLOW

Work Flow

OVERALL SEQUENCE



DETAILED FLOW

1.INTERVIEW FOR MALFUNCTION

It is also important to clarify the customer concerns before starting the inspection. Interview the customer about the concerns carefully and understand the symptoms fully.

NOTE:

DIAGNOSIS AND REPAIR WORK FLOW

[ICC] < BASIC INSPECTION > The customers are not professionals. Never assume that "maybe the customer means..." or "maybe the customer mentioned this symptom". Α >> GO TO 2. 2.self-diagnosis with consult 1. Perform "All DTC Reading" with CONSULT. Check if any DTC is detected in self-diagnosis results of "ICC/ADAS", "LASER/RADAR", and "BSW/ BUZZER". Is any DTC detected? YES >> GO TO 5. D NO >> GO TO 3. 3. ACTION TEST Perform the ICC system action test to check the operation status. Refer to CCS-95, "Description". Check if any other malfunctions occur. >> GO TO 4. 4.SYMPTOM DIAGNOSIS Perform the applicable diagnosis according to the diagnosis chart by symptom. Refer to CCS-119, "Symptom Table". >> GO TO 6. Н 5.TROUBLE DIAGNOSIS BY DTC Check the DTC in the self-diagnosis results. Perform trouble diagnosis for the detected DTC. Refer to CCS-58, "DTC Index" (ICC/ADAS) or CCS-63, "DTC Index" (LASER/RADAR) or DAS-280, "DTC Index" (BSW/BUZZER). If "DTC: U1000" is detected, first diagnose the CAN communication system or ITS communication system. >> GO TO 6. K **6.**MALFUNCTIONING PART REPAIR Repair or replace the identified malfunctioning parts. >> GO TO 7. 7.REPAIR CHECK (SELF-DIAGNOSIS WITH CONSULT) Erases self-diagnosis results. 2. Perform "All DTC Reading" again after repairing or replacing the malfunctioning parts. 3. Check if any DTC is detected in self-diagnosis results of "ICC/ADAS", "LASER/RADAR", and "BSW/ BUZZER". Is any DTC detected? YFS >> GO TO 5. ccs NO >> GO TO 8. 8.REPAIR CHECK (ACTION TEST) Perform the ICC system action test. Check if the malfunction symptom is solved or no other symptoms occur.

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Is there any malfunction symptom?

>> INSPECTION END

>> GO TO 4.

YES

NO

ADDITIONAL SERVICE WHEN REPLACING ICC SENSOR

< BASIC INSPECTION > [ICC]

ADDITIONAL SERVICE WHEN REPLACING ICC SENSOR

Description INFOID:000000009644232

Always perform the radar alignment after removing and installing or replacing the ICC sensor.
 CAUTION:

The system does not operate normally unless the radar alignment is performed. Always perform it.

• Perform the ICC system action test to check that the ICC system operates normally.

Work Procedure

1.PERFORM RADAR ALIGNMENT

Perform the radar alignment. Refer to CCS-83, "TYPE 1: Description".

>> GO TO 2.

2.ICC SYSTEM ACTION TEST

- 1. Perform the ICC system action test. Refer to CCS-95, "Description".
- 2. Check that the ICC system operates normally.

>> INSPECTION END

< BASIC INSPECTION > [ICC]

ICC SENSOR ALIGNMENT

Application Notice

INFOID:0000000010304532	

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Туре	Description	-
TYPE 1	When using KV99112700 for radar alignment.	_
TYPE 2	When using following tools for radar alignment. ICC Alignment Kit (1-20-2721-1-IF) Wheel Adaptor (1-20-2722-1-IF) ICC alignment kit attachment board (J-50808)	_

TYPE 1

TYPE 1: Description

INFOID:0000000009644234

OUTLINE OF RADAR ALIGNMENT PROCEDURE

- A 4-wheel vehicle alignment must be performed before proceeding with radar alignment procedure.
- Always perform the radar alignment after removing and installing or replacing the ICC sensor.

WARNING:

Radio waves could adversely affect electric medical equipment. Those who use a pacemaker should contact the electric medical equipment manufacturer for the possible influences before use.

CAUTION:

The system does not operate normally unless the radar alignment is performed. Always perform it.

- 1. Set the distance sensor target board (SST: KV99112700) to the correct position in front of the vehicle.
- 2. Set the radar alignment mode ("MILLIWAVE RADAR ADJUST" on "Work support") with CONSULT, and then perform the adjustment according to the display. (ICC sensor automatically adjusts.)

CAUTIONARY POINT FOR RADAR ALIGNMENT PROCEDURE

CAUTION:

- For radar alignment procedure, choose a level location with a few meter of working space in front and surrounding the vehicle.
- Vehicle must be stationary and unoccupied during the whole alignment procedure.
- Any slight vibration during the alignment procedure can cause the test to fail. If this happens, you
 will have to restart the alignment process.
- The ignition switch must be in the ON position.
- The battery voltage must not fall below 12 volts during the whole alignment procedure. Failure to maintain adequate battery voltage will cause the test to fail. If this happens, you will have to restart the alignment process.
- The ICC target board must be set in front of the vehicle facing the sensor.
- Adjust the radar alignment with CONSULT. (The radar alignment procedure cannot be adjusted without CONSULT.)
- Never enter the vehicle during radar alignment.
- Never block the area between the radar and the ICC target board at any time during the alignment process.
- Accurate steering wheel setting is crucial. Once set, do not disturb the steering wheel for the remainder of the alignment procedure.
- For proper system operation and adjustment, all vehicle wheels must be of the same size.

TYPE 1: Work Procedure (Preparation)

INFOID:0000000009644235

1. ADVANCE PREPARATION FOR RADAR ALIGNMENT

- 1. Adjust all tire pressure to the specified value.
- 2. Empty the vehicle. (Remove any luggage from the passenger compartment, trunk room, etc.)
- 3. Shift the selector lever to "P" position, and release the parking brake.
- 4. Fully fill the fuel tank, and then check that the coolant and oils are filled up to correct level.

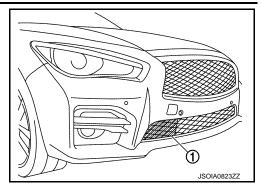
Revision: 2013 October CCS-83 2014 Q50

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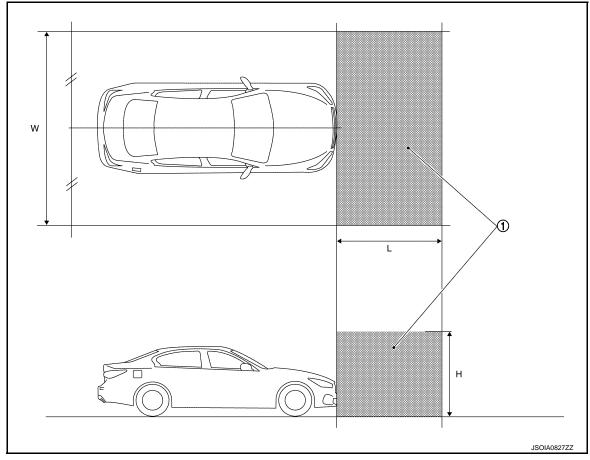
5. Clean the ICC sensor area ① of the front bumper grille.

>> GO TO 2.



2. RADAR ALIGNMENT OPERATION AREA

Position the vehicle in a place that is level and where ① area can be secured.



W : 3000 mm (118.11 in) L : 2000 mm (78.74 in) H : 2000 mm (78.74 in)

NOTE:

1) is a no object zone.

>> Go to CCS-84. "TYPE 1: Work Procedure (Setting The ICC Target Board)".

TYPE 1: Work Procedure (Setting The ICC Target Board)

INFOID:0000000009644236

DESCRIPTION

Accurate adjustment of the radar alignment requires that the ICC sensor target board be accurately positioned.

CAUTION:

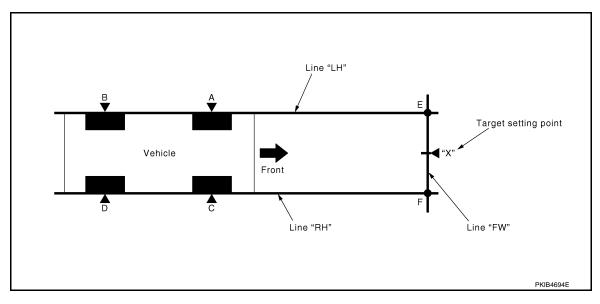
If the radar alignment is adjusted with the distance sensor target board in the incorrect position, the ICC system does not function normally.

1. DISTANCE SENSOR TARGET BOARD HEIGHT ADJUSTMENT

Adjust the base of ICC target board to approximately 30 mm (1.18 in) from the ground.

>> GO TO 2.

2.PREPARATION OF SETTING DISTANCE SENSOR TARGET BOARD (1)



1. Mark points "A", "B", "C" and "D"at the center of the lateral surface of each wheels.

NOTE:

Hang a string with a cone from the fender so as to pass through the center of wheel, and then mark a point at the center of the lateral surface of the wheel.

2. Draw line "LH" passing through points "A" and "B" on the left side of vehicle.

NOTE:

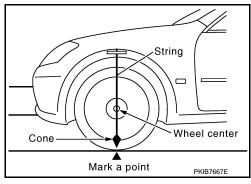
Approximately 4 m (13.12 ft) or more from the front end of vehicle.

- 3. Mark point "E" on the line "LH" at the positions 1727 mm (67.99 in) from point "A".
- 4. Draw line "RH" passing through points "C" and "D" on the right side of vehicle in the same way as step 2. **NOTE:**

Approximately 2 m (6.56 ft) or more from the front end of vehicle.

- 5. Mark point "F" on the line "RH" at the positions 1727 mm (67.99 in) from point "C".
- 6. Draw line "FW" passing through the points "E" and "F" on the front side of vehicle.
- Mark point "X" at the center of point "E" and "F" on the line "FW". CAUTION:

Make sure that "E" to "X" is equal to "F" to "X".



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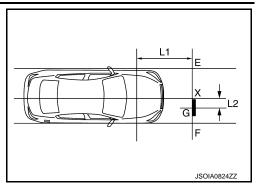
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8. With point "X" as the starting point, mark point "G" on "F" point side 368 mm (14.49 in).

L1 : 1727 mm (67.99 in) L2 : 368 mm (14.49 in)

>> GO TO 3.



$3.\mathsf{setting}$ distance sensor target board

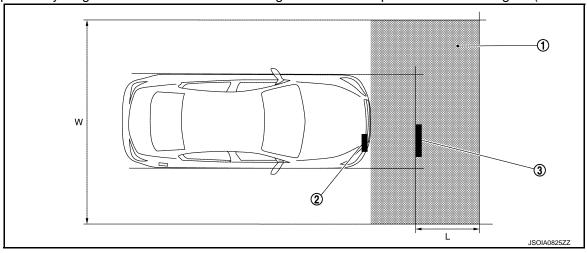
Place the center of ICC target board on point "G" at line "E-F" and install the ICC target board.

For performing the radar alignment correctly, securely install (ICC target board) to be parallel with the "E-F" line.

>> GO TO 4.

4. CHECK THE DISTANCE SENSOR TARGET BOARD INSTALLATION AREA

Do not place anything other than distance sensor target board in the space shown in the figure (view from top).



No object zone

W. 3000 mm (118.11 in)

② ICC sensor

1500 mm (59.06 in)

③ ICC target board

>> Go to CCS-86, "TYPE 1: Work Procedure (Radar Alignment)".

TYPE 1: Work Procedure (Radar Alignment)

DESCRIPTION

The radar alignment is performed automatically with CONSULT.

CAUTION:

Perform all necessary work for radar alignment until the adjustment completes as shown in the procedure. If the procedure does not complete, the ICC system is inoperable.

1. PERFORM RADAR ALIGNMENT

- Start the engine.
- Connect CONSULT and select "Work support" of "LASER/RADAR".
- Select "MILLIWAVE RADAR ADJUST" after the "Work support" screen is displayed.
 NOTE:

Confirm the following items;

• The target should be accurately placed.

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< BASIC INSPECTION > [ICC]

- The vehicle should be stopped.
- 4. Select "Start" after the "MILLIWAVE RADAR ADJUST" screen is displayed.

CAUTION:

Never select "Start" when the target is not accurately placed.

- 5. Select "Start" after the preparation information is displayed.
- 6. Select "Next" after the "Starting alignment." screen is displayed.

NOTE:

If the radar is in alignment at this time, "Alignment in progress" is displayed. It may take several 10s of seconds until the result is displayed.

- 7. Confirm the displayed item.
- "Alignment completed.": Go to 8.
- Except "Alignment completed.": Perform the following services.

Displayed item	Possible cause	Service procedure
Alignment condition is not ready.	 DTC is detected (Except C1A12). The position of the ICC target board is not correct. Vehicle is moving. 	Check the vehicle condition and perform radar alignment again.
Alignment condition is not ready. (Stop the vehicle.)	Vehicle is moving.	Stop the vehicle and perform radar alignment again.
Target is not detected.	A target is not-yet-placed. (The ICC sensor cannot detect target) The position of the ICC target board is not correct. The position of the ICC sensor is not correct.	Check the target board condition and perform radar alignment again.
Sensor malfunction.	ICC sensor malfunction.	Check the vehicle condition and perform radar alignment again.

NOTE:

Replace ICC sensor if "Sensor malfunction." is repeatedly indicated.

8. Confirm displayed value.

Displayed item	Monitor item	Reference value
	FACTORY AIM L/R	Less than 3.00 deg
Alignment completed	FACTORY AIM U/D	Less than 3.00 deg
Alignment completed.	AIMING VALUE L/R	Less than 3.00 deg
	AIMING VALUE U/D	Less than 3.00 deg

- Within reference value: Go to 9.
- Outside of reference value: Check the target board condition and perform radar alignment again.

NOTE:

- Check the condition of the ICC sensor installation.
- Check the vehicle for damage.
- Replace ICC sensor if it is outside the reference value, even when ICC sensor installation is installed normally and the vehicle is not damaged.
- 9. Select "OK" after the "No error detected." is displayed.
- 10. Select "OK" after the "End of alignment." is displayed.

CAUTION:

Once "MILLIWAVE RADAR ADJUST" is started with CONSULT, always continue the work until the horizontal radar alignment is completed successfully. If the job is stopped midway, the radar alignment is not adjusted and the ICC system cannot operate.

>> RADAR ALIGNMENT END

TYPE 2

TYPE 2: Description

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OUTLINE OF RADAR ALIGNMENT PROCEDURE

A 4-wheel vehicle alignment must be performed before proceeding with radar alignment procedure.

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< BASIC INSPECTION > [ICC]

- Always perform the radar alignment after removing and installing or replacing the ICC sensor.
- Always perform the radar alignment if rear axle toe settings have been made.

WARNING

Radio waves could adversely affect electric medical equipment. Those who use a pacemaker should contact the electric medical equipment manufacturer for the possible influences before use.

CAUTION:

The system does not operate normally unless the ICC sensor is aligned properly.

- Required tools, refer to <u>CCS-88, "TYPE 2 : Required Tools"</u>.
- Preparation, refer to <u>CCS-89</u>, "TYPE 2: Preparation".
- Vehicle set up, refer to <u>CCS-90, "TYPE 2: Vehicle Set Up"</u>.
- 4. Setting the ICC target board, refer to CCS-92, "TYPE 2: Setting The ICC Target Board".
- 5. ICC sensor adjustment, refer to CCS-93, "TYPE 2: ICC Sensor Adjustment".

CAUTIONARY POINT FOR RADAR ALIGNMENT PROCEDURE

CAUTION:

- For radar alignment procedure, choose a level location with a few feet of working space in front and surrounding the vehicle.
- Vehicle must be stationary and unoccupied during the whole alignment procedure.
- Any slight vibration during the alignment procedure can cause the test to fail. If this happens, you will have to restart the alignment process.
- The battery voltage must not fall below 12 volts during the whole alignment procedure. Failure to maintain adequate battery voltage will cause the test to fail. If this happens, you will have to restart the alignment process.
- The ICC target board must be set in front of the vehicle facing the sensor.
- Adjust the radar alignment with CONSULT. (The radar alignment procedure cannot be adjusted without CONSULT.)
- · Never enter the vehicle during radar alignment.
- Never block the area between the radar and the ICC target board at any time during the alignment process.
- Accurate steering wheel setting is crucial. Once set, do not disturb the steering wheel for the remainder of the alignment procedure.
- For proper system operation and adjustment, all vehicle wheels must be of the same size.

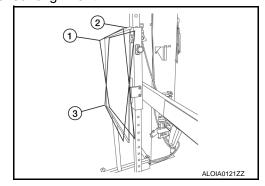
TYPE 2 : Required Tools

INFOID:0000000010249676

- ICC alignment kit in addition to one of the following:
 - a) Hunter self-centering wheel adapter (Hunter wheel alignment tool)
 - b) Special Service Tool kit 1-20-2722-1-IF (kit SCA W/Tire Clamp-ICC Aiming)

The following ICC alignment kit are necessary to perform the ICC sensor alignment:

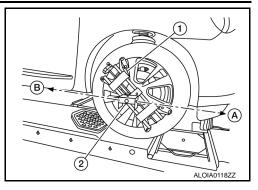
- ICC target board.
- (1): Position 1, with top tilted 2° toward vehicle (Not used).
- 2: Position 2, vertical.
- ③: Position 3, with top tilted 2° away from vehicle (Not used).



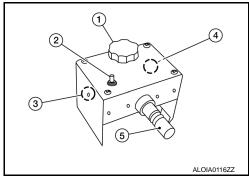
[ICC] < BASIC INSPECTION >

• Hunter self-centering wheel adapter ① [shown with laser assembly (2) installed] (Hunter alignment rack head may be substituted). NOTE:

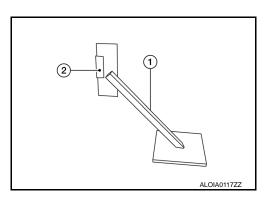
- Retailers that are not equipped with a Hunter self-centering wheel adapter will require the following kit: Part No. 1-20-2722-1-IF (kit SCA W/Tire Clamp-ICC Aiming)
- Directional arrows (A) and (B) are shown to illustrate the direction of the laser assembly beams.



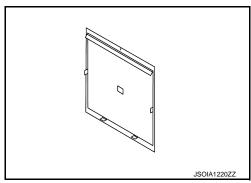
- Laser assembly (with bi-directional laser beam) as shown in the illustration.
- Tightening knob (1)
- Power ON/OFF button (2)
- Front laser beam opening (3)
- Rear laser beam opening (4)
- Attaching shaft (5)



- Stationary target as shown in the illustration.
- Stationary target (1)
- Laser signal reception plate 2



• ICC alignment kit attachment board as shown in the illustration.



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TYPE 2: Preparation

1. ADVANCE PREPARATION FOR RADAR ALIGNMENT PROCEDURE

- 1. Adjust all tire pressure to the specified value.
- 2. Empty the vehicle. (Remove any luggage from the passenger compartment, luggage room, etc.)
- Shift the selector lever to "P" position, and release the parking brake.
- 4. Fully fill the fuel tank, and then check that the coolant and oils are filled up to correct level.

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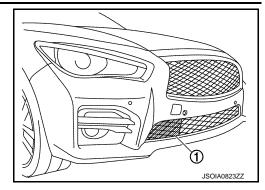
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< BASIC INSPECTION > [ICC]

5. Clean the ICC sensor area ① of the front bumper grille.

>> Refer to CCS-90, "TYPE 2 : Vehicle Set Up".



TYPE 2: Vehicle Set Up

INFOID:0000000010249678

DESCRIPTION

Accurate adjustment of the radar alignment requires that the ICC target board, wheel adapter, laser assembly, and stationary target be properly positioned.

CAUTION:

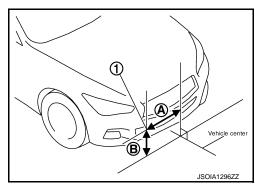
If the radar alignment is adjusted with the ICC target board, wheel adapter, laser assembly, or stationary target in the incorrect position, the ICC system will not function properly or the alignment procedure may not be completed successfully.

1. PREPOSITION TARGET BOARD

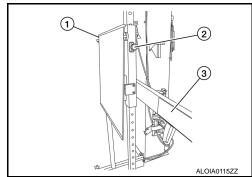
NOTE:

• To identify the sensor wave axis center, measure the point ① as shown in the illustration.

A : 368 mm (14.49 in)
B : 320 mm (12.6 in)

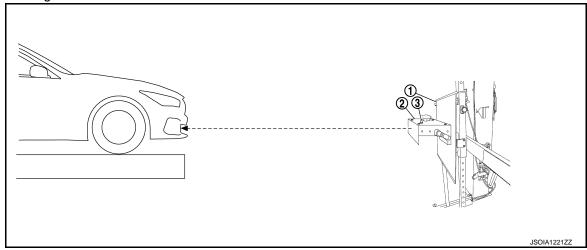


- ICC target board setting must be in the center position. (Position 2)
- Attaching the ICC alignment kit attachment board to the ICC target board.
- Position the ICC target board in front facing the right front side of the vehicle:
- Place the marked center of the ICC target board ① 1060 mm (41.73 in.) ± 50 mm (1.97 in) facing the ICC sensor.
- Adjust the height of the ICC target board using the adjustable nut ② to achieve the proper height. The up/down tolerance is \pm 30 mm (1.18 in).
- Adjust the ICC target board lateral position aligning the marked center of the board horizontally with the center of the ICC sensor. The right/left tolerance is \pm 80 mm (3.15 in).
- 2. Extend the machined arm of the ICC target board exposing the reflective surface (3) to the right front side of the vehicle.



[ICC] < BASIC INSPECTION >

Place one side of the laser assembly ② flush against the center of the ICC target board ① to assist in the positioning.



- 4. Turn the laser assembly ON ③ allowing the laser beam to emit through the opening of the laser assembly toward the center of the ICC sensor.
- Move the ICC target board (1) as necessary so that center of ICC target board aligns with center of ICC sensor.
- Turn the laser assembly OFF when done.

Are using Hunter alignment equipment?

YES >> Refer to Hunter's equipment instructions for complete vehicle set up and ICC target board setting. Then, refer to CCS-93, "TYPE 2: ICC Sensor Adjustment".

NO >> GO TO 2.

2.INSTALLING LASER ASSEMBLY

NOTE:

- Insure the steering wheel is positioned in the center straight forward position.
- Insure all 4 vehicle wheels do not contain any physical damage.
- 1. Install the wheel adapter (1) on the right front wheel.
- 2. Mount the laser assembly ② to the wheel adapter ① as shown in the figure.

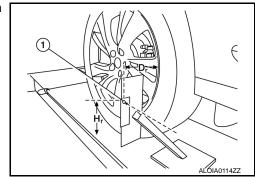
NOTE:

When the power switch is turned ON, the front laser signal (A) will be emitted toward the front ICC target board, and the rear laser signal (B) will be emitted toward the rear of the vehicle.

>> GO TO 3.

$3.\mathsf{setting}$ up stationary target

Place the stationary target next to the right rear tire as shown in the figure.



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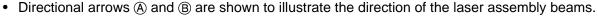
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2. Turn the laser assembly ON allowing the laser beam to be emitted through the front and rear laser assembly openings.

- 3. Measure and record the distance (Dr) between the edge of the right rear wheel and the laser beam (1) on the stationary target (horizontal line).
- 4. Measure and record the height (Hr) between the laser beam ① on the stationary target and ground level (vertical line).
- 5. Measure and record the distance (Df) between the edge of the right front wheel and the laser beam signal/opening ① on the laser assembly (horizontal line).
- 6. Measure and record the height (H_f) between the laser beam signal/opening ① on the laser assembly and ground level (vertical line).

NOTE:

- Horizontal adjustment [front distance (Df) and rear distance (Dr)] is accomplished by slowly turning the steering wheel until the 2 distances are the same.
- Vertical adjustment [front height (H_f) and rear height (H_r)] is accomplished by rotating the laser assembly around its axis until the two heights are the same.



7. Adjust laser beam as necessary until the two distances match and the two heights match.

NOTE:

Must be verify both horizontal and vertical adjustments anytime one adjustment is made.

>> Refer to CCS-92, "TYPE 2 : Setting The ICC Target Board".

TYPE 2 : Setting The ICC Target Board

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DESCRIPTION

Accurate adjustment of the radar alignment requires that the ICC target board be accurately positioned.

If the radar alignment is adjusted with the ICC target board in the incorrect position, the ICC system will not function properly or the alignment procedure may not be completed successfully.

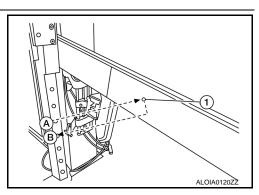
1.ICC TARGET BOARD FINAL SETTING

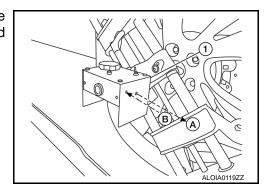
1. With the ICC target board arm extended, the laser beam ① emitted by the laser assembly ⓐ will be reflected back ⓑ toward the laser assembly.

NOTE:

When adjusted properly, reflected laser beam (B) must align with emitted laser beam (A) and the two laser beams will be seen as one

- 2. Rotate the ICC target board to achieve the necessary horizontal adjustment.
- Adjust the ICC target board leveling screws to achieve the necessary vertical adjustment.
- 4. The figure shown illustrates the laser beam (A) emitted by the laser assembly (1) and its reflection (B) off of the ICC target board arm.

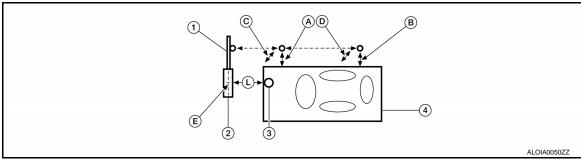




>> GO TO 2.

2.CHECK THE POSITION OF THE ICC TARGET BOARD

Do not place anything other than the ICC target board in the space shown in front of the vehicle (view from top).



- (1) ICC target board arm
- ICC target board

n ICC sensor

- Vehicle
- Distance between front wheel and laser beam (Df)
- Height between rear laser beam and ground (Hr)
- Distance between rear wheel and laser beam (Dr)
- ICC target board center position
- Height between front laser beam and ground (Hf)
- ① 1010 1110 mm (39.76 43.7 in)

>> Refer to CCS-93, "TYPE 2 : ICC Sensor Adjustment".

TYPE 2: ICC Sensor Adjustment

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DESCRIPTION

The radar alignment is performed automatically with CONSULT.

CAUTION:

Perform all necessary work for radar alignment until the adjustment completes as shown in the procedure. If the procedure does not complete, the ICC system is inoperable.

1.PERFORM RADAR ALIGNMENT

- 1. Start the engine.
- 2. Connect CONSULT and select "Work support" of "LASER/RADAR".
- Select "MILLIWAVE RADAR ADJUST" after the "Work support" screen is displayed.

NOTE:

Confirm the following items;

- The target should be accurately placed.
- The vehicle should be stopped.
- 4. Select "Start" after the "MILLIWAVE RADAR ADJUST" screen is displayed.

CAUTION:

Never select "Start" when the target is not accurately placed.

- 5. Select "Start" after the preparation information is displayed.
- 6. Select "Next" after the "Starting alignment." screen is displayed.

NOTE:

If the radar is in alignment at this time, "Alignment in progress" is displayed. It may take several 10s of seconds until the result is displayed.

- 7. Confirm the displayed item.
- "Alignment completed.": Go to 8.
- Except "Alignment completed.": Perform the following services.

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Displayed item	Possible cause	Service procedure
Alignment condition is not ready.	 DTC is detected (Except C1A12). The position of the ICC target board is not correct. Vehicle is moving. 	Check the vehicle condition and perform radar alignment again.
Alignment condition is not ready. (Stop the vehicle.)	Vehicle is moving.	Stop the vehicle and perform radar alignment again.
Target is not detected.	 A target is not-yet-placed. (The ICC sensor cannot detect target) The position of the ICC target board is not correct. The position of the ICC sensor is not correct. 	Check the target board condition and perform radar alignment again.
Sensor malfunction.	ICC sensor malfunction.	Check the vehicle condition and perform radar alignment again.

NOTE:

Replace ICC sensor if "Sensor malfunction." is repeatedly indicated.

8. Confirm displayed value.

Displayed item	Monitor item	Reference value
	FACTORY AIM L/R	Less than 3.00 deg
Alignment completed.	FACTORY AIM U/D	Less than 3.00 deg
Alignment completed.	AIMING VALUE L/R	Less than 3.00 deg
	AIMING VALUE U/D	Less than 3.00 deg

- Within reference value: Go to 9.
- Outside of reference value: Check the target board condition and perform radar alignment again.

NOTE:

- Check the condition of the ICC sensor installation.
- Check the vehicle for damage.
- Replace ICC sensor if it is outside the reference value, even when ICC sensor installation is installed normally and the vehicle is not damaged.
- 9. Select "OK" after the "No error detected." is displayed.
- 10. Select "OK" after the "End of alignment." is displayed.

CAUTION:

Once "MILLIWAVE RADAR ADJUST" is started with CONSULT, always continue the work until the horizontal radar alignment is completed successfully. If the job is stopped midway, the radar alignment is not adjusted and the ICC system cannot operate.

>> RADAR ALIGNMENT END

< BASIC INSPECTION > [ICC]

ACTION TEST

Description INFOID:000000000644238

Always perform the ICC system action test to check that the ICC system operates normally after replacing the ICC sensor or repairing any ICC system malfunction.

CAUTION:

- Always drive safely when performing the action test.
- Turn the DCA system to OFF when performing the action test.

Work Procedure (Vehicle-To-Vehicle Distance Control Mode)

INFOID:0000000009644239

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NOTE:

- When there is no vehicle ahead, drive at the set speed steadily.
- When there is a vehicle ahead, control to maintain distance from the vehicle ahead, watching its speed.
- The running speed can be set between 32 km/h (20 MPH) and 144 km/h (90 MPH).

CAUTION:

Never set the cruise speed exceeding the posted speed limit.

1. CHECK FOR MAIN SWITCH

- 1. Start the engine.
- 2. Press the MAIN switch (1) (less than 1.5 seconds).

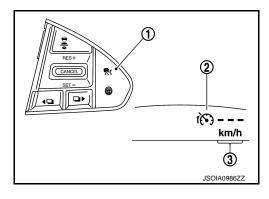
Information display status

MAIN switch indicator ② : ON

Set distance indicator (3) : Long mode

Set vehicle speed indicator 4 "——"

'km/h" ("MPH")



- Check the ICC system display on the information display to check that the vehicle-to-vehicle distance control mode is ready for activation.
- 4. Press the MAIN switch, and check that the ICC system display on the information display turns OFF when the ICC system is deactivated.
- 5. Check that the ICC system display on the information display turns OFF after starting the engine again.

>> GO TO 2.

2.CHECK FOR DISTANCE SWITCH

- 1. Start the engine.
- 2. Press the MAIN switch (less than 1.5 seconds).
- Press the DISTANCE switch.

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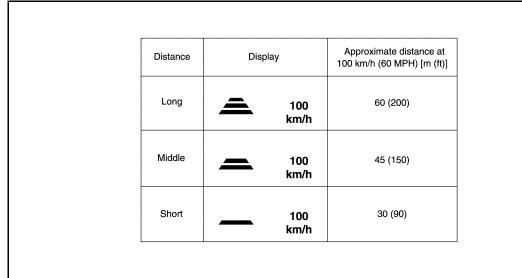
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Check that the set distance indicator changes display in order of: (Long)→(Middle)→(Short).



NOTE:

When the MAIN switch is turned ON, initial setting set to (Long).

>> GO TO 3.

3.CHECK FOR RESUME/ACCELERATE, SET/COAST, AND CANCEL SWITCHES

- 1. Check that RESUME/ACCELERATE, SET/COAST, CANCEL switches are operated smoothly.
- 2. Check that switches come up as hand is released from the switches.

>> GO TO 4.

4.SET CHECKING (1)

- 1. Start the engine.
- Press the MAIN switch (less than 1.5 seconds) and turn the vehicle-to-vehicle distance control mode ON.

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- 3. Drive the vehicle at 32 km/h (20 MPH) or more.
- 4. Push down the SET/COAST switch.
- Check that the desired speed is set and vehicle-to-vehicle distance control mode control starts when releasing SET/COAST switch.

NOTE:

The set vehicle speed is indicated on the set vehicle speed indicator in the ICC system display on the information display.

>> GO TO 5.

5.CHECK FOR INCREASE OF CRUISING SPEED (1)

- 1. Set the vehicle-to-vehicle distance control mode at desired speed.
- 2. Check that the set speed increases by 1 km/h (1 MPH) as RESUME/ACCELERATE switch is pushed up. **NOTE:**

The maximum set speed of the vehicle-to-vehicle distance control mode is 144 km/h (90 MPH).

CAUTION:

Never set the cruise speed exceeding the posted speed limit.

>> GO TO 6.

6. CHECK FOR DECREASE OF CRUISING SPEED (1)

- Set the vehicle-to-vehicle distance control mode at desired speed.
- 2. Check that the set speed decreases by 1 km/h (1 MPH) as SET/COAST switch is pushed down. **NOTE:**
- The minimum set speed is approximately 32 km/h (20 MPH).

< BASIC INSPECTION > [ICC]

 Cancel the control automatically when the vehicle speed is less than approximately 24 km/h (15 MPH) and when the system does not detect any vehicle ahead.

>> GO TO 7.

7.SET CHECKING (2)

- 1. Stop the vehicle.
- 2. Drive the vehicle at less than approximately 32 km/h (20 MPH).
- 3. Push down the SET/COAST switch when the system detects a vehicle ahead.
- Check that the vehicle-to-vehicle distance control mode is performed so that the vehicle maintains a
 proper distance according to the vehicle speed [maximum: approximately 32 km/h (20 MPH)] when
 releasing SET/COAST switch.

NOTE:

- The vehicle-to-vehicle distance control mode cannot be set when the vehicle speed is less than 32 km/h (20 MPH) and when a vehicle ahead is not detected.
- Cancel the control automatically when the vehicle speed is 24 km/h (15 MPH) or less during the control and when the system does not detect any vehicle ahead.
- The set vehicle speed indicator in the ICC system display on the information display is set to 32 km/h (20 MPH).

>> GO TO 8.

>> GO TO 9.

8. CHECK FOR INCREASE OF CRUISING SPEED (2)

- 1. Set the vehicle-to-vehicle distance control mode when the vehicle speed is less than approximately 32 km/h (20 MPH) and when a vehicle ahead is detected.
- 2. Check that the set speed increases by 1 km/h (1 MPH) as RESUME/ACCELERATE switch is pushed up.

NOTE:

The maximum set speed of the vehicle-to-vehicle distance control mode is 144 km/h (90 MPH).

CAUTION:

Never set the cruise speed exceeding the posted speed limit.

9. CHECK FOR DECREASE OF CRUISING SPEED INSPECTION (2)

- 1. Set the vehicle-to-vehicle distance control mode when the vehicle speed is less than approximately 32 km/h (20 MPH) and when a vehicle ahead is detected.
- Set the set vehicle speed to the desired vehicle speed according to "check for increase of cruising speed".
- 3. Check that the set speed decreases by 1 km/h (1 MPH) as SET/COAST switch is pushed down.

NOTE:

- The minimum the set speed is approximately 32 km/h (20 MPH).
- If the vehicle ahead comes to a stop, the vehicle decelerates to a standstill within the limitations of the system. The system will cancel once it judges a standstill with a warning chime.

CAUTION:

The creep occurs because the stop status is not maintained.

>> GO TO 10.

10.check for cancellation of vehicle-to-vehicle distance control mode

Check that the vehicle-to-vehicle distance control mode is canceled when performing the following operations.

- When the brake pedal is depressed after vehicle-to-vehicle distance control mode is set and the vehicle is driven.
- When the selector lever is in the "N" position after vehicle-to-vehicle distance control mode is set and the vehicle is driven.
- When the MAIN switch is turned OFF after vehicle-to-vehicle distance control mode is set and the vehicle is driven
- When the CANCEL switch is pressed after vehicle-to-vehicle distance control mode is set and the vehicle is driven.

>> GO TO 11.

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Revision: 2013 October CCS-97 2014 Q50

< BASIC INSPECTION > [ICC]

11. CHECK FOR RESTORING SPEED THAT IS SET BY VEHICLE-TO-VEHICLE DISTANCE CONTROL MODE BEFORE CANCELLATION

Check that the vehicle restores the previous speed kept before the system deactivation when performing the following operations.

- Drive the vehicle when the vehicle-to-vehicle distance control mode is set and depress the brake pedal to cancel the control. Check that the vehicle restores the previous vehicle speed kept before the system deactivation when pushing up the RESUME/ACCELERATE switch.
- Drive the vehicle when the vehicle-to-vehicle distance control mode is set and shift the selector lever to the "N" position to cancel the control. Check that the vehicle restores the previous vehicle speed kept before the system deactivation when shifting the selector lever to the "D" position and pushing up the RESUME/ ACCELERATE switch.
- Drive the vehicle when the vehicle-to-vehicle distance control mode is set and press the CANCEL switch to
 cancel the control. Check that the vehicle restores the previous vehicle speed kept before the system deactivation when pushing up the RESUME/ACCELERATE switch.

>> INSPECTION END

Work Procedure [Conventional (Fixed Speed) Cruise Control Mode]

INFOID:000000000964424

NOTE

The running speed can be set between 40 km/h (25 MPH) and 144 km/h (90 MPH) CAUTION:

Never set the cruise speed exceeding the posted speed limit.

1. CHECK FOR MAIN SWITCH

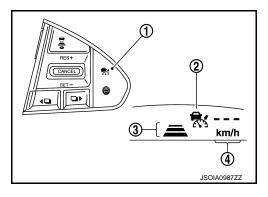
- 1. Start the engine.
- 2. Press the MAIN switch (1) (1.5 seconds or more).

Information display status

MAIN switch indicator ② : ON

Set vehicle speed indicator ③ : "____"

**m/h" ("MPH")



- Check that the ICC system display on the information display turns on and the display is ready for activation.
- Press the MAIN switch, and check that the ICC system display on the information display turns OFF when the ICC system is deactivated.
- 5. Check that the ICC system display on the information display turns OFF after starting the engine again.

>> GO TO 2.

2.CHECK FOR RESUME/ACCELERATE, SET/COAST, AND CANCEL SWITCHES

- 1. Check that RESUME/ACCELERATE, SET/COAST, CANCEL switches are operated smoothly.
- 2. Check that switches come up as hand is released from the switches.

>> GO TO 3.

3.SET CHECKING

- Start the engine.
- Press the MAIN switch (1.5 seconds or more) and turn the conventional (fixed speed) cruise control mode to ON.
- 3. Drive the vehicle at 40 km/h (25 MPH) or more.
- Push down the SET/COAST switch.

< BASIC INSPECTION > [ICC]

5. Check that the desired speed is set and conventional (fixed speed) cruise control mode control starts when releasing SET/COAST switch.

NOTE:

- The set vehicle speed is not displayed in the ICC system display on the information display.
- Display the set status in the ICC system display on the information display.

>> GO TO 4.

4. CHECK FOR INCREASE OF CRUISING SPEED

- 1. Set the vehicle speed to any desired speed, and drive the vehicle.
- 2. Check that the set speed increases by 1.6 km/h (1 MPH) as RESUME/ACCELERATE switch is pushed up.

NOTE:

- The maximum set speed is 144 km/h (90 MPH).
- The set vehicle speed increases while pushing up the RESUME/ACCELERATE switch.

CAUTION:

Never set the cruise speed exceeding the posted speed limit.

>> GO TO 5.

5. CHECK FOR DECREASE OF CRUISING SPEED

- 1. Set the vehicle speed to any desired speed, and drive the vehicle.
- 2. Check that the set speed decreases by 1.6 km/h (1 MPH) as SET/COAST switch is pushed down.

NOTE:

- The minimum set speed is 40 km/h (25 MPH).
- The set vehicle speed decreases while pressing down the SET/COAST switch.

>> GO TO 6.

6. CHECK FOR CANCELLATION OF CONVENTIONAL (FIXED SPEED) CRUISE CONTROL MODE

Check that the conventional (fixed speed) cruise control mode is canceled when performing the following operations.

- When the brake pedal is depressed after the conventional (fixed speed) cruise control mode is set and the vehicle is driven.
- When the selector lever is in the "N" position after the conventional (fixed speed) cruise control mode is set and the vehicle is driven.
- When the MAIN switch is turned OFF after the conventional (fixed speed) cruise control mode is set and the vehicle is driven.
- When the CANCEL switch is pressed after the conventional (fixed speed) cruise control mode is set and the vehicle is driven.

>> GO TO 7.

7.CHECK FOR RESTORING SPEED THAT IS SET BY CONVENTIONAL (FIXED SPEED) CRUISE CONTROL MODE BEFORE CANCELLATION

Check that the vehicle restores the previous speed kept before the system deactivation when performing the following operations.

- Drive the vehicle when the conventional (fixed speed) cruise control mode is set and depress the brake
 pedal to cancel the control. Check that the vehicle restores the previous vehicle speed kept before the system deactivation when pushing up the RESUME/ACCELERATE switch at the vehicle speed approximately
 40 km/h (25 MPH) or more.
- Drive the vehicle when the conventional (fixed speed) cruise control mode is set and shift the selector lever
 is in the "N" position to cancel the control. Check that the vehicle restores the previous vehicle speed kept
 before the system deactivation when shifting the selector lever is in the "D" position and pushing up the
 RESUME/ACCELERATE switch at the vehicle speed of approximately 40 km/h (25 MPH) or more.
- Drive the vehicle when the conventional (fixed speed) cruise control mode is set and press the CANCEL switch to cancel the control. Check that the vehicle restores the previous vehicle speed kept before the system deactivation when pushing up the RESUME/ACCELERATE switch at the vehicle speed of approximately 40 km/h (25 MPH) or more.

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< BASIC INSPECTION > [ICC]

>> INSPECTION END

C1A00 CONTROL UNIT

< DTC/CIRCUIT DIAGNOSIS > [ICC]

DTC/CIRCUIT DIAGNOSIS

C1A00 CONTROL UNIT

DTC Logic

DTC DETECTION LOGIC

DTC	Trouble diagnosis name	DTC detecting condition
C1A00	CONTROL UNIT (Control unit malfunction)	ICC sensor internal malfunction

POSSIBLE CAUSE

ICC sensor

FAIL-SAFE

The following systems are canceled.

- Vehicle-to-vehicle distance control mode
- Conventional (fixed speed) cruise control mode
- Distance Control Assist (DCA)
- Forward Emergency Braking (FEB)
- Predictive Forward Collision Warning (PFCW)

DTC CONFIRMATION PROCEDURE

1. PERFORM DTC CONFIRMATION PROCEDURE

- Start the engine.
- Perform "All DTC Reading" with CONSULT.
- 3. Check if the "C1A00" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/RADAR".

Is "C1A00" detected as the current malfunction?

YES >> Refer to CCS-101, "Diagnosis Procedure".

NO-1 >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident".

NO-2 >> Confirmation after repair: INSPECTION END

Diagnosis Procedure

1. CHECK SELF-DIAGNOSIS RESULTS

Check if any DTC other than "C1A00" is detected in "Self Diagnostic Result" of "LASER/RADAR".

Is any DTC detected?

YES >> Perform diagnosis on the detected DTC and repair or replace the malfunctioning parts. Refer to CCS-63, "DTC Index".

NO >> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation".

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C1A01 POWER SUPPLY CIRCUIT 1, C1A02 POWER SUPPLY CIRCUIT 2

< DTC/CIRCUIT DIAGNOSIS >

[ICC]

C1A01 POWER SUPPLY CIRCUIT 1, C1A02 POWER SUPPLY CIRCUIT 2

DTC Logic INFOID:0000000009644243

DTC DETECTION LOGIC

DTC	Trouble diagnosis name	DTC detecting condition
C1A01	POWER SUPPLY CIR (Power supply circuit)	The battery voltage sent to ICC sensor remains less than 7.9 V for 5 seconds
C1A02	POWER SUPPLY CIR 2 (Power supply circuit 2)	The battery voltage sent to ICC sensor remains more than 19.3 V for 5 seconds

POSSIBLE CAUSE

- Connector, harness, fuse
- ICC sensor

FAIL-SAFE

The following systems are canceled.

- Vehicle-to-vehicle distance control mode
- Conventional (fixed speed) cruise control mode
- Distance Control Assist (DCA)
- Forward Emergency Braking (FEB)
- Predictive Forward Collision Warning (PFCW)

DTC CONFIRMATION PROCEDURE

${f 1}$. PERFORM DTC CONFIRMATION PROCEDURE

- Start the engine.
- Turn the MAIN switch of ICC system ON.
- Perform "All DTC Reading" with CONSULT. Check if the "C1A01" or "C1A02" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/RADAR".

Is "C1A01" or "C1A02" detected as the current malfunction?

- >> Refer to CCS-102, "Diagnosis Procedure".
- >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident". NO-1
- NO-2 >> Confirmation after repair: INSPECTION END

Diagnosis Procedure

INFOID:00000000009644244

${f 1}.$ CHECK ICC SENSOR POWER SUPPLY AND GROUND CIRCUIT

Check power supply and ground circuit of ICC sensor. Refer to CCS-118, "Diagnosis Procedure". Is the inspection result normal?

YES >> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation".

NO >> Repair or replace the malfunctioning parts.

C1A12 RADAR OFF-CENTER < DTC/CIRCUIT DIAGNOSIS > [ICC]			
C1A12 R	ADAR OFF-CENTER		А
DTC Logic	;	INFOID:0000000009644245	
DTC DETEC	CTION LOGIC		В
DTC	Trouble diagnosis name	DTC detecting condition	
C1A12	RADAR OFF-CENTER (Radar off-center)	Radar of ICC sensor is off the aiming point	С
POSSIBLE (Radar is off th	CAUSE ne aiming point		D
Vehicle-to-vDistance CoForward En	systems are canceled. vehicle distance control mode ontrol Assist (DCA) nergency Braking (FEB) Forward Collision Warning (PFC	2/4/)	E
	RMATION PROCEDURE		
1.PERFORM	M DTC CONFIRMATION PROC	CEDURE	G
 Turn the Perform ' 	 Turn the MAIN switch of ICC system ON. Perform "All DTC Reading" with CONSULT. Check if the "C1A12" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/" 		Н
•	Is "C1A12" detected as the current malfunction?		
YES >> Refer to CCS-103 , "Diagnosis Procedure". NO-1 >> To check malfunction symptom before repair: Refer to GI-43 , "Intermittent Incident". NO-2 >> Confirmation after repair: INSPECTION END			J
Diagnosis	Procedure	INFOID:0000000009644246	
1.ADJUST F	RADAR AIMING		K
Perform '	'All DTC Reading". the "C1A12" is detected in "Sel	SULT. Refer to CCS-83, "TYPE 1 : Description". f Diagnostic Result" of "LASER/RADAR".	L

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>> Replace the ICC sensor. Refer to $\underline{\text{CCS-135.}}$ "Removal and Installation". >> INSPECTION END

YES

NO

[ICC]

C1A16 RADAR BLOCKED

DTC Logic

DTC DETECTION LOGIC

DTC	Trouble diagnosis name	DTC detecting condition
C1A16	RADAR BLOCKED (Radar blocked)	Inclusion of dirt or stains on the ICC sensor area of the front bumper

NOTE:

DTC "C1A16" may be detected under the following conditions. (Explain to the customer about the difference between the contamination detection function and the indication when the malfunction is detected and tell them "This is not malfunction".)

- When contamination or foreign materials adhere to the ICC sensor area of the front bumper
- When driving while it is snowing or when frost forms on the ICC sensor area of the front bumper
- When ICC sensor area of the front bumper is temporarily fogged

POSSIBLE CAUSE

- · Stain or foreign materials is deposited
- · Cracks or scratches exist

FAIL-SAFE

The following systems are canceled.

- Vehicle-to-vehicle distance control mode
- Distance Control Assist (DCA)
- Forward Emergency Braking (FEB)
- Predictive Forward Collision Warning (PFCW)

DTC CONFIRMATION PROCEDURE

1. PERFORM DTC CONFIRMATION PROCEDURE

- 1. Start the engine.
- 2. Turn the MAIN switch of ICC system ON.
- Perform "All DTC Reading" with CONSULT.
- Check if the "C1A16" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/ RADAR".

Is "C1A16" detected as the current malfunction?

YES >> Refer to CCS-104, "Diagnosis Procedure".

NO-1 >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident".

NO-2 >> Confirmation after repair: INSPECTION END

Diagnosis Procedure

INFOID:0000000009644248

1. VISUAL CHECK 1

Check the contamination and foreign matter on the ICC sensor area of the front bumper.

Does contamination or foreign materials adhere?

YES >> Wipe out the contamination and foreign matter on the ICC sensor area of the front bumper.

NO >> GO TO 2.

2. VISUAL CHECK 2

- 1. Remove the front bumper.Refer to EXT-14, "Removal and Installation".
- 2. Check ICC sensor for contamination and foreign matter.

Does contamination or foreign matter adhere?

YES >> Wipe out the contamination and foreign matter from the ICC sensor.

NO >> GO TO 3.

3. VISUAL CHECK 3

Check ICC sensor for cracks and scratches.

C1A16 RADAR BLOCKED

< DTC/CIRCUIT DIAGNOSIS > [ICC]

Is it found?

YES >> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation".

NO >> GO TO 4.

4.INTERVIEW

- 1. Ask if there is any trace of contamination or foreign materials adhering to the ICC sensor area of the front bumper.
- 2. Ask if ICC sensor area of the front bumper was frosted during driving or if vehicle was driven in snow.
- 3. Ask if ICC sensor area of the front bumper was temporarily fogged. (Windshield glass may also tend to fog, etc.)

Is any of above conditions seen?

- YES >> Explain to the customer about the difference between the contamination detection function and the indication when the malfunction is detected and tell them "This is not malfunction".
- NO >> Replace the ICC sensor. Refer to CCS-135. "Removal and Installation".

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[ICC]

C1A21 UNIT HIGH TEMP

DTC Logic

DTC DETECTION LOGIC

DTC	Trouble diagnosis name	DTC detecting condition
C1A21	UNIT HIGH TEMP (Unit high temperature)	Temperature detected by the temperature sensor integrated in ICC sensor remains more than 105 °C (221 °F) for 5 seconds or more

POSSIBLE CAUSE

Temperature around the ICC sensor becomes extremely low or high

FAIL-SAFE

The following systems are canceled.

- Vehicle-to-vehicle distance control mode
- Conventional (fixed speed) cruise control mode
- Distance Control Assist (DCA)
- Forward Emergency Braking (FEB)
- Predictive Forward Collision Warning (PFCW)

DTC CONFIRMATION PROCEDURE

1. PERFORM DTC CONFIRMATION PROCEDURE

- 1. Turn the ignition switch OFF.
- 2. Wait for 10 minutes or more.
- 3. Start the engine.
- 4. Turn the MAIN switch of ICC system ON.
- 5. Perform "All DTC Reading" with CONSULT.
- Check if the "C1A21" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/ RADAR".

Is "C1A21" detected as the current malfunction?

YES >> Refer to CCS-106, "Diagnosis Procedure".

NO-1 >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident".

NO-2 >> Confirmation after repair: INSPECTION END

Diagnosis Procedure

INFOID:0000000009644252

1. CHECK ENGINE COOLING SYSTEM

Check for any malfunctions in engine cooling system.

Is engine cooling system normal?

YES >> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation".

NO >> Repair engine cooling system.

C1A23 UNIT LOW TEMP

< DTC/CIRCUIT DIAGNOSIS > [ICC]

C1A23 UNIT LOW TEMP

DTC Logic (INFOID:0000000000731493

DTC DETECTION LOGIC

DTC	Trouble diagnosis name	DTC detecting condition
C1A23	UNIT LOW TEMP (Unit low temperature)	Temperature detected by the temperature sensor integrated in ICC sensor remains less than -45 $^{\circ}$ C (-49 $^{\circ}$ F) for 5 seconds or more

POSSIBLE CAUSE

Temperature around the ICC sensor becomes extremely low or high

FAIL-SAFE

The following systems are canceled.

- Vehicle-to-vehicle distance control mode
- Conventional (fixed speed) cruise control mode
- Distance Control Assist (DCA)
- Forward Emergency Braking (FEB)
- Predictive Forward Collision Warning (PFCW)

DTC CONFIRMATION PROCEDURE

1. PERFORM DTC CONFIRMATION PROCEDURE

- 1. Turn the ignition switch OFF.
- 2. Wait for 10 minutes or more.
- 3. Start the engine.
- 4. Turn the MAIN switch of ICC system ON.
- 5. Perform "All DTC Reading" with CONSULT.
- Check if the "C1A23" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/ RADAR".

Is "C1A23" detected as the current malfunction?

YES >> Refer to CCS-107, "Diagnosis Procedure".

NO-1 >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident".

NO-2 >> Confirmation after repair: INSPECTION END

Diagnosis Procedure

1. CHECK ENVIRONMENT CONDITION

Check ambient temperature.

Is ambient temperature 0°C (32°F) or more?

YES >> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation".

NO >> Perform check again at 0°C (32°F) or more.

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[ICC]

C1A39 STEERING ANGLE SENSOR

DTC Logic

DTC DETECTION LOGIC

DTC	Trouble diagnosis name	DTC detecting condition
C1A39	STRG SEN CIR (Steering angle sensor circuit)	If the steering angle sensor is malfunction

POSSIBLE CAUSE

Steering angle sensor

FAIL-SAFE

The following systems are canceled.

- Vehicle-to-vehicle distance control mode
- · Conventional (fixed speed) cruise control mode
- Distance Control Assist (DCA)
- Forward Emergency Braking (FEB)
- Predictive Forward Collision Warning (PFCW)

DTC CONFIRMATION PROCEDURE

1. CHECK DTC PRIORITY

If DTC "C1A39" is displayed with DTC "U1000", first diagnose the DTC "U1000".

Is applicable DTC detected?

YES >> Perform diagnosis of applicable. Refer to DAS-128, "DTC Logic".

NO >> GO TO 2.

2.PERFORM DTC CONFIRMATION PROCEDURE

- 1. Start the engine.
- Turn the MAIN switch of ICC system ON.
- Perform "All DTC Reading" with CONSULT.
- 4. Check if the "C1A39" is detected as the current malfunction in self-diagnosis results of "LASER/RADAR".

Is "C1A39" detected as the current malfunction?

YES >> Refer to CCS-108, "Diagnosis Procedure".

NO-1 >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident".

NO-2 >> Confirmation after repair: INSPECTION END

Diagnosis Procedure

INFOID:0000000009644254

CHECK DTC PRIORITY

If DTC "C1A39" is displayed with DTC "U1000", first diagnose the DTC "U1000".

Is applicable DTC detected?

YES >> Perform diagnosis of applicable. Refer to DAS-128, "DTC Logic".

NO >> GO TO 2.

2.CHECK ADAS CONTROL UNIT SELF-DIAGNOSIS RESULTS

Check if any DTC is detected in "Self Diagnostic Result" of "ICC/ADAS".

Is any DTC detected?

YES >> Perform diagnosis on the detected DTC and repair or replace the malfunctioning parts. Refer to CCS-58, "DTC Index".

NO >> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation".

C1A50 ADAS CONTROL UNIT [ICC] < DTC/CIRCUIT DIAGNOSIS > C1A50 ADAS CONTROL UNIT Α DTC Logic INFOID:0000000009644255 DTC DETECTION LOGIC DTC DTC detecting condition Trouble diagnosis name ADAS MALFUNCTION C1A50 If ADAS control unit is malfunctioning (ADAS control unit malfunction) POSSIBLE CAUSE D ADAS control unit FAIL-SAFE Е The following systems are canceled. Vehicle-to-vehicle distance control mode Conventional (fixed speed) cruise control mode Distance Control Assist (DCA) Forward Emergency Braking (FEB) Predictive Forward Collision Warning (PFCW) DTC CONFIRMATION PROCEDURE 1. CHECK DTC PRIORITY If DTC "C1A50" is displayed with DTC "U1000", first diagnose the DTC "U1000". Н Is applicable DTC detected? YES >> Perform diagnosis of applicable. Refer to CCS-116, "DTC Logic". NO >> GO TO 2. 2.PERFORM DTC CONFIRMATION PROCEDURE Start the engine. Turn the MAIN switch of ICC system ON. 3. Perform "All DTC Reading" with CONSULT. Check if the "C1A50" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/ RADAR". Is "C1A50" detected as the current malfunction? >> Refer to CCS-109, "Diagnosis Procedure". >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident". NO-2 >> Confirmation after repair: INSPECTION END Diagnosis Procedure INFOID:0000000009644256 M 1. CHECK DTC PRIORITY If DTC "C1A50" is displayed with DTC "U1000", first diagnose the DTC "U1000". Ν Is applicable DTC detected?

YES >> Perform diagnosis of applicable. Refer to CCS-116, "DTC Logic".

NO >> GO TO 2.

2 .CHECK ADAS CONTROL UNIT SELF-DIAGNOSIS RESULTS

Check if any DTC is detected in "Self Diagnostic Result" of "ICC/ADAS".

Is any DTC detected?

YES >> Perform diagnosis on the detected DTC and repair or replace the malfunctioning parts. Refer to CCS-58. "DTC Index".

CCS-109

>> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation". NO

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2014 Q50

[ICC]

U0104 ADAS CAN 1

DTC Logic

DTC DETECTION LOGIC

DTC	Trouble diagnosis name	DTC detecting condition
U0104	ADAS CAN CIR 1 (ADAS control unit CAN circuit 1)	If ICC sensor detects an error signal that is received from ADAS control unit via ITS communication

POSSIBLE CAUSE

ADAS control unit

FAIL-SAFE

The following systems are canceled.

- Vehicle-to-vehicle distance control mode
- Conventional (fixed speed) cruise control mode
- Distance Control Assist (DCA)
- Forward Emergency Braking (FEB)
- Predictive Forward Collision Warning (PFCW)

DTC CONFIRMATION PROCEDURE

CHECK DTC PRIORITY

If DTC "U0104" is displayed with DTC "U1000", first diagnose the DTC "U1000".

Is applicable DTC detected?

YES >> Perform diagnosis of applicable. Refer to CCS-116, "DTC Logic".

NO >> GO TO 2.

2.PERFORM DTC CONFIRMATION PROCEDURE

- 1. Start the engine.
- Turn the MAIN switch of ICC system ON.
- Perform "All DTC Reading" with CONSULT.
- Check if the "U0104" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/ RADAR".

Is "U0104" detected as the current malfunction?

YES >> Refer to CCS-110, "Diagnosis Procedure".

NO-1 >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident".

NO-2 >> Confirmation after repair: INSPECTION END

Diagnosis Procedure

INFOID:0000000009644258

1. CHECK DTC PRIORITY

If DTC "U0104" is displayed with DTC "U1000", first diagnose the DTC "U1000".

Is applicable DTC detected?

YES >> Perform diagnosis of applicable. Refer to CCS-116, "DTC Logic".

NO >> GO TO 2.

2.CHECK ADAS CONTROL UNIT SELF-DIAGNOSIS RESULTS

Check if any DTC is detected in "Self Diagnostic Result" of "ICC/ADAS".

Is any DTC detected?

YES >> Perform diagnosis on the detected DTC and repair or replace the malfunctioning parts. Refer to CCS-58, "DTC Index".

NO >> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation".

< DTC/CIRC	UIT DIAGNOSIS >	[ICC]
U0121 VI	DC CAN 2	
DTC Logic		INFOID:000000000096442
DTC DETEC	CTION LOGIC	
DTC	Trouble diagnosis name	DTC detecting condition
U0121	VDC CAN CIR2 (VDC CAN circuit2)	If ICC sensor detects an error signal that is received from ABS actuator and electric unit (control unit) via ADAS control unit
OSSIBLE		
	r and electric unit (control unit)	
Vehicle-to-vConvention	y systems are canceled. Vehicle distance control mode val (fixed speed) cruise control control Assist (DCA)	mode
	nergency Braking (FEB)	
Predictive F	Forward Collision Warning (PF	CW)
_	RMATION PROCEDURE	
1.CHECK D	TC PRIORITY	
	• •	00", first diagnose the DTC "U1000".
• •	DTC detected?	D (1 000 110 IDTO 1 II
	Perform diagnosis of applicable GO TO 2.	. Refer to <u>CCS-116, "DTC Logic"</u> .
	M DTC CONFIRMATION PRO	CEDURE
1. Start the		
 Turn the Perform 	MAIN switch of ICC system Of "All DTC Reading" with CONSI	n. JLT.
I. Check if	the "U0121" is detected as	the current malfunction in "Self Diagnostic Result" of "LASEF
"RADAR S "U0121" de	etected as the current malfunct	on?
	Refer to <u>CCS-111, "Diagnosis P</u>	
NO-1 >> 7		before repair: Refer to GI-43, "Intermittent Incident".
Diagnosis	Procedure	INFOID:00000000096442
1. CHECK D	TC PRIORITY	
f DTC "U012	21" is displayed with DTC "U100	00", first diagnose the DTC "U1000".
	DTC detected?	-
YES >> F	Perform diagnosis of applicable	. Refer to CCS-116, "DTC Logic".

NO >> GO TO 2.

$2. \hbox{check adas control unit self-diagnosis results}$

Check if any DTC is detected in "Self Diagnostic Result" of "ICC/ADAS".

Is any DTC detected?

>> Perform diagnosis on the detected DTC and repair or replace the malfunctioning parts. Refer to YES CCS-58, "DTC Index"
>> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation".

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NO

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2014 Q50

[ICC]

U0126 STRG SEN CAN 1

DTC Logic

DTC DETECTION LOGIC

DTC	Trouble diagnosis name	DTC detecting condition
U0126	STRG SEN CAN CIR1 (Steering angle sensor CAN circuit1)	If ICC sensor detects an error signal that is received from steering angle sensor via ADAS control unit

POSSIBLE CAUSE

Steering angle sensor error

FAIL-SAFE

The following systems are canceled.

- Vehicle-to-vehicle distance control mode
- Conventional (fixed speed) cruise control mode
- Distance Control Assist (DCA)
- Forward Emergency Braking (FEB)
- Predictive Forward Collision Warning (PFCW)

DTC CONFIRMATION PROCEDURE

1. CHECK DTC PRIORITY

If DTC "U0126" is displayed with DTC "U1000", first diagnose the DTC "U1000".

Is applicable DTC detected?

YES >> Perform diagnosis of applicable. Refer to CCS-116, "DTC Logic".

NO >> GO TO 2.

2. PERFORM DTC CONFIRMATION PROCEDURE

- 1. Start the engine.
- Turn the MAIN switch of ICC system ON.
- 3. Perform "All DTC Reading" with CONSULT.
- Check if the "U0126" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/ RADAR".

Is "U0126" detected as the current malfunction?

YES >> Refer to CCS-112, "Diagnosis Procedure".

NO-1 >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident".

NO-2 >> Confirmation after repair: INSPECTION END

Diagnosis Procedure

INFOID:0000000009644262

1. CHECK DTC PRIORITY

If DTC "U0126" is displayed with DTC "U1000", first diagnose the DTC "U1000".

Is applicable DTC detected?

YES >> Perform diagnosis of applicable. Refer to CCS-116, "DTC Logic".

NO >> GO TO 2.

2.CHECK ADAS CONTROL UNIT SELF-DIAGNOSIS RESULTS

Check if any DTC is detected in "Self Diagnostic Result" of "ICC/ADAS".

Is any DTC detected?

YES >> Perform diagnosis on the detected DTC and repair or replace the malfunctioning parts. Refer to CCS-58, "DTC Index".

NO >> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation".

U0405 ADAS CAN 2 [ICC] < DTC/CIRCUIT DIAGNOSIS > U0405 ADAS CAN 2 Α DTC Logic INFOID:0000000009644263 DTC DETECTION LOGIC В DTC DTC detecting condition Trouble diagnosis name ADAS CAN CIR 2 If ICC sensor detects an error signal that is received from ADAS control unit U0405 (ADAS control unit CAN circuit 2) via ITS communication POSSIBLE CAUSE D ADAS control unit FAIL-SAFE The following systems are canceled. Е Vehicle-to-vehicle distance control mode Conventional (fixed speed) cruise control mode Distance Control Assist (DCA) Forward Emergency Braking (FEB) Predictive Forward Collision Warning (PFCW) DTC CONFIRMATION PROCEDURE 1. CHECK DTC PRIORITY If DTC "U0405" is displayed with DTC "U1000", first diagnose the DTC "U1000". Н Is applicable DTC detected? YES >> Perform diagnosis of applicable. Refer to CCS-116, "DTC Logic". NO >> GO TO 2. 2.PERFORM DTC CONFIRMATION PROCEDURE Start the engine. Turn the MAIN switch of ICC system ON. Perform "All DTC Reading" with CONSULT. Check if the "U0405" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/ RADAR". Is "U0405" detected as the current malfunction? >> Refer to CCS-113, "Diagnosis Procedure". >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident". NO-2 >> Confirmation after repair: INSPECTION END Diagnosis Procedure INFOID:0000000009644264 M 1. CHECK DTC PRIORITY If DTC "U0405" is displayed with DTC "U1000", first diagnose the DTC "U1000". Ν Is applicable DTC detected? YES >> Perform diagnosis of applicable. Refer to CCS-116, "DTC Logic".

NO >> GO TO 2.

2.CHECK ADAS CONTROL UNIT SELF-DIAGNOSIS RESULTS

Check if any DTC is detected in "Self Diagnostic Result" of "ICC/ADAS".

Is any DTC detected?

YES >> Perform diagnosis on the detected DTC and repair or replace the malfunctioning parts. Refer to CCS-58, "DTC Index".

>> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation". NO

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[ICC]

U0415 VDC CAN 1

DTC Logic

DTC DETECTION LOGIC

DTC	Trouble diagnosis name	DTC detecting condition
U0415	VDC CAN CIR1 (VDC CAN circuit1)	If ICC sensor detects an error signal that is received from ABS actuator and electric unit (control unit) via ADAS control unit

POSSIBLE CAUSE

ABS actuator and electric unit (control unit)

FAIL-SAFE

The following systems are canceled.

- Vehicle-to-vehicle distance control mode
- · Conventional (fixed speed) cruise control mode
- Distance Control Assist (DCA)
- Forward Emergency Braking (FEB)
- Predictive Forward Collision Warning (PFCW)

DTC CONFIRMATION PROCEDURE

1. CHECK DTC PRIORITY

If DTC "U0415" is displayed with DTC "U1000", first diagnose the DTC "U1000".

Is applicable DTC detected?

YES >> Perform diagnosis of applicable. Refer to CCS-116, "DTC Logic".

NO >> GO TO 2.

2.PERFORM DTC CONFIRMATION PROCEDURE

- 1. Start the engine.
- Turn the MAIN switch of ICC system ON.
- Perform "All DTC Reading" with CONSULT.
- Check if the "U0415" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/ RADAR".

Is "U0415" detected as the current malfunction?

YES >> Refer to CCS-114, "Diagnosis Procedure".

NO-1 >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident".

NO-2 >> Confirmation after repair: INSPECTION END

Diagnosis Procedure

INFOID:0000000009644266

1. CHECK DTC PRIORITY

If DTC "U0415" is displayed with DTC "U1000", first diagnose the DTC "U1000".

Is applicable DTC detected?

YES >> Perform diagnosis of applicable. Refer to CCS-116, "DTC Logic".

NO >> GO TO 2.

2.CHECK ADAS CONTROL UNIT SELF-DIAGNOSIS RESULTS

Check if any DTC is detected in "Self Diagnostic Result" of "ICC/ADAS".

Is any DTC detected?

YES >> Perform diagnosis on the detected DTC and repair or replace the malfunctioning parts. Refer to CCS-58, "DTC Index".

NO >> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation".

U0428 STRG SEN CAN 2

< DTC/CIRCUIT DIAGNOSIS > [ICC]

U0428 STRG SEN CAN 2

DTC Logic

DTC DETECTION LOGIC

DTC	Trouble diagnosis name	DTC detecting condition
U0428	STRG SEN CAN CIR2 (Steering angle sensor CAN circuit2)	If ICC sensor detects an error signal that is received from steering angle sensor via ADAS control unit

POSSIBLE CAUSE

Steering angle sensor

FAIL-SAFE

The following systems are canceled.

- Vehicle-to-vehicle distance control mode
- Conventional (fixed speed) cruise control mode
- Distance Control Assist (DCA)
- Forward Emergency Braking (FEB)
- Predictive Forward Collision Warning (PFCW)

DTC CONFIRMATION PROCEDURE

1. CHECK DTC PRIORITY

If DTC "U0428" is displayed with DTC "U1000", first diagnose the DTC "U1000".

Is applicable DTC detected?

YES >> Perform diagnosis of applicable. Refer to CCS-116, "DTC Logic".

NO >> GO TO 2.

2. PERFORM DTC CONFIRMATION PROCEDURE

- Start the engine.
- 2. Turn the MAIN switch of ICC system ON.
- Perform "All DTC Reading" with CONSULT.
- Check if the "U0428" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/ RADAR".

Is "U0428" detected as the current malfunction?

YES >> Refer to CCS-115, "Diagnosis Procedure".

NO-1 >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident".

NO-2 >> Confirmation after repair: INSPECTION END

Diagnosis Procedure

1. CHECK DTC PRIORITY

If DTC "U0428" is displayed with DTC "U1000", first diagnose the DTC "U1000".

Is applicable DTC detected?

YES >> Perform diagnosis of applicable. Refer to CCS-116, "DTC Logic".

NO >> GO TO 2.

2 .CHECK ADAS CONTROL UNIT SELF-DIAGNOSIS RESULTS

Check if any DTC is detected in "Self Diagnostic Result" of "ICC/ADAS".

Is any DTC detected?

NO >> Replace the ICC sensor. Refer to CCS-135, "Removal and Installation".

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INFOID:0000000009644268

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[ICC]

U1000 CAN COMM CIRCUIT

Description INFOID:0000000009644269

ITS COMMUNICATION

 ITS communication is a multiplex communication system. This enables the system to transmit and receive large quantities of data at high speed by connecting control units with 2 communication lines.

ITS communication lines adopt twisted-pair line style (two lines twisted) for noise immunity.

DTC Logic INFOID:0000000009644270

DTC DETECTION LOGIC

DTC	Trouble diagnosis name	DTC detecting condition
U1000	CAN COMM CIRCUIT (CAN communication circuit)	If ICC sensor is not transmitting or receiving ITS communication signal for 2 seconds or more

POSSIBLE CAUSE

ITS communication system

FAIL-SAFE

The following systems are canceled.

- Vehicle-to-vehicle distance control mode
- Conventional (fixed speed) cruise control mode
- Distance Control Assist (DCA)
- Forward Emergency Braking (FEB)
- Predictive Forward Collision Warning (PFCW)

DTC CONFIRMATION PROCEDURE

${f 1}$.PERFORM DTC CONFIRMATION PROCEDURE

- Start the engine.
- Turn the MAIN switch of ICC system ON.
- 3. Perform "All DTC Reading" with CONSULT.
- Check if the "U1000" is detected as the current malfunction in "Self Diagnostic Result" of "ICC/ADAS".

Is "U1000" detected as the current malfunction?

>> Refer to CCS-116, "Diagnosis Procedure". YES

NO-1 >> To check malfunction symptom before repair: Refer to GI-43, "Intermittent Incident".

NO-2 >> Confirmation after repair: INSPECTION END

Diagnosis Procedure

INFOID:00000000009644271

${f 1}$. PERFORM THE SELF-DIAGNOSIS

- Turn the ignition switch ON.
- Turn the MAIN switch of ICC system ON, and then wait for 2 seconds or more.
- Perform "All DTC Reading" with CONSULT.
- 4. Check if the "U1000" is detected as the current malfunction in "Self Diagnostic Result" of "LASER/ RADAR".

Is "U1000" detected as the current malfunction?

YES >> Refer to LAN-26, "Trouble Diagnosis Flow Chart".

	U101	0 CONTROL UNIT (CAN)	
< DTC/CIRC	UIT DIAGNOSIS >		[ICC]
U1010 C0	ONTROL UNIT (CA	N)	
Description	า	INFO	OID:00000000009644272
CAN controlle	er controls the communication	on of ITS communication signal and the error detection.	В
DTC Logic		_ INFC	OID:00000000009644273
DTC DETEC	CTION LOGIC		C
DTC	Trouble diagnosis name	DTC detecting condition	
U1010	CONTROL UNIT (CAN) [Control unit (CAN)]	If ICC sensor detects malfunction by CAN controller initial diagnosis	
POSSIBLE (CAUSE		Е
Vehicle-to-vConventionDistance CoForward Em	systems are canceled. The chicle distance control mode al (fixed speed) cruise control trol Assist (DCA) The control Assist (DCA) The control of the control	ol mode	F
DTC CONFI	RMATION PROCEDURE		F
1.PERFORM	I DTC CONFIRMATION PR	OCEDURE	
 Perform " Check if t 	MAIN switch of ICC system AII DTC Reading" with CON the "U1010" is detected as the "U1010" is detected	ISULT. he current malfunction in "Self Diagnostic Result" of "ICC/	/ADAS".
YES >> R NO-1 >> T	tected as the current malfur befer to CCS-116, "Diagnosis to check malfunction sympto confirmation after repair: INS	s <u>Procedure"</u> . m before repair: Refer to <u>GI-43, "Intermittent Incident"</u> .	K
Diagnosis	Procedure	INFO	OID:00000000009644274
	I DTC CONFIRMATION PR	OCEDURE	L
2. Perform "	MAIN switch of ICC system All DTC Reading" with CON the "U1010" is detected a		of "LASER/

RADAR".

Is "U1010" detected as the current malfunction?

>> Replace the ICC sensor. Refer to $\underline{\text{CCS-135}}$, "Removal and Installation". >> INSPECTION END YES

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POWER SUPPLY AND GROUND CIRCUIT

< DTC/CIRCUIT DIAGNOSIS >

[ICC]

POWER SUPPLY AND GROUND CIRCUIT

Diagnosis Procedure

INFOID:0000000009644275

1. CHECK FUSES

Check if any of the following fuses are blown:

Signal name	Fuse No.
Ignition power supply	54

Is the inspection result normal?

YES >> GO TO 2.

NO >> Replace the blown fuse after repairing the affected circuit if a fuse is blown.

2. CHECK ICC SENSOR POWER SUPPLY CIRCUIT

Check voltage between ICC sensor harness connector and ground.

Terminal			Condition	
(+)		(-)	Condition	Voltage (Approx.)
ICC sensor			Ignition	
Connector	Terminal		switch	
		Ground	OFF	0 V
E80	1		ON	Battery volt- age

Is the inspection result normal?

YES >> GO TO 3.

NO >> Repair the ICC sensor power supply circuit.

3.check icc sensor ground circuit

- 1. Turn the ignition switch OFF.
- 2. Disconnect the ICC sensor connector.
- 3. Check for continuity between ICC sensor harness connector and ground.

ICC s	sensor		Continuity	
Connector	Terminal	Ground	Continuity	
E80	8		Existed	

Is the inspection result normal?

YES >> INSPECTION END

NO >> Repair the ICC sensor ground circuit.

INTELLIGENT CRUISE CONTROL SYSTEM SYMPTOMS

< SYMPTOM DIAGNOSIS >

[ICC]

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SYMPTOM DIAGNOSIS

INTELLIGENT CRUISE CONTROL SYSTEM SYMPTOMS

Symptom Table

INFOID:00000000009644276

	Symptoms	Reference page	
	MAIN switch does not turn ON	Refer to CCS-120, "Description"	
	MAIN switch does not turn OFF		
	ICC system cannot be set (MAIN switch turns ON/OFF)	Refer to CCS-121, "Description"	
	CANCEL switch does not function		
Operation	Resume does not function		
	Set speed does not increase	Refer to CCS-123, "Description"	
	Set distance to a vehicle ahead cannot be changed		
	ICC is not canceled when the A/T selector lever is "N" position	Refer to CCS-124, "Description"	
Display/Chime	ICC system display not appear	Refer to MWI-62, "On Board Diagnosis Function"	
	Chime does not sound	Refer to CCS-125, "Description"	
Control	Driving force is hunting	Refer to CCS-127, "Description"	
	System frequently cannot detect a vehicle ahead	Refer to CCS-128. "Description"	
	Distance to detect a vehicle ahead is short		
Function to detect a vehicle ahead	System misidentifies a vehicle even though there is no vehicle ahead	Perform radar alignment: Refer to CCS-83, "TYPE 1 : Description"	
	System misidentifies a vehicle in the next lane	Perform ICC system action test. Refer to <u>CCS-95</u> , " <u>Description</u> "	
	System does not detect a vehicle at all	Refer to CCS-130, "Description"	

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MAIN SWITCH DOES NOT TURN ON, MAIN SWITCH DOES NOT TURN OFF

< SYMPTOM DIAGNOSIS >

[ICC]

MAIN SWITCH DOES NOT TURN ON, MAIN SWITCH DOES NOT TURN OFF

Description INFOID:000000009644277

MAIN switch does not turn ON

• ICC system display does not appear even when MAIN switch is pressed.

MAIN switch does not turn OFF

When ICC system display is ON, display does not turn OFF even if MAIN switch is pressed.

NOTE:

When ICC system warning illuminates, perform the self-diagnosis of ICC system, and then repair or replace the malfunctioning parts.

Diagnosis Procedure

INFOID:0000000009644278

1. MAIN SWITCH INSPECTION

- 1. Start the engine.
- Check that "MAIN SW" and "CRUISE LAMP" operate normally in "DATA MONITOR" of "ICC/ADAS" with CONSULT.

Is the inspection result normal?

YES >> GO TO 2.

NO >> GO TO 4.

2. CHECK COMBINATION METER

Check that "CRUISE IND" operates normally in "DATA MONITOR" of "METER/M&A".

Is the inspection result normal?

YES >> GO TO 3.

NO >> GO TO 4.

3.perform self-diagnosis of combination meter

- 1. Perform "Self Diagnostic Result" of "METER/M&A".
- 2. Check if DTC is detected. Refer to MWI-80, "DTC Index".

Is any DTC detected?

YES >> Repair or replace malfunctioning parts.

NO >> GO TO 4.

f 4.PERFORM SELF-DIAGNOSIS RESULTS OF ICC SYSTEM

- Perform "All DTC Reading".
- Check if the "U1000" is detected in self-diagnosis results of "ICC/ADAS".

Is "U1000" detected?

YES >> GO TO 5.

NO >> GO TO 6.

5. CAN COMMUNICATIONS INSPECTION

Check the CAN communication and repair or replace malfunctioning parts. Refer to CCS-116, "DTC Logic".

>> INSPECTION END

6. CHECK ICC STEERING SWITCH

Check the ICC steering switch. Refer to DAS-80, "Diagnosis Procedure".

ICC SYSTEM CANNOT BE SET (MAIN SWITCH TURNS ON/OFF)

[ICC] < SYMPTOM DIAGNOSIS >

ICC SYSTEM CANNOT BE SET (MAIN SWITCH TURNS ON/OFF)

Description INFOID:0000000009644279

The MAIN switch can be turned ON/OFF, but the ICC system cannot be set even if the SET/COAST switch is pressed.

NOTE:

The system cannot be set in the following case.

- When the vehicle ahead is not detected below the speed of 32 km/h (20 MPH).
- When the selector lever is not in the "D" position or manual mode.
- When the brake pedal is depressed.
- When the VDC is turned OFF.
- When ABS or VDC (including the TCS) operates.
- When a wheel slips.
- When ABS warning lamp is ON.
- When drive mode select switch is in SNOW position.
- When the radar is temporarily interrupted.

Diagnosis Procedure

1. CHECK CAUSE OF AUTOMATIC CANCELLATION

Check if there is the cancellation cause in the "CAUSE OF AUTO-CANCEL" on "WORK SUPPORT" of "ICC/ ADAS" with CONSULT.

Is it displayed?

Not displayed>>GO TO 2.

"OPE SW VOLT CIRC">>Refer to DAS-80, "DTC Logic".

"VHCL SPD UNMATCH">>Refer to DAS-72, "DTC Logic".

"IGN LOW VOLT">>Refer to CCS-102, "DTC Logic".

"ECM CIRCUIT">>Refer to DAS-89, "DTC Logic".

"CAN COMM ERROR">>Refer to DAS-122, "DTC Logic".

"ICC SENSOR CAN COMM ERR">>Refer to DAS-122, "DTC Logic".

"ABS/TCS/VDC CIRC">>Refer to DAS-74, "DTC Logic".

"ECD CIRCUIT">>Refer to DAS-95, "DTC Logic".

2.perform the self-diagnosis

1. Perform "All DTC Reading".

Check if any DTC is detected in "Self Diagnostic Result" of "ICC/ADAS" or "LASER/RADAR". Refer to CCS-58, "DTC Index" (ICC/ADAS) or CCS-63, "DTC Index" (LASER/RADAR).

Is any DTC detected?

YES >> GO TO 3.

NO >> GO TO 4.

3.REPAIR OR REPLACE MALFUNCTIONING PARTS

Repair or replace malfunctioning parts identified by the self-diagnosis result.

>> GO TO 6.

4.CHECK EACH SWITCH AND VEHICLE SPEED SIGNAL

- Start the engine.
- 2. Check that the following items operate normally in "DATA MONITOR" of "ICC/ADAS".
- "VHCL SPEED SE"
- "D RANGE SW"
- "SET/COAST SW"
- "BRAKE SW"
- "PKB SW"

Is there a malfunctioning item?

All items are normal>>GO TO 5.

"VHCL SPEED SE">>Refer to DAS-72, "DTC Logic".

"D RANGE SW">>Refer to CCS-124, "Diagnosis Procedure".

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ICC SYSTEM CANNOT BE SET (MAIN SWITCH TURNS ON/OFF)

< SYMPTOM DIAGNOSIS >

[ICC]

"SET/COAST SW">>Refer to DAS-80, "DTC Logic".

"BRAKE SW">>Refer to DAS-75, "DTC Logic".

"PKB SW">>Refer to WCS-56, "Diagnosis Procedure".

5. REPLACE ADAS CONTROL UNIT

Replace the ADAS control unit. Refer to <u>DAS-161</u>, "Removal and Installation".

>> GO TO 6.

6. CHECK ICC SYSTEM

- 1. Erase the self-diagnosis results, and then perform "All DTC Reading" again after performing the action test. (Refer to CCS-95, "Description" for action test.)
- 2. Check that the ICC system is normal.

< SYMPTOM DIAGNOSIS > ICC STEERING SWITCH (OTHER THAN MAIN SWITCH) DOES NOT **FUNCTION** Description INFOID:0000000009644281 В ICC MAIN switch can be turned ON/OFF, but the operation of RESUME/ACCELERATE switch, CANCEL switch, and DISTANCE switch cannot be performed during ICC system operation. NOTE: Resume is not accepted when the following condition is met. When the MAIN switch is turned OFF once. The set distance change is not accepted when any of the following condition is met. D When the DCA system is turned ON. Diagnosis Procedure INFOID:0000000009644282 Е 1. CHECK EACH SWITCH Start the engine. Check that each switch operates normally on "DATA MONITOR" of "ICC/ADAS" with CONSULT. F "RESUME/ACC SW" "CANCEL SW" "DISTANCE SW" Is the inspection result normal? YES >> GO TO 5. NO >> GO TO 2. Н 2.perform all of the self-diagnosis items Perform "All DTC Reading". Check if the "U1000" is detected in "Self Diagnostic Result" of "ICC/ADAS". Is "U1000" detected? YES >> GO TO 3. NO >> GO TO 4. 3 .CAN COMMUNICATIONS INSPECTION Check the CAN communication and repair or replace malfunctioning parts. Refer to CCS-116, "DTC Logic". >> INSPECTION END CHECK ICC STEERING SWITCH Check the ICC steering switch. Refer to DAS-81, "Component Inspection". >> GO TO 6. REPLACE ADAS CONTROL UNIT Replace the ADAS control unit. Refer to DAS-161, "Removal and Installation". >> GO TO 6. CCS 6. CHECK ICC SYSTEM Erase the self-diagnosis results, and then perform "All DTC Reading" again after performing the action test. (Refer to <u>CCS-95</u>, "<u>Description</u>" for action test.) Р Check that the ICC system is normal.

ICC STEERING SWITCH (OTHER THAN MAIN SWITCH) DOES NOT FUNCTION

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ICC SYSTEM DOES NOT CANCEL WHEN A/T SELECTOR LEVER SETS ON "N"

< SYMPTOM DIAGNOSIS >

[ICC]

ICC SYSTEM DOES NOT CANCEL WHEN A/T SELECTOR LEVER SETS ON "N"

Description INFOID:000000009644283

The ICC system is not canceled even when the A/T selector lever is shifted to the N position while the ICC system is active.

Diagnosis Procedure

INFOID:0000000009644284

1. CHECK D RANGE SWITCH

Check if "D RANGE SW" operates normally in "DATA MONITOR" of "ICC/ADAS" with CONSULT.

Is the inspection result normal?

YES >> GO TO 6. NO >> GO TO 2.

2. PERFORM ALL SELF-DIAGNOSIS ITEMS

- 1. Perform "All DTC Reading".
- 2. Check if the "U1000" is detected in "self-diagnosis results" of "ICC/ADAS".

Is "U1000" detected?

YES >> GO TO 3.

NO >> GO TO 4.

3. CAN COMMUNICATIONS INSPECTION

Check the CAN communication and repair or replace malfunctioning parts. Refer to CCS-116, "DTC Logic".

>> INSPECTION END

4. CHECK POSITION SWITCH

Check if "SLCT LVR POSI" operates normally in "DATA MONITOR" of "TRANSMISSION".

Is the inspection result normal?

YES >> GO TO 6. NO >> GO TO 5.

5. PERFORM TCM SELF-DIAGNOSIS

- 1. Perform the "Self Diagnostic Result" of "TRANSMISSION".
- Repair or replace malfunctioning parts. Refer to TM-85, "DTC Index".

>> GO TO 7.

6. REPLACE ADAS CONTROL UNIT

Replace the ADAS control unit. Refer to DAS-161, "Removal and Installation".

>> GO TO 7.

7. CHECK ICC SYSTEM

- 1. Erase the self-diagnosis results, and then perform "All DTC Reading" again after performing the action test. (Refer to CCS-95, "Description" for action test.)
- 2. Check that the ICC system is normal.

CHIME DOES NOT SOUND

[ICC] < SYMPTOM DIAGNOSIS >

CHIME DOES NOT SOUND

Description INFOID:0000000009644285

Symptom check: In the following conditions, the warning chime may not sound even if the vehicle distance is

- When the vehicles are traveling at the same speed and the distance between vehicles is not changing.
- When the vehicle ahead is traveling faster and the distance between vehicles is increasing.
- The warning chime will not sound when the accelerator pedal is depressed, overriding the system.
- The warning chime will not sound when own vehicle approaches vehicles that are parked or moving slowly.
- The warning chime does not sound when the system does not detect any vehicle ahead. (Diagnose the conditions under which the system is detecting the vehicle ahead and when the system is malfunctioning. If there is any malfunction in detecting the vehicle ahead, check the system following the CCS-128, "Description".)

Diagnosis Procedure

1. PERFORM ACTIVE TEST

Check if the warning chime sounds on the active test item "ICC BUZZER" of "ICC/ADAS" with CONSULT.

Does the warning chime sound?

YES >> GO TO 2. NO >> GO TO 3.

2.CHECK THE MALFUNCTION SYMPTOM DURING WARNING CHIME OPERATION

Understand the vehicle ahead detecting condition when the malfunction occurred. If the warning chime should have sounded, replace the ADAS control unit. Refer to DAS-161, "Removal and Installation".

>> GO TO 8.

3.CHECK DRIVER ASSISTANCE BUZZER

Check if the warning chime sounds on the active test item BUZZER 2 (ADAS) of "BSW/BUZZER" with CON-SULT.

Is the inspection result normal?

YES >> GO TO 4. NO >> GO TO 5.

f 4.PERFORM THE SELF-DIAGNOSIS OF ADAS CONTROL UNIT

- 1. Perform "All DTC Reading" with CONSULT.
- Check if the any DTC is detected in self-diagnosis results of "ICC/ADAS".

Is any DTC detected?

YES >> GO TO 6.

NO >> GO TO 5.

5.PERFORM THE SELF-DIAGNOSIS OF DRIVER ASSISTANCE BUZZER CONTROL MODULE

CCS-125

- Perform "All DTC Reading" with CONSULT.
- Check if the "any DTC" is detected in self-diagnosis results of "BSW/BUZZER".

Is "any DTC" detected?

YES >> GO TO 6. NO >> GO TO 7.

O. REPAIR OR REPLACE MALFUNCTIONING PARTS

Repair or replace malfunctioning parts.

>> GO TO 8.

7.REPLACE ADAS CONTROL UNIT

Replace the ADAS control unit. Refer to DAS-161, "Removal and Installation".

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INFOID:0000000009644286

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CHIME DOES NOT SOUND

< SYMPTOM DIAGNOSIS > [ICC]

>> GO TO 8.

8. CHECK ICC SYSTEM

- 1. Erase the self-diagnosis results, and then perform "All DTC Reading" again after performing the action test. (Refer to CCS-95, "Description" for action test.)
- 2. Check that the ICC system is normal.

DRIVING FORCE IS HUNTING

[ICC] < SYMPTOM DIAGNOSIS > DRIVING FORCE IS HUNTING Α Description INFOID:0000000009644287 The vehicle causes hunting when the ICC system is active. В Diagnosis Procedure INFOID:0000000009644288 1. PERFORM SELF-DIAGNOSIS OF ECM Perform "All DTC Reading" with CONSULT. Check if the DTC is detected in self-diagnosis results of "ENGINE". Refer to EC-106, "DTC Index". D Is any DTC detected? YES >> GO TO 3. NO >> GO TO 2. Е 2. CHECK ICC SENSOR Check the vehicle driving conditions. Refer to CCS-128, "Description". 2. Check the ICC sensor for contamination, foreign materials, or cracks. Refer to CCS-128, "Diagnosis Procedure". >> INSPECTION END 3.REPAIR OR REPLACE MALFUNCTIONING PARTS Repair or replace malfunctioning parts identified by the self-diagnosis result. Н >> GO TO 4. 4. CHECK ICC SYSTEM Erase the self-diagnosis results, and then perform "All DTC Reading" again after performing the action test. (Refer to CCS-95, "Description" for action test.) Check that the ICC system is normal. >> INSPECTION END Ν

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FREQUENTLY CANNOT DETECT THE VEHICLE AHEAD / DETECTION ZONE IS SHORT

< SYMPTOM DIAGNOSIS >

FREQUENTLY CANNOT DETECT THE VEHICLE AHEAD / DETECTION ZONE IS SHORT

Description INFOID:0000000009644289

The detection function may become unstable in the following cases.

- When radar reflections from the vehicle ahead is interrupted.
- When driving a road with extremely sharp corners.
- When the sensor cannot detect a vehicle ahead while the vehicle ahead passes a hill or valley.

Diagnosis Procedure

INFOID:0000000009644290

1. VISUAL CHECK (1)

Check the contamination and foreign matter on the ICC sensor area of the front bumper.

Do foreign matter adhere?

YES >> GO TO 3.

NO >> GO TO 2.

2.VISUAL CHECK (2)

- Remove the front bumper. Refer to EXT-14, "Removal and Installation".
- Check ICC sensor for contamination and foreign matter.

Do foreign matter adhere?

>> GO TO 3. YES

>> GO TO 4. NO

3.WIPE OUT DIRT AND FOREIGN MATERIALS

Wipe out the contamination and foreign matter in the area around the ICC sensor.

>> GO TO 8.

4. VISUAL CHECK (3)

Check ICC sensor for cracks and scratches.

Are there any cracks or scratches?

YES >> GO TO 6.

NO >> GO TO 5.

PERFORM RADAR ALIGNMENT

- Install the front bumper. Refer to EXT-14, "Removal and Installation".
- Perform the radar alignment. Refer to CCS-83, "TYPE 1: Description".
- Perform ICC system action test. Refer to CCS-95, "Description".
- Check that the vehicle ahead detection performance improves.

Does it improve?

YES >> INSPECTION END

>> GO TO 6. NO

6. REPLACE ICC SENSOR

- Replace the ICC sensor. Refer to CCS-135, "Exploded View".
- Install the front bumper. Refer to EXT-14, "Removal and Installation". Perform the radar alignment. Refer to CCS-83, "TYPE 1: Description".
- Perform ICC system action test. Refer to CCS-95, "Description".
- Check that the vehicle ahead detection performance improves.

Does it improve?

>> INSPECTION END YES

NO >> GO TO 7.

.REPLACE ADAS CONTROL UNIT

Replace ADAS control unit. Refer to DAS-161, "Removal and Installation".

FREQUENTLY CANNOT DETECT THE VEHICLE AHEAD / DETECTION ZONE IS SHORT

< SYMPTOM DIAGNOSIS > [ICC]

>> GO TO 8. 8.CHECK ICC SYSTEM

1. Erase the self-diagnosis results, and then perform "All DTC Reading" again after performing the action-test. (Refer to CCS-95, "Description" for action test).

2. Check that the ICC system is normal.

>> INSPECTION END

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THE SYSTEM DOES NOT DETECT THE VEHICLE AHEAD AT ALL

< SYMPTOM DIAGNOSIS >

[ICC]

THE SYSTEM DOES NOT DETECT THE VEHICLE AHEAD AT ALL

Description INFOID:000000009644291

When ICC system is active, the ICC system does not perform any control even through there is a vehicle ahead.

Diagnosis Procedure

INFOID:0000000009644292

1. CHECK ICC SYSTEM DISPLAY ON MULTI INFORMATION DISPLAY

- 1. Start the self-diagnosis mode of combination meter. Refer to MWI-62, "On Board Diagnosis Function".
- 2. Check that the multi information display turns on normally.

Is the inspection result normal?

YES >> GO TO 2.

NO >> Replace the combination meter.

2.VISUAL CHECK (1)

Check the contamination and foreign matter on the ICC sensor area of the front bumper.

Do foreign materials adhere?

YES >> GO TO 4.

NO >> GO TO 3.

3.VISUAL CHECK (2)

- 1. Remove the front bumper. Refer to EXT-14, "Removal and Installation".
- 2. Check ICC sensor for contamination and foreign matter.

Do foreign matter adhere?

YES >> GO TO 4.

NO >> GO TO 5.

4. WIPE OUT DIRT AND FOREIGN MATERIALS

Wipe out the contamination and foreign matter in the area around the ICC sensor.

>> GO TO 9.

5. VISUAL CHECK (3)

Check ICC sensor for cracks and/or scratches.

Are there cracks?

YES >> GO TO 7.

NO >> GO TO 6.

6. PERFORM RADAR ALIGNMENT

- 1. Install the front bumper. Refer to EXT-14, "Removal and Installation".
- Perform the radar alignment. Refer to <u>CCS-83, "TYPE 1 : Description"</u>.
- 3. Perform ICC system action test. Refer to CCS-95, "Description".
- 4. Check that the vehicle ahead detection performance improves.

Does it improve?

YES >> INSPECTION END

NO >> GO TO 8.

7. REPLACE ICC SENSOR

- 1. Replace the ICC sensor. Refer to CCS-135, "Exploded View".
- 2. Install the front bumper. Refer to EXT-14, "Removal and Installation".
- 3. Perform the radar alignment. Refer to CCS-83, "TYPE 1: Description".
- 4. Perform ICC system action test. Refer to CCS-95, "Description"
- 5. Check that the vehicle ahead detection performance improves.

Does it improve?

YES >> INSPECTION END

THE SYSTEM DOES NOT DETECT THE VEHICLE AHEAD AT ALL < SYMPTOM DIAGNOSIS > [ICC]	
NO >> GO TO 8.	
8. REPLACE ADAS CONTROL UNIT	Α
Replace ADAS control unit. Refer to <u>DAS-161</u> , "Removal and Installation".	
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>> GO TO 9.	
9. CHECK ICC SYSTEM	С
 Erase the self-diagnosis results, and then perform "All DTC Reading" again after performing the action test. (Refer to <u>CCS-95</u>, "<u>Description</u>" for action test.) Check that the ICC system is normal. 	
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NORMAL OPERATING CONDITION

< SYMPTOM DIAGNOSIS > [ICC]

NORMAL OPERATING CONDITION

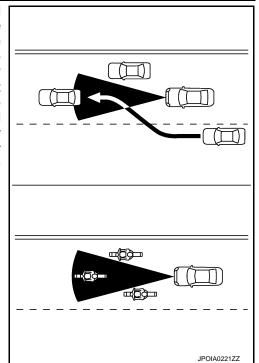
Description INFOID:000000009644293

PRECAUTIONS FOR VEHICLE-TO-VEHICLE DISTANCE CONTROL MODE

- ICC system is only an aid to assist the driver and is not a collision warning or avoidance device. It is the
 driver's responsibility to stay alert, drive safely and be in control of the vehicle at all times.
- The system is primarily intended for use on straight, dry, open roads with light traffic. It is not advisable to use the system in city traffic or congested areas.
- This system will not adapt automatically to road conditions. This system should be used in evenly flowing traffic. Do not use the system on roads with sharp curves, or on icy roads, in heavy rain or in fog.
- The ICC sensor will not detect under most conditions.
- Stationary and slow moving vehicles.
- Pedestrians or objects in the roadway.
- Oncoming vehicles in the some lane.
- Motorcycles traveling offset in the travel lane.
- As there is a performance limit to the distance control function, never rely solely on the ICC system. This
 system does not correct careless, inattentive or absent-minded driving, or overcome poor visibility in rain,
 fog, or other bad weather. Decelerate the vehicle speed by depressing the brake pedal, depending on the
 distance to the vehicle ahead and the surrounding circumstances in order to maintain a safe distance
 between vehicles.
- If the vehicle ahead comes to a stop, the vehicle decelerates to a standstill within the limitations of the system. The system will cancel once it judges that the vehicle has come to a standstill and sound a warning chime. To prevent the vehicle from moving, the driver must depress the brake pedal.
- The system may not detect the vehicle in front of the driver in certain road or weather conditions. To avoid accidents, never use the ICC system under the following conditions:
- On roads where the traffic is heavy or there are sharp curves.
- On slippery road surfaces such as on ice or snow, etc.
- During bad weather (rain, fog, snow, etc.)
- When rain, snow or dirt adhere to the system sensor.
- On steep downhill roads (the vehicle may go beyond the set vehicle speed and frequent braking may result in overheating the brakes).
- On repeated uphill and downhill roads.
- When traffic conditions make it difficult to keep a proper distance between vehicles because of frequent acceleration or deceleration.
- In some road or traffic conditions, a vehicle or object can unexpectedly come into the sensor detection zone
 and cause automatic braking. The driver may need to control the distance from other vehicles using the
 accelerator pedal. Always stay alert and avoid using the ICC system when it is not recommended in this section.
- The vehicle-to-vehicle distance control mode uses a sensor located behind the lower grille of the front bumper to detect vehicles traveling ahead. The sensor generally detects the signals returned from the vehicle ahead. Therefore, if the sensor cannot detect the reflection from the vehicle ahead, the ICC system may not maintain the selected distance.
- The following are some conditions in which the sensor cannot detect the signals:
- When the snow or road spray from traveling vehicles reduces the sensor's visibility.
- When excessively heavy baggage is loaded in the rear seat or the trunk room of own vehicle.
- The ICC system is designed to automatically check the sensor's operation within the limitation of the system. When the sensor area of the front bumper is covered with dirt or is obstructed, the system will automatically be canceled. If the sensor is covered with ice, a transparent or translucent vinyl bag, etc., the ICC system may not detect them. In these instances, the vehicle-to-vehicle distance control mode may not cancel and may not be able to maintain the selected following distance from the vehicle ahead. Be sure to check and clean the sensor regularly.
- The ICC system does not control vehicle speed or warn the driver when own vehicle approaches stationary and slow moving vehicles. The driver must pay attention to vehicle operation to maintain proper distance from vehicles ahead when approaching toll gates or traffic congestion.

• The detection zone of the ICC sensor is limited. A vehicle ahead must be in the detection zone for the vehicle-to-vehicle distance detection mode to maintain the selected distance from the vehicle ahead. A vehicle ahead may move outside of the detection zone due to its position within the same lane of travel. Motorcycles may not be detected in the same lane ahead if they are traveling offset from the center line of the lane. A vehicle that is entering the lane ahead may not be detected until the vehicle has completely moved into the lane. If this occurs, the ICC system may warn the driver by blinking the system indicator and sounding the chime. The driver may have to manually control the proper distance away from vehi-

cle traveling ahead.

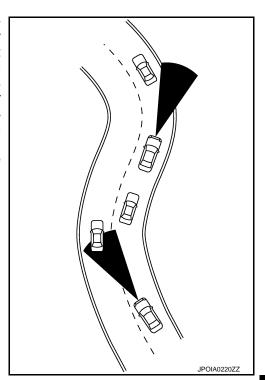


[ICC]

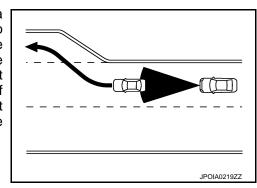
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• When driving on some roads, such as winding, hilly, curved, narrow roads, or roads which are under construction, the ICC sensor may detect vehicles in a different lane, or may temporarily not detect a vehicle traveling ahead. This may cause the ICC system to decelerate or accelerate the vehicle. The detection of vehicles may also be affected by vehicle operation (steering maneuver or traveling position in the lane, etc.) or vehicle condition. If this occurs, the ICC system may warn the driver by blinking the system indicator and sounding the chime unexpectedly. The driver will have to manually control the proper distance away from the vehicle traveling ahead.



• When driving on the freeway at a set speed and approaching a slower traveling vehicle ahead, the ICC will adjust the speed to maintain the distance, selected by the driver, from the vehicle ahead. If the vehicle ahead changes lanes or exits the freeway, the ICC system will accelerate and maintain the speed up to the set speed. Pay attention to the driving operation to maintain control of the vehicle as it accelerates to the set speed. The vehicle may not maintain the set speed on winding or hilly roads. If this occurs, the driver will have to manually control the vehicle speed.



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NORMAL OPERATING CONDITION

< SYMPTOM DIAGNOSIS >

Normally when controlling the distance to a vehicle ahead, this system automatically accelerates or decelerates own vehicle according to the speed of the vehicle ahead. Depress the accelerator to properly accelerate own vehicle when acceleration is required for a lane change. Depress the brake pedal when deceleration is required to maintain a safe distance to the vehicle ahead due to its sudden braking or if a vehicle cuts in. Always stay alert when using the ICC system.

PRECAUTIONS FOR CONVENTIONAL (FIXED SPEED) CRUISE CONTROL MODE

- In the conventional (fixed speed) cruise control mode, a warning chime does not sound to warn the driver if own vehicle is too close to the vehicle ahead, as neither the presence of the vehicle ahead nor the vehicleto-vehicle distance is detected.
- Pay special attention to the distance between own vehicle and the vehicle ahead or a collision could occur.
- Always confirm the setting in the ICC system display.
- Do not use the conventional (fixed speed) cruise control mode when driving under the following conditions:
- When it is not possible to keep the vehicle at a set speed.
- In heavy traffic or in traffic that varies in speed.
- On winding or hilly roads.
- On slippery roads (rain, snow, ice, etc.).
- In very windy areas.
- Doing so could cause a loss of vehicle control and result in an accident.
- To avoid accidentally engaging cruise control, make sure to turn the MAIN switch off when not using the ICC system.

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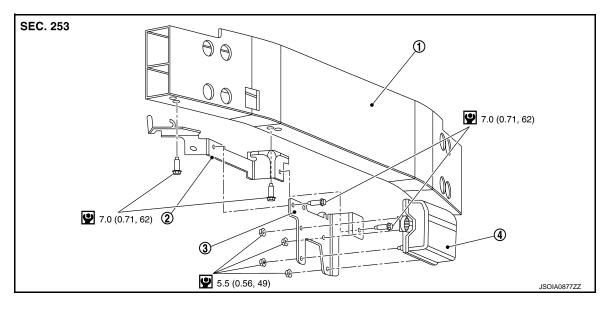
REMOVAL AND INSTALLATION

ICC SENSOR

Exploded View

CAUTION:

Always perform the laser beam aiming adjustment and check the operation after the replacement, removal and installation of ICC sensor.



- Front bumper reinforcement
- Ø bracket A

(3) bracket B

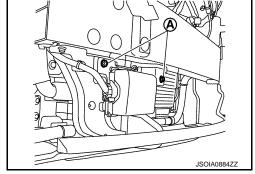
- (4) ICC sensor
- : N·m (kg-m, in-lb)

Removal and Installation

INFOID:0000000009644295

REMOVAL

- 1. Remove front bumper fascia. Refer to EXT-14, "Removal and Installation".
- 2. Disconnect ICC sensor connector.
- Remove mounting bolts (A) of bracket A to remove ICC sensor with bracket A.



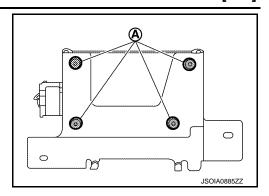
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4. Remove mounting nuts (A) of ICC sensor.



- 5. Remove ICC sensor.
- 6. Remove mounting bolts of bracket B to remove bracket B from front bumper reinforcement.

INSTALLATION

Install in the reverse order of removal.

CAUTION:

Always perform the radar alignment and check the operation after the replacement, removal, and installation of ICC sensor. Refer to CCS-82, "Description".

ICC STEERING SWITCH [ICC] < REMOVAL AND INSTALLATION > **ICC STEERING SWITCH** Α **Exploded View** INFOID:0000000009644296 ICC steering switch is integrated in the steering switch. В Refer to ST-86, "Removal and Installation". NOTE: Always remove ICC steering switch together with steering wheel. C D Е F G Н

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Revision: 2013 October CCS-137 2014 Q50

AUTOMATIC SPEED CONTROL DEVICE (ASCD)

< SYSTEM DESCRIPTION >

[ASCD]

SYSTEM DESCRIPTION

AUTOMATIC SPEED CONTROL DEVICE (ASCD)

Information INFOID:0000000009240444

Automatic Speed Control Device (ASCD) system is controlled by ECM.

Regarding the information for ASCD system, refer to EC-48, "AUTOMATIC SPEED CONTROL DEVICE (ASCD): System Description".